

**Computability in Europe 2023**  
**Special session on Proof Theory**

$\partial$  is for Dialectica

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# Gödel's Dialectica Transformation

- ▶ Gödel Dialectica transformation [1958] : a translation from intuitionistic arithmetic to a finite type extension of primitive recursive arithmetic.

$$A \rightsquigarrow \exists u : \mathbb{W}(A), \forall x : \mathbb{C}(A), A^D[u, x]$$

- ▶ De Paiva [1991]: the linearized Dialectica translation operates on Linear Logic (types) and  $\lambda$ -calculus (terms).
- ▶ Pedrot [2014] A *computational* Dialectica translation preserving  $\beta$ -equivalence, via the introduction of an "abstract multiset constructor" on types on the target.

# Gödel's Dialectica

1.  $(F \wedge G)' = (\exists yv) (zw) [A (y, z, x) \wedge B (v, w, u)].$
2.  $(F \vee G)' = (\exists yvt) (zw) [t=0 \wedge A (y, z, x) \cdot \vee \cdot t=1 \wedge B (v, w, u)].$
3.  $[(s) F]' = (\exists Y) (sz) A (Y (s), z, x).$
4.  $[(\exists s) F]' = (\exists sy) (z) A (y, z, x).$
5.  $(F \supset G)' = (\exists VZ) (yw) [A (y, Z (yw), x) \supset B (V (y), w, u)].$
6.  $(\neg F)' = (\exists \bar{Z}) (y) \neg A (y, \bar{Z} (y), x).$



Kurt Gödel (1958). Über eine bisher noch nicht benützte Erweiterung des finiten Standpunktes. *Dialectica*.

# Gödel's Dialectica

- ▶ Validates semi-classical axioms:
  - ▶ Markov's principle :  $\neg\neg\exists xA \rightarrow \exists xA$  when  $A$  is decidable.
  - ▶ Independent of premises :  $(A \rightarrow \exists xB) \rightarrow (\exists x.(A \rightarrow B))$
- ▶ Numerous applications :
  - ▶ Soundness results
  - ▶ Proof mining

A further distinguishing feature of the D-interpretation is its nice behavior with respect to modus ponens. In contrast to cut-elimination, which entails a global (and computationally infeasible) transformation of proofs, the D-interpretation extracts constructive information through a purely local procedure: when proofs of  $\varphi$  and  $\varphi \rightarrow \psi$  are combined to yield a proof of  $\psi$ , witnessing terms for the antecedents of this last inference are combined to yield a witnessing term for the conclusion. As a result of this modularity, the interpretation of a theorem can be readily obtained from the interpretations of the lemmata used in its proof.



Jeremy Avigad and Solomon Feferman (1999). Gödel's functional ("Dialectica") interpretation

# A peek into Dialectica interpretation of functions

$$(A \rightarrow B)_D = \exists f g \forall x y (A_D(x, gxy) \rightarrow B_D(fx, y))$$

**Usual explanation** : least unconstructive prenexation.

- ▶ Start from  $\exists x, \forall u, A_D[x, u] \rightarrow \exists y, \forall v, B_D[y, v]$ .
- ▶ Obvious prenexation :  $\forall x (\forall u, A_D[x, u] \rightarrow \exists y, \forall v, B_D[y, v])$
- ▶ Weak form of IP :  $\forall x \exists y (\forall u, A_D[x, u] \rightarrow \forall v, B_D[y, v])$
- ▶ Prenexation :  $\forall x \exists y, \forall v, \exists u (A_D[x, u] \rightarrow B_D[y, v])$ .
- ▶ Markov :  $\forall x, \exists y, \forall v, \exists u (A_D[x, u] \rightarrow B_D[y, v])$
- ▶ Axiom of choice :  $\exists f, \exists g, \forall u, \forall v, (A_D(u, guv) \rightarrow B_D[fu, v])$ .

**Dynamic behaviour** : agrees to a chain rule.

Mathematical meaning : it's some kind of approximation.



Ulrich Kohlenbach, *Applied Proof Theory: Proof Interpretations and their Use in Mathematics*, 2008

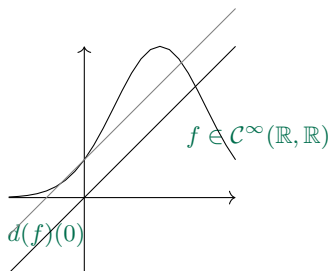
# Outline of the talk

- The Historical Dialectica
- Differentiation and Differentiable Programming.
- Factorizing Dialectica through differential linear logic.
- Dialectica acting on  $\lambda$ -terms.
- Applications and related work.

# Differentiable Programming

# Differentiation

- **Differentiation** is finding the best linear approximation to a function at a point.



$$\text{Chain Rule : } D_0(f \circ g) = D_{g(0)}f \circ D_0g$$

- **Differentiation** is a mathematical operation which needs to be fitted to logical and computer science use.
  - **Algorithmic Differentiation** : differentiating sequences of many-valued functions efficiently.
  - **Differential Linear Logic** : Differentiating proofs and  $\lambda$ -terms.



## Dialectica verifies the chain rule

Composing the Dialectica interpretation of arrows:

$$(A \Rightarrow B)_D[\phi_1; \psi_1, u_1; v_1] := A_D(u_1, \psi_1 u_1 v_1) \Rightarrow B_D(\phi_1 u_1, v_1)$$

$$(B \Rightarrow C)_D[\phi_2; \psi_2, u_2; v_2] := B_D(u_2, \psi_2 u_2 v_2) \Rightarrow C_D(\phi_2 u_2, v_2)$$

$$(A \Rightarrow C)_D[\phi_3; \psi_3, u_3; v_3] := A_D(u_3, \psi_3 u_3 v_3) \Rightarrow C_D(\phi_3 u_3, v_3)$$

The Dialectica interpretation amounts to the following equations:

$$u_3 = u_1$$

$$\psi_3, u_3, v_3 = \psi_1, u_1, v_1$$

$$v_3 = v_2$$

$$\phi_2 u_2 = \phi_1, u_1$$

$$u_2 = \phi_1 u_1$$

$$v_1 = \psi_2(u_2, v_2)$$

which can be simplified to:

$$\phi_3(u_3) = \phi_2(\phi_1(u_3)) \text{ composition of functions}$$

$$\psi_3(u_3, v_3) = \psi_1(u_3, \psi_2(\phi_1 u_3, v_3)) \text{ composition of their differentials}$$

*Thanks to T. Powell for noticing typos here.*

*But verifying the chain rule does not make you differentiation!*

- ▶ More **modern** presentations of Dialectica.
- ▶ More **Computer Science Friendly** presentations of Differentiation.
- ▶ **Linearity** must enter the game.

# Curry-Howard for semantics

<b>Programs</b>	<b>Logic</b>	<b>Semantics</b>
<code>fun (x:A)-&gt; (t:B)</code>	Proof of $A \vdash B$	$f : A \rightarrow B.$
Types	Formulas	Objects
Execution	Cut-elimination	Equality
<b>Dialectica</b>		
Differential $\lambda$ -calculus	Differential Linear Logic	Differential Categories

*Dialectica is Backward Differentiation in Logic*

## And now for something completely different : Automatic Differentiation

How does one compute the differentiation of an algebraic expression, computed as a sequence of elementary operations ?

$$\begin{array}{lll} \text{E.g. : } z = y + \cos(x^2) & x_1 = x_0^2 & x'_1 = 2x_0x'_0 \\ & x_2 = \cos(x_1) & x'_2 = -x'_0 \sin(x_0) \\ & z = y + x_2 & z' = y' + 2x_2x'_2 \end{array}$$

**Derivative of a sequence of instruction**



**sequence of instruction** × **sequence of derivatives**

**Forward Mode differentiation** [Wengert, 1964]

$(x_1, x'_1) \rightarrow (x_2, x'_2) \rightarrow (z, z')$ .

**Reverse Mode differentiation:** [Speelmaning, Rall, 1980s]

$x_1 \rightarrow x_2 \rightarrow z \rightarrow z' \rightarrow x'_2 \rightarrow x'_1$  while keeping formal the unknown derivative.

# Curry-Howard for semantics

*The syntax mirrors the semantics.*

Programs	Logic	Semantics
$\text{fun } (x:A) \rightarrow (t:B)$	Proof of $A \vdash B$	$f : A \rightarrow B.$
Types	Formulas	Objects
Execution	Cut-elimination	Equality

- ▶ Programs **acts on programs**.
  - ▶ Functions are higher-order: they act not only on  $\mathbb{R}^n$ , but also on  $\mathcal{C}^\infty(\mathbb{R}^n, \mathbb{R})$ .
- ▶ Programs **are typed**.
  - ▶  $Add : \mathcal{C}^\infty(\mathbb{R}^n, \mathbb{R}) \times \mathcal{C}^\infty(\mathbb{R}^n, \mathbb{R}) \rightarrow \mathcal{C}^\infty(\mathbb{R}^n, \mathbb{R})$
- ▶ Everything is interpreted in Categories.
  - ▶ Objects are Data
  - ▶ Functions are Programs
  - ▶ Transformations are functorial:

$$\mathcal{F}(p_1; p_2) = \mathcal{F}(p_1); \mathcal{F}(p_2)$$

$$\mathcal{F}(f_2 \circ f_1) = \mathcal{F}(f_2) \circ \mathcal{F}(f_1)$$

## Back to AD: I hate graphs

$$D_u(f \circ g) = D_{g(u)}f \circ D_u(g)$$

▶ **Forward Mode differentiation :**

$$g(u) \rightarrow D_u g \rightarrow f(g(u)) \rightarrow D_{g(u)}f \rightarrow D_{g(u)}f \circ D_u(g).$$

▶ **Reverse Mode differentiation:**

$$g(u) \rightarrow f(g(u)) \rightarrow D_{g(u)}f \rightarrow D_u(g) \rightarrow D_{g(u)}f \circ D_u(g)$$

The choice of an algorithm is due to complexity considerations:

- ▶ **Forward mode** for  $f \circ g : \mathbb{R} \rightarrow \mathbb{R}^n$ .
- ▶ **Reverse mode** for  $f \circ g : \mathbb{R}^n \rightarrow \mathbb{R}$

↪ *Differentiable programming* is a new research area triggered by the advances of deep learning algorithms on neural networks, it tries to attach two very old domains: lambda-calculus and automatic differentiation, with *correctness* and *modularity* goals in mind.

## AD from a functorial point of view

$$\mathbf{D}_u(f \circ g) = \mathbf{D}_{g(u)}f \circ \mathbf{D}_u(g)$$

Non-functorial !!!

How to make differentiation functorial ? Make it act on pairs !

$$f : E \Rightarrow F$$

**Forward Mode differentiation :**

$$f : E \Rightarrow F \rightsquigarrow \overrightarrow{D}f : E \Rightarrow E \multimap F.$$

$$\overrightarrow{D}(f) : \begin{cases} E \Rightarrow E \multimap F \\ u \mapsto v \mapsto D_u(f)(v) \end{cases}$$

**Functorial forward differentiation :**

$$(f, \overrightarrow{D}(f)) : \begin{cases} E \times E \rightarrow F \times F \\ (a, x) \mapsto (f(a), (D_a f \cdot x)) \end{cases}$$

# Reverse AD from a functorial point of view

How to make **reverse** differentiation functorial ?

Make it act on pairs with **linear duals** !



# Reverse functorial differentiation

## Linear Dual

$$A^\perp \equiv A \multimap \perp \equiv \mathcal{L}(A, \mathbb{R})$$

### ► Reverse Mode differentiation:

$$g(u) \rightarrow f(g(u)) \rightarrow D_{g(u)}f \rightarrow D_{g(u)}f \circ D_u(g)$$

$$f : E \Rightarrow F \rightsquigarrow \overleftarrow{D}f : E \Rightarrow F^\perp \Rightarrow E^\perp.$$

$$\overleftarrow{D}(f) : \begin{cases} E \Rightarrow F^\perp \multimap E^\perp \\ u \mapsto \ell \mapsto \ell \circ D_u(f) \end{cases}$$

[Mazza, Pagani, POPL2020]

### ► Reverse functorial differentiation :

$$(f, \overleftarrow{D}(f)) : (E \Rightarrow F) \times (E \Rightarrow F^\perp \Rightarrow E^\perp)$$

# Types !

Programs and variable are **typed**  
by logical formulas which describe their behavior

$$A \rightsquigarrow \exists x : \overbrace{\mathbb{W}(A)}^{\text{witness}}, \forall u : \underbrace{\mathbb{C}(A)}_{\text{opponent}}, A_D[x, u]$$

**Witness and counter types :**

$$\mathbb{C}(A \Rightarrow B) = \mathbb{C}(A) \times \mathbb{C}(B)$$

$$\mathbb{W}(A \Rightarrow B) = (\mathbb{W}(A) \Rightarrow \mathbb{W}(B)) \times (\mathbb{W}(A) \Rightarrow \mathbb{C}(B) \Rightarrow \mathbb{C}(A))$$

**Reverse Mode differentiation:**

$$\text{Functorial} : (h, \overleftarrow{D}h) : (A \Rightarrow B) \times (A \Rightarrow B^\perp \multimap A^\perp)$$

**However:**

- ▶ Having the same type does not mean you're the same program.
- ▶ Some french (linear) logicians have a strong opinion on what proof differentiation should.

# Types !

Programs and variable are **typed**

by logical formulas which describe their behavior

$$A \rightsquigarrow \exists \overbrace{x : \mathbb{W}(A)}^{\text{global witness}}, \forall \underbrace{u : \mathbb{C}(A)}_{\text{local opponent}}, A_D[x, u]$$

**Witness and counter for implication types :**

$$\mathbb{C}(A \Rightarrow B) = \mathbb{C}(A) \times \mathbb{C}(B)$$

$$\mathbb{W}(A \Rightarrow B) = \overbrace{(\mathbb{W}(A) \Rightarrow \mathbb{W}(B))}^{\text{function}} \times \left( \mathbb{W}(A) \Rightarrow \underbrace{\mathbb{C}(B) \Rightarrow \mathbb{C}(A)}_{\text{reverse derivative}} \right)$$

**Reverse Mode differentiation:**

$$\text{Functorial} : (h, \overleftarrow{D}h) : (A \Rightarrow B) \times (A \Rightarrow B^\perp \multimap A^\perp)$$

**However:**

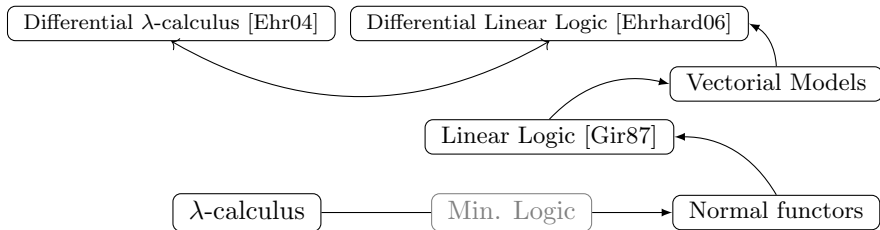
- ▶ Having the same type does not mean you're the same program.
- ▶ Some french (linear) logicians have a strong opinion on what proof differentiation should.

# A Linear Logic Refinement

# Curry-Howard for semantics

*The syntax mirrors the semantics.*

Programs	Logic	Semantics
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Execution	Cut-elimination	Equality



*Doing to proofs everything we do to functions*

# Linear Logic

Usual Implication

Linear and Non Linear Arrows

$$A \Rightarrow B = !A \multimap B$$
$$\mathcal{C}^\infty(A, B) \simeq \mathcal{L}(!A, B)$$

*A proof is linear when it uses only once its hypothesis A.*

- ▶ Notions of **ressources** which have made their way into programming through **linear types**.
- ▶ The dynamics of linearity gets encoded through the rules of the ! connective, and its dual ?.

$$A, B := A \otimes B \mid A \wp B \mid A \oplus B \mid A \& B \mid !A \mid ?A$$

# Linear Logic

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# Linear Logic

Usual implication

Linear and Non Linear Arrows

Linear Implication

$$A \Rightarrow B = !A \multimap B$$

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Exponential

*A proof is linear when it uses only once its hypothesis A.*

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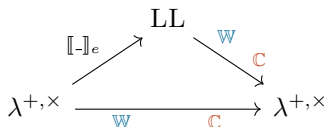
# Dialectica factorizes through Linear Logic

## The call by name arrow

$$A \Rightarrow B := !A \multimap B := ((!A) \otimes B^\perp)^\perp$$

$$\begin{array}{ll} \mathbb{W}(A^\perp) & := \mathbb{C}(A) & \mathbb{C}(A^\perp) & := \mathbb{W}(A) \\ \mathbb{W}(!A) & := \mathbb{W}(A) & \mathbb{C}(!A) & := \mathbb{W}(A) \Rightarrow \mathbb{C}(A) \end{array}$$

$$\begin{array}{ll} \mathbb{W}(A \otimes B) & := \mathbb{W}(A) \times \mathbb{W}(B) \\ \mathbb{C}(A \otimes B) & := (\mathbb{W}(A) \Rightarrow \mathbb{C}(B)) \times (\mathbb{W}(B) \Rightarrow \mathbb{C}(A)) \end{array}$$



Valeria de Paiva, 1989, A dialectica-like model of linear logic.

# Differential Linear Logic

$$\frac{\vdash \ell : A \multimap B}{\vdash \ell : !A \multimap B} d$$

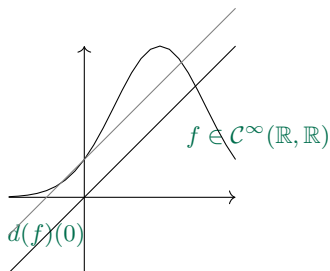
A linear proof

is in particular non-linear.

$$\frac{\vdash f : !A \multimap B}{\vdash D_0 f : A \multimap B} \bar{d}$$

From a non-linear proof

we can extract a linear proof



Differential interaction nets, Ehrhard and Regnier, TCS (2006)

# Exponential rules of Differential Linear Logic

## Exponential connectives:

$$[!A] := \mathcal{C}^\infty([A], \mathbb{K})' \quad [?A] := \mathcal{C}^\infty([A]', \mathbb{K})$$

$$\frac{\vdash \Gamma}{\vdash \Gamma, \mathit{cst}_1 : ?A} w$$

$$\frac{\vdash \Gamma, f : ?A, g : ?A}{\vdash \Gamma, f.g : ?A} c$$

$$\frac{\vdash \Gamma, \ell : A}{\vdash \Gamma, \ell : ?A} d$$

$$\frac{\vdash \Gamma}{\vdash \Gamma, \delta_0 : !A} \bar{w}$$

$$\frac{\vdash \Gamma, \phi : !A \quad \vdash \Delta, \psi : !A}{\vdash \Gamma, \Delta, \psi * \phi : !A} \bar{c}$$

$$\frac{\vdash \Gamma, x : A}{\vdash \Gamma, D_0(-)(x) : !A} \bar{d}$$

$$\frac{? \Gamma \vdash x : A}{? \Gamma \vdash \delta_x : !A} p$$

# Differentiation in Differential Linear Logic

The only thing you need to know:

$$\frac{\frac{\vdash \Gamma, \delta_u : !A \quad \frac{\vdash \Gamma, v : A}{\vdash \Gamma, D_0(-)(v) : !A} \bar{d}}{\vdash \Gamma, \Delta, D_u(-)(v) : !A} \bar{c}}$$

# Dialectica factorizes through Differential Linear Logic

Witnesses are functorial reverse derivative

$$\mathbb{W}(A \Rightarrow B) = (\mathbb{W}(A) \Rightarrow \mathbb{W}(B)) \times (\mathbb{W}(A) \Rightarrow \mathbb{C}(B) \Rightarrow \mathbb{C}(A))$$

$$\begin{array}{ll}
 \mathbb{W}(A \otimes B) & := \mathbb{W}(A) \otimes \mathbb{W}(B) & \mathbb{C}(A \otimes B) & := (\mathbb{W}(A) \multimap \mathbb{C}(B)) \\
 \mathbb{W}(A \multimap B) & := (\mathbb{W}(A) \multimap \mathbb{W}(B)) & & \oplus (\mathbb{W}(B) \multimap \mathbb{C}(A)) \\
 & \& (\mathbb{C}(B) \multimap \mathbb{C}(A)) & \mathbb{C}(A \multimap B) & := \mathbb{W}(A) \otimes \mathbb{C}(B) \\
 \mathbb{W}(A \& B) & := \mathbb{W}(A) \& \mathbb{W}(B) & \mathbb{C}(A \& B) & := \mathbb{C}(A) \oplus \mathbb{C}(B) \\
 \mathbb{W}(A \oplus B) & := \mathbb{W}(A) \oplus \mathbb{W}(B) & \mathbb{C}(A \oplus B) & := \mathbb{C}(A) \& \mathbb{C}(B) \\
 \mathbb{W}(!A) & := !\mathbb{W}(A) & \mathbb{C}(!A) & := !\mathbb{W}(A) \multimap \mathbb{C}(A)
 \end{array}$$

If  $\Gamma \vdash A$  in LL, then  $\mathbb{W}(\Gamma) \vdash \mathbb{W}(A)$  in classical DiLL.

$$\frac{\frac{\frac{}{\vdash A, A^\perp} \text{ax}}{\vdash A, !A^\perp} \bar{d}}{\vdash ?A, A, !A^\perp} \bar{c} \quad \frac{\frac{}{\vdash ?A, !A^\perp} \text{ax}}{\vdash ?A} \bar{c}}{\Gamma \vdash ?A, A} \text{cut} \quad \frac{\pi}{\Gamma \vdash ?A}$$

# Dialectica factorizes through Differential Linear Logic

## The economical translation

$$\llbracket A \Rightarrow B \rrbracket_e := !A \multimap B$$

$$\llbracket A \times B \rrbracket_e := A \& B$$

$$\llbracket A + B \rrbracket_e := A \oplus B$$

$$\begin{array}{ccc} \text{ILL} & \xrightarrow[\text{C}]{\text{W}} & \text{IDiLL} \\ \llbracket - \rrbracket_e \uparrow & & \downarrow \dots \\ \lambda^{+, \times} & \xrightarrow[\text{C}]{\text{W}} & \lambda^{+, \times} \end{array}$$

**IDILL : Intuitionnistic Differential Linear Logic ? Oh no ...**

$$A \rightsquigarrow \exists \overbrace{x : \mathbb{W}(A)}^{\text{witness}}, \forall \underbrace{u : \mathbb{C}(A)}_{\text{opponent}}, A_D[x, u]$$

Let's say  $x, u, f, g$  are  $\lambda$ -terms.

## The computational Dialectica : a reverse Differential $\lambda$ -calculus

"Behind every successful proof there is a program", *Gödel's wife*

# A computational Dialectica

Making Dialectica act on  $\lambda$ -terms instead of formulas.

$\lambda$ -terms with an extra type allowing for sums

$$\frac{}{\Gamma \vdash \emptyset : \mathfrak{M} A} \qquad \frac{\Gamma \vdash m_1 : \mathfrak{M} A \quad \Gamma \vdash m_2 : \mathfrak{M} A}{\Gamma \vdash m_1 \otimes m_2 : \mathfrak{M} A}$$
$$\frac{\Gamma \vdash t : A}{\Gamma \vdash \{t\} : \mathfrak{M} A} \qquad \frac{\Gamma \vdash m : \mathfrak{M} A \quad \Gamma \vdash f : A \Rightarrow \mathfrak{M} B}{\Gamma \vdash m \gg= f : \mathfrak{M} B}$$

$$\begin{aligned} \mathbb{W}(A \Rightarrow B) &:= (\mathbb{W}(A) \Rightarrow \mathbb{W}(B)) \\ &\quad \times (\mathbb{C}(B) \Rightarrow \mathbb{W}(A) \Rightarrow \mathfrak{M} \mathbb{C}(A)) \\ \mathbb{C}(A \Rightarrow B) &:= \mathbb{W}(A) \times \mathbb{C}(B) \end{aligned}$$



# Pédrot's Dialectica Transformation

## Soundness [Ped14]

If  $\Gamma \vdash t : A$  in the source then we have in the target

- ▶  $\mathbb{W}(\Gamma) \vdash t^\bullet : \mathbb{W}(A)$
- ▶  $\mathbb{W}(\Gamma) \vdash t_x : \mathbb{C}(A) \Rightarrow \mathfrak{M} \mathbb{C}(X)$  provided  $x : X \in \Gamma$ .

## A global and a local transformation

$$\begin{array}{ll} x^\bullet & := x & (\lambda x. t)^\bullet & := (\lambda x. t^\bullet, \lambda \pi x. t_x \pi) \\ x_x & := \lambda \pi. \{\pi\} & (\lambda x. t)_y & := \lambda \pi. (\lambda x. t_y) \pi.1 \pi.2 \\ x_y & := \lambda \pi. \emptyset \text{ if } x \neq y & (t u)^\bullet & := (t^\bullet.1) u^\bullet \end{array}$$

$$(t u)_y := \lambda \pi. (t_y (u^\bullet, \pi)) \circledast ((t^\bullet.2) \pi u^\bullet \gg= u_y)$$

## Flashback: Differential $\lambda$ -calculus [Ehrhard, Regnier 04]

Inspired by denotational models of Linear Logic in vector spaces of sequences, it introduces a differentiation of  $\lambda$ -terms.

$D(\lambda x.t)$  is the **linearization** of  $\lambda x.t$ , it substitute  $x$  linearly, and then it remains a term  $t'$  where  $x$  is free.

Syntax:

$$\begin{aligned}\Lambda^d : S, T, U, V &::= 0 \mid s \mid s+T \\ \Lambda^s : s, t, u, v &::= x \mid \lambda x.s \mid sT \mid \mathbf{D}s \cdot t\end{aligned}$$

Operational Semantics:

$$\begin{aligned}(\lambda x.s)T &\rightarrow_{\beta} s[T/x] \\ \mathbf{D}(\lambda x.s) \cdot t &\rightarrow_{\beta_D} \lambda x. \frac{\partial s}{\partial x} \cdot t\end{aligned}$$

where  $\frac{\partial s}{\partial x} \cdot t$  is the **linear substitution** of  $x$  by  $t$  in  $s$ .

# Linearity in Linear Logic

**Linearity is about resources:** A proof/program is *linear* iff it uses only once its hypotheses/argument.

Linear	Non-linear
$A \vdash A \vee B$	$A \vdash A \wedge A$
$\lambda f \lambda x. f x x$	$\lambda x. \lambda f. f x x$

Differentiation is about making a  $\lambda$ -term linear :

$\rightsquigarrow$  about making a  $\lambda$ -term have a linear usage of its arguments.

$$\lambda x \lambda f. f x x \rightsquigarrow ?$$

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$$D(\lambda x \lambda f. f x x) \cdot v := \lambda x. \lambda f. v x + ?$$

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Differentiation is about making a  $\lambda$ -term linear :

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$$D(\lambda x \lambda f. fxx) \cdot v := \lambda x. \lambda f. vx + \lambda x. \lambda f. Dxxv$$

## The linear substitution ...

... which is not exactly a substitution

$$\frac{\partial y}{\partial x} \cdot t = \begin{cases} t & \text{if } x = y \\ 0 & \text{otherwise} \end{cases} \quad \frac{\partial}{\partial x}(tu) \cdot s = \left(\frac{\partial t}{\partial x} \cdot s\right)u + (Dt \cdot \left(\frac{\partial u}{\partial x} \cdot s\right))u$$

$$\frac{\partial}{\partial x}(\lambda y \cdot s) \cdot t = \lambda y \cdot \frac{\partial s}{\partial x} \cdot t \quad \frac{\partial}{\partial x}(Ds \cdot u) \cdot t = D\left(\frac{\partial s}{\partial x} \cdot t\right) \cdot u + Ds \cdot \left(\frac{\partial u}{\partial x} \cdot t\right)$$

$$\frac{\partial 0}{\partial x} \cdot t = 0 \quad \frac{\partial}{\partial x}(s + u) \cdot t = \frac{\partial s}{\partial x} \cdot t + \frac{\partial u}{\partial x} \cdot t$$

$\frac{\partial s}{\partial x} \cdot t$  represents  $s$  where  $x$  is linearly (i.e. one time) substituted by  $t$ .

# The linear substitution ...

## The computational Dialectica

$$\frac{\partial y}{\partial x} \cdot t = \begin{cases} t & \text{if } x = y \\ 0 & \text{otherwise} \end{cases} \quad \frac{\partial}{\partial x}(tu) \cdot s = \left(\frac{\partial t}{\partial x} \cdot s\right)u + (Dt \cdot \left(\frac{\partial u}{\partial x} \cdot s\right))u$$

$$x_y \cdot \pi = \begin{cases} \pi & \text{if } x = y \\ \emptyset & \text{otherwise} \end{cases} \quad (t u)_y := \lambda \pi. (t_y (u^\bullet, \pi)) \otimes ((t^\bullet \cdot 2) \pi u^\bullet \gg= u_y)$$

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# Tracking differentiation in Dialectica

$$\begin{array}{ll} x_x & := \lambda \pi. \{\pi\} & x^\bullet & := x \\ x_y & := \lambda \pi. \emptyset \quad \text{if } x \neq y & (\lambda x. t)^\bullet & := (\lambda x. t^\bullet, \lambda x \pi. t_x \pi) \\ (\lambda x. t)_y & := \lambda \pi. (\lambda x. t_y) \pi.1 \pi.2 & (t u)^\bullet & := (t^\bullet.1) u^\bullet \end{array}$$

$$(t u)_y := \lambda \pi. (t_y (u^\bullet, \pi)) \otimes ((t^\bullet.2) u^\bullet \pi \gg= u_y)$$



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$$(t u)_y := \lambda\pi. (t_y (u^\bullet, \pi)) \circledast ((t^\bullet.2) u^\bullet \pi \ggg = u_y)$$

## That's reverse differentiation

- ▶  $(-)^{\bullet.2}$  obeys the chain rule,  $(-)^{\bullet}$  is the functorial differentiation.
- ▶  $t_x$  is contravariant in  $x$ , representing a reverse linear substitution.

## Theorem [K. Pédrot 22]

$$\llbracket u \ggg = t_x[\Gamma \leftarrow \vec{r}^\bullet] \rrbracket \equiv_{\beta, \eta} \lambda z. (\llbracket u \rrbracket ((\partial x. t[\Gamma \leftarrow \vec{r}^\bullet])z))$$

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Dialectica is differentiation in categories

*That's already known through lenses !*

# What's categorical differentiation ?

**To cook a good differential category, one needs :**

- ▶ A category of regular/continuous/non-linear functions

$$\mathbb{C}(A, B) = !A \multimap B .$$

- ▶ A category of linear functions, in which differentiation embeds

$$\mathcal{L}(A, B) = A \multimap B .$$

- ▶ Something which linearizes :

$$\bar{d} : A \rightarrow !A$$

- ▶ A notion of duality, if one wants to encode reverse. differentiation.

↪ Basically, one wants a categorical model of DILL.

# Dialectica categories

## Categories representing specific relations

Consider a category  $\mathcal{C}$ .  $\mathbf{Dial}(\mathcal{C})$  is constructed as follows:

- ▶ Objects : relations  $\alpha \subseteq U \times X, \beta \subseteq V \times Y$ .
- ▶ Maps from  $\alpha$  to  $\beta$  :

$$(f : U \rightarrow V, F : U \times Y \rightarrow X)$$

- ▶ Composition : the chain rule !

Consider

$$\begin{array}{l} (f, F) : \alpha \subseteq (A, X) \rightarrow \beta \subseteq (B, Y) \\ \text{and } (g, G) : \beta \subseteq (B, Y) \rightarrow \gamma \subseteq (C, Z) \end{array}$$

two arrows of the Dialectica category. Then their composition is defined as

$$(g, G) \circ (f, F) := (g \circ f, (a, z) \mapsto F(a, G(f(a), z))).$$

# Dialectica categories through Differential Categories

In a  $*$ -autonomous differential category :

$$\partial : Id \otimes ! \rightarrow !$$

$$\mathcal{L}(B \otimes A, C^\perp) \simeq \mathcal{L}(A, (B \otimes C)^\perp)$$

from  $f : !A \rightarrow B$  one constructs :

$$\overleftarrow{D}(f) \in \mathcal{L}(!A \otimes B^\perp, A^\perp).$$

## Dialectica categories factorize through differential categories

If  $\mathcal{L}$  is a model of DILL such that  $\mathcal{L}!$  has finite limits:

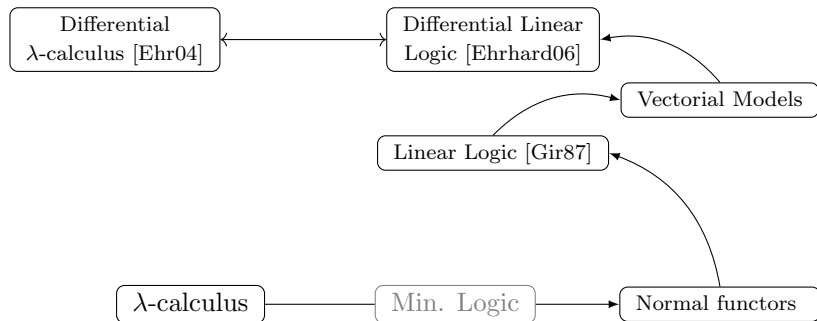
$$\left\{ \begin{array}{l} \mathcal{L}! \rightarrow \mathcal{D}(\mathcal{L}!) \\ A \mapsto A \times A^\perp \\ f \mapsto (f, \overleftarrow{D}(f)) \end{array} \right.$$

We have an obvious forgetful functor:

$$U : \left\{ \begin{array}{l} \mathcal{D}(\mathcal{L}!) \rightarrow \mathcal{L}! \\ \alpha \subseteq A \times X \mapsto A \\ (f, F) \mapsto f \end{array} \right.$$

# Recap

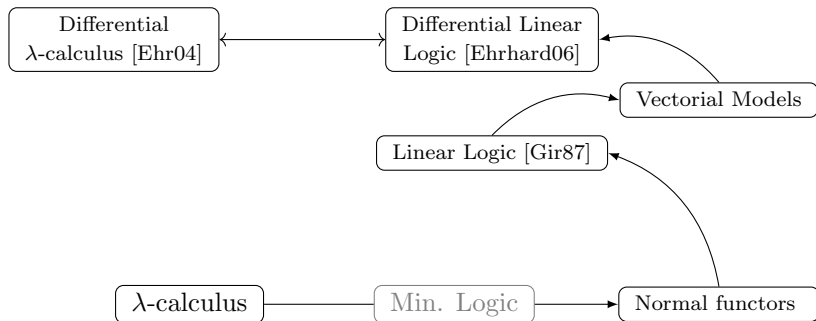
<b>Programs</b>	<b>Logic</b>	<b>Semantics</b>
$\text{fun } (x:A) \rightarrow (t:B)$	Proof of $A \vdash B$	$f : A \rightarrow B.$
Types	Formulas	Objects
Execution	Cut-elimination	Equality





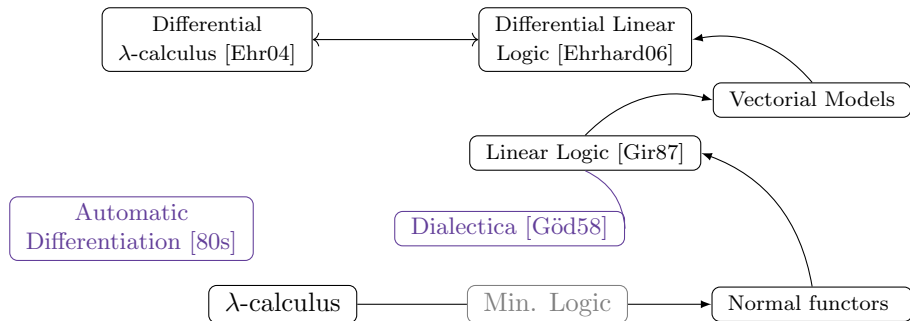
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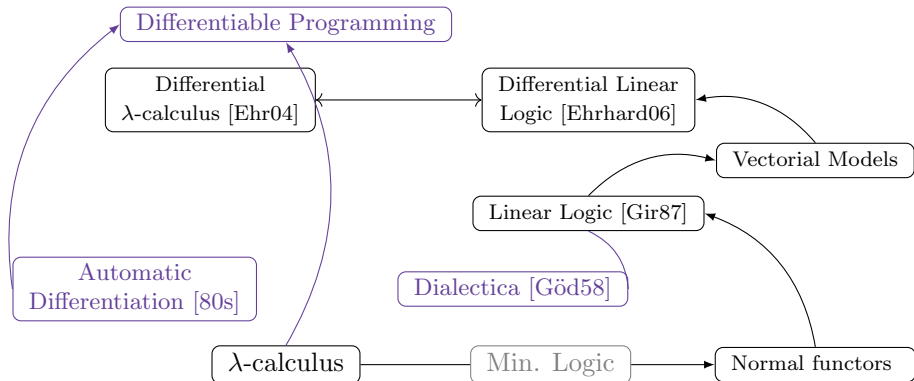
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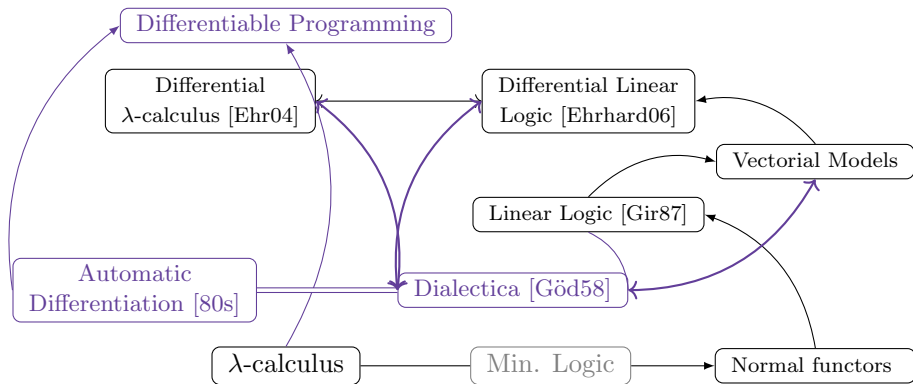
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# Recap

Programs	Logic	Semantics
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*A good point for logicians : Gödel invented Dialectica 40 years before reverse differentiation was put to light*

## Conclusion and applications

Take home message:

**Dialectica is functorial reverse differentiation,**  
extracting ~~intensional~~ local content from proofs.

A new semantical correspondance between computations and mathematics :  
~~intentional meaning~~ of program is **local behaviour** of functions.

Program	Proof	Function
Quantitative	Resources	Linearity
<b>Control</b>	<b>Classical Principles</b>	<b>Differentiation</b>

**Related work and potential applications:**

- ▶ **Markov's principle** and delimited continuations on positive formulas.
- ▶ **Proof mining** and backpropagation.
- ▶ **Bar Induction** and Taylor Exponentiation.

# Dialectica is differentiation ...

... We knew it already !

*The codereliction of differential proof nets:* In terms of polarity in linear logic [23], the  $\forall\multimap$ -free constraint characterizes the formulas of intuitionistic logic that can be built only from positive connectives ( $\oplus$ ,  $\otimes$ ,  $0$ ,  $1$ ,  $!$ ) and the why-not connective (“?”). In this framework, Markov’s principle expresses that from such a  $\forall\multimap$ -free formula  $A$  (e.g.  $? \oplus_x (?A(x) \otimes ?B(x))$ ) where the presence of “?” indicates that the proof possibly used weakening (efq or throw) or contraction (catch), a linear proof of  $A$  purged from the occurrences of its “?” connective can be extracted (meaning for the example above a proof of  $\oplus_x (A(x) \otimes B(x))$ ). Interestingly, the removal of the “?”, i.e. the steps from  $?P$  to  $P$ , correspond to applying the codereliction rule of differential proof nets [24].

**Differentiation :**  $(?P = (P \multimap \perp) \Rightarrow \perp) \rightarrow ((P \multimap \perp) \multimap \perp) \equiv P$



Hugo Herbelin, “An intuitionistic logic that proves Markov’s principle”, LICS ’10 .

# Differentiation and delimited continuations

## Herbelin Lics'10

Markov's principle is proved by allowing `catch` and `throw` operations on hereditary positive formulas.

$$\frac{\frac{\frac{\overline{a : \neg\neg T \vdash_{\alpha:T} a : \neg\neg T} \text{ AXIOM} \quad \frac{\overline{b : T \vdash_{\alpha:T} b : T} \text{ AXIOM} \quad \frac{\overline{b : T \vdash_{\alpha:T} \text{throw}_{\alpha} b : \perp}}{\vdash_{\alpha:T} \lambda b. \text{throw}_{\alpha} b : \neg T} \text{ THROW}}{\vdash_{\alpha:T} \lambda b. \text{throw}_{\alpha} b : \neg T} \rightarrow_I}{\vdash_{\alpha:T} \lambda b. \text{throw}_{\alpha} b : \neg T} \rightarrow_E}{\frac{\overline{a : \neg\neg T \vdash_{\alpha:T} a (\lambda b. \text{throw}_{\alpha} b) : \perp}}{\vdash_{\alpha:T} a (\lambda b. \text{throw}_{\alpha} b) : T} \perp_E}{\frac{\overline{a : \neg\neg T \vdash_{\alpha:T} \text{efq } a (\lambda b. \text{throw}_{\alpha} b) : T}}{\vdash_{\alpha:T} \text{catch}_{\alpha} \text{efq } a (\lambda b. \text{throw}_{\alpha} b) : T} \text{ CATCH}}{\vdash \lambda a. \text{catch}_{\alpha} \text{efq } a (\lambda b. \text{throw}_{\alpha} b) : \neg\neg T \rightarrow T} \rightarrow_I} \text{ MP}$$

Figure 3. Proof of *MP*



## Extracting quantitative information from proofs.

Effective moduli from ineffective uniqueness proofs. An unwinding of de La Vallée Poussin's proof for Chebycheff approximation\*

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### Abstract

We consider uniqueness theorems in classical analysis having the form

$$(+) \forall u \in U, v_1, v_2 \in V_u (G(u, v_1) = 0 = G(u, v_2) \rightarrow v_1 = v_2),$$

where  $U, V$  are complete separable metric spaces,  $V_u$  is compact in  $V$  and  $G : U \times V \rightarrow \mathbb{R}$  is a constructive function.

If  $(+)$  is proved by arithmetical means from analytical assumptions

$$(++) \forall x \in X \exists y \in Y_x \forall z \in Z (F(x, y, z) = 0)$$

only (where  $X, Y, Z$  are complete separable metric spaces,  $Y_x \subset Y$  is compact and  $F : X \times Y \times Z \rightarrow \mathbb{R}$  constructive), then we can extract from the proof of  $(++) \rightarrow (+)$  an effective modulus of uniqueness, i.e.

$$(+++ ) \forall u \in U, v_1, v_2 \in V_u, k \in \mathbb{N} (|G(u, v_1)|, |G(u, v_2)| \leq 2^{-\Phi u k} \rightarrow d_V(v_1, v_2) \leq 2^{-k}).$$

# Proof Mining

Markov's principle and the independence of premises are necessary for most of **mathematical analysis proofs** :

Proof mining allows to refine these proofs by taking away these principles as guaranteed by (some variant of) Dialectica's transformation.

## Conjecture

Does it differentiate the function  $(\epsilon \rightarrow \eta)$  in :

$$\forall u, v_1, v_2, \forall \epsilon > 0, \exists \eta > 0, \|G(u, v_1) - G(u, v_2)\| < \eta \rightarrow d_V(v_1, v_2) < \epsilon$$

?

Is proof mining (based on) [reverse differentiation applied to proofs](#)?

What else can we explain by differentiation ?

Thank you for Listening !