Solutions of BVPs in the Fully Coupled Theory of Elasticity for a Sphere with Double Porosity

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The purpose of this paper is to consider the basic boundary value problems of the fully coupled equilibrium theory of elasticity for solids with double porosity and explicitly solve the BVPs of statics in the fully coupled theory for a sphere. The explicit solutions of these BVPs are represented by means of absolutely and uniformly convergent series.

Keywords: Double porosity, Explicit solution, Sphere.

AMS Subject Classification: 74F10, 74G05.

1. Introduction

The theory of consolidation with double porosity was first proposed by Aifantis and co-authors in the papers [1,3]. This theory unifies a model proposed by Biot for the consolidation of deformable single porosity media with a model proposed by Barenblatt for seepage in undeformable media with two degrees of porosity. In a material with two degrees of porosity, there are two pore systems, the primary and the secondary. For example in a fissured rock (i.e.a mass of porous blocks separated from each other by an interconnected and continuously distributed system of fissures) most of the porosity is provided by the pores of the blocks or primary porosity, while most of permeability is provided by the fissures or the secondary porosity. In part I of a series of paper on the subject, Wilson and Aifantis [1] gave detailed physical interpretations of the phenomenological coefficients appearing in the double porosity theory. In part II of this series, uniqueness and variational principles were established by Beskos and Aifantis [2] for the equations of double porosity, while in part III Khaled, Beskos and Aifantis [3] provided a related finite element to consider the numerical solution of Aifantis' equations of double porosity (see [1],[2],[3] and the references cited therein.) The basic results and the historical information on the theory of porous media may be found in [4]. However, Aifantis' quasi-static theory ignored the cross-coupling effect between the volume change of the pores and fissures in the system. The cross-coupled terms were included in the equations of conservation of mass for the pore and fissure fluid and in Darcy's law for solids with double porosity by Khalili and coauthors in [5,8]. The phenomeno-

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logical equations of the quasi-static theory for double porous media are established in [9,10], where a method to calculate the relevant coefficients is also presented.

For the past years many authors have investigated the BVPs of the theory of elasticity for materials with double porosity, publishing a large number of papers (for details see [11-16] and references therein).

In [17-20] the fully coupled linear theory of elasticity is considered for solids with double porosity. Four special cases of the dynamical equations are considered. The fundamental solutions are constructed by means of elementary functions and the basic properties of the fundamental solutions are established. In [21,22] for Aifantis' equations, explicit solution of the problems of elastostatics for an elastic circle with double porosity, are considered. In [23-25], for Aifantis' equations, the explicit solutions of some BVPs of elasticity for an elastic sphere, for the space with a spherical cavity and for the half-space are constructed.

The purpose of this paper is to consider the basic boundary value problems of the fully coupled equilibrium theory of elasticity for solids with double porosity and explicitly solve the BVPs of statics in the fully coupled theory for a sphere. The explicit solutions of these BVPs are represented by means of absolutely and uniformly convergent series.

2. Basic equations and boundary value problems

Let $\mathbf{x} = (x_1, x_2, x_3)$ be a point of the Euclidean three-dimensional space E^3 . Let us assume that D is a ball of radius R, centered at point O(0, 0, 0) in space E^3 and Sis a spherical surface of radius R. Let us assume that the domain D is filled with an isotropic material with double porosity.

The system of homogeneous equations in the fully coupled linear equilibrium theory of elasticity for materials with double porosity can be written as follows [6,17]

$$\mu \Delta \mathbf{u} + (\lambda + \mu) graddiv \mathbf{u} - grad(\beta_1 p_1 + \beta_2 p_2) = 0, \tag{1}$$

$$(k_{1}\Delta - \gamma)p_{1} + (k_{12}\Delta + \gamma)p_{2} = 0,$$

$$(k_{21}\Delta + \gamma)p_{1} + (k_{2}\Delta - \gamma)p_{2} = 0,$$
(2)

where $\mathbf{u}(\mathbf{x}) = \mathbf{u}(u_1, u_2, u_3)$ is the displacement vector in a solid, $p_1(\mathbf{x})$ and $p_2(\mathbf{x})$ are the pore and fissure fluid pressures respectively. β_1 and β_2 are the effective stress parameters, $\gamma > 0$ is the internal transport coefficient and corresponds to fluid transfer rate with respect to the intensity of flow between the pore and fissures, λ , μ , are constitutive coefficients, $k_j = \frac{\kappa_j}{\mu'}$, $k_{12} = \frac{\kappa_{12}}{\mu'}$, $k_{21} = \frac{\kappa_{21}}{\mu'}$. μ' is the fluid viscosity, κ_1 and κ_2 are the macroscopic intrinsic permeabilities associated with matrix and fissure porosity, respectively, κ_{12} and κ_{21} are the cross-coupling permeabilities for fluid flow at the interface between the matrix and fissure phases, Δ is the Laplace operator. If needed, we consider vectors as column matrices.

Introduce the definition of a regular vector-function.

Definition 2.1: A vector-function $\mathbf{U}(\mathbf{x}) = (u_1, u_2, u_3, p_1, p_2)$ defined in the do-

main D is called regular if it has integrable continuous second derivatives in Dand $\mathbf{U}(\mathbf{x})$ itself and its first order derivatives are continuously extendable at every point of the boundary of D, i.e., $\mathbf{U}(\mathbf{x}) \in C^2(D) \bigcap C^1(\overline{D})$.

For system (1),(2) we pose the following BVPs.

Problem 1: Find in the domain D a regular solution $\mathbf{U}(\mathbf{x}) = (\mathbf{u}, p_1, p_2)$, of equations (1),(2) by the boundary conditions

$$\mathbf{u}^+(\mathbf{z}) = \mathbf{\Psi}(\mathbf{z}), \quad p_1^+(\mathbf{z}) = f_4(\mathbf{z}), \quad p_2^+(\mathbf{z}) = f_5(\mathbf{z}), \quad \mathbf{z} \in S.$$
 (3)

Problem 2: Find in the domain *D* a regular solution $\mathbf{U}(\mathbf{x}) = (\mathbf{u}, p_1, p_2)$, of equations (1),(2) by the boundary conditions

$$[\mathbf{P}(\partial \mathbf{x}, \mathbf{n})\mathbf{U}]^{+} = \mathbf{G}(\mathbf{z}), \quad \left(\mathbf{P}^{(1)}(\partial \mathbf{x}, \mathbf{n})\mathbf{p}\right)^{+} = \mathbf{g}(\mathbf{z}), \quad \mathbf{z} \in S,$$
(4)

where $[\cdot]^+$ denotes the limiting value from D, the vector-functions $\Psi(\mathbf{z}) = (\Psi_1, \Psi_2, \Psi_3)$, $\mathbf{G}(\mathbf{z}) = (G_1, G_2, G_3)$, $\mathbf{g}(\mathbf{z}) = (g_1, g_2)$ and the functions $f_4(\mathbf{z}), f_5(\mathbf{z})$ are given functions on S, $\mathbf{n}(\mathbf{z}) = (n_1, n_2, n_3)$ is the external unit normal vector on S at \mathbf{z} and $\mathbf{P}(\partial \mathbf{x}, \mathbf{n})\mathbf{U}$ is the stress vector in the considered theory, which acts on the elements of S with the normal \mathbf{n} ,

$$\mathbf{P}(\partial \mathbf{x}, \mathbf{n})\mathbf{U} = \mathbf{T}(\partial \mathbf{x}, \mathbf{n})\mathbf{u} - \mathbf{n}(\beta_1 p_1 + \beta_2 p_2),$$

 $\mathbf{T}(\partial \mathbf{x}, \mathbf{n})\mathbf{u}$ is the stress vector in the classical theory of elasticity

$$\mathbf{T}(\partial \mathbf{x}, \mathbf{n})\mathbf{u}(\mathbf{x}) = 2\mu \frac{\partial \mathbf{u}(\mathbf{x})}{\partial n} + \lambda \mathbf{n} div \mathbf{u}(\mathbf{x}) + \mu [\mathbf{n} \times rot \mathbf{u}(\mathbf{x})],$$

and

$$\mathbf{P}^{(1)}(\partial \mathbf{x}, \mathbf{n})\mathbf{p} = \begin{pmatrix} k_1 & k_{12} \\ k_{21} & k_2 \end{pmatrix} \frac{\partial \mathbf{p}}{\partial \mathbf{n}}, \quad \mathbf{p} = (p_1, p_2),$$
$$\frac{\partial}{\partial \mathbf{n}} = n_1 \frac{\partial}{\partial x_1} + n_2 \frac{\partial}{\partial x_2} + n_3 \frac{\partial}{\partial x_3}.$$

Note that BVPs for the system (2) which contain only p_1 and p_2 can be investigated separately. Then suppose p_j as known we can study BVPs for system (1) with respect to **u**. Combining the results obtained we arrive at explicit solutions of BVPs for system (1)-(2).

On the basis of equations (2) we can write

$$\Delta(\Delta + \lambda_1^2)p_j = 0, \qquad j = 1, 2.$$

We can easily see that the solution of system (2) can be represented in the form

$$p_1(\mathbf{x}) = \varphi(\mathbf{x}) + A\varphi_1(\mathbf{x}), \quad p_2(\mathbf{x}) = \varphi(\mathbf{x}) + \varphi_1(\mathbf{x}),$$
 (5)

where the functions φ and φ_1 are the solutions of the following equations

$$\Delta \varphi = 0, \quad (\Delta + \lambda_1^2)\varphi_1 = 0, \tag{6}$$

respectively,

$$A = \frac{\gamma - k_{12}\lambda_1^2}{\gamma + k_1\lambda_1^2} = -\frac{k_2 + k_{12}}{k_1 + k_{21}},$$

$$\lambda_1 = i\sqrt{\frac{\gamma k_0}{k_1 k_2 - k_{12} k_{21}}} = i\lambda_0, \quad i = \sqrt{-1}, \quad k_0 = k_1 + k_2 + k_{12} + k_{21};$$

$$k_1 > 0$$
, $k_2 > 0$, $\gamma > 0$, $k_1 k_2 - k_{12} k_{21} > 0$, $k_0 > 0$.

Let us substitute the expression (5) into (1) and let us search the particular solution of the following nonhomogeneous equation

$$\mu \Delta \mathbf{u} + (\lambda + \mu) graddiv \mathbf{u} = grad[(\beta_1 + \beta_2)\varphi + (A\beta_1 + \beta_2)\varphi_1].$$

It is well-known that a general solution of the last equation can be presented in the form

$$\mathbf{u}(\mathbf{x}) = \mathbf{v}(\mathbf{x}) + \mathbf{v}_0(\mathbf{x}),\tag{7}$$

where $\mathbf{v}(\mathbf{x})$ is a general solution of equation

$$\mu\Delta\mathbf{v} + (\lambda + \mu)graddiv\mathbf{v} = 0, \tag{8}$$

and $\mathbf{v}_0(\mathbf{x})$ is a particular solution of the nonhomogeneous equation. It is easy to see, that the vector $\mathbf{v}_0(\mathbf{x})$ has the form

$$\mathbf{v}_0(\mathbf{x}) = \frac{1}{\lambda + 2\mu} grad \left[(\beta_1 + \beta_2)\varphi_0(\mathbf{x}) - \frac{\beta_1 A + \beta_2}{\lambda_1^2} \varphi_1(\mathbf{x}) \right], \quad \mathbf{x} \in D,$$
(9)

where the function φ_0 must satisfy the condition $\Delta \varphi_0 = \varphi$. Thus, $\Delta \Delta \varphi_0 = 0$. We will study separately the following BVPs:

Problem B₁. Find in the domain D the regular solutions of system (6) satisfying the following boundary conditions

$$\varphi^+(\mathbf{z}) = h(\mathbf{z}), \quad \varphi_1^+(\mathbf{z}) = h_1(\mathbf{z}), \quad \mathbf{z} \in S,$$
 (10)

respectively, where $h(\mathbf{z})$ and $h_1(\mathbf{z})$ are known functions defined by formulas

$$h(\mathbf{z}) = \frac{1}{k_0} [(k_1 + k_{21})f_4(\mathbf{z}) + (k_2 + k_{12})f_5(\mathbf{z})],$$

$$h_1(\mathbf{z}) = \frac{1}{k_0} (k_1 + k_{21}) [f_5(\mathbf{z}) - f_4(\mathbf{z})].$$

Problem B₂. Find in the domain D the solutions of system (6) satisfying the following boundary conditions

$$\left(\frac{\partial\varphi}{\partial R}\right)^{+} = h_2(\mathbf{z}), \quad \left(\frac{\partial\varphi_1}{\partial R}\right)^{+} = h_3(\mathbf{z}), \quad \mathbf{z} \in S,$$
(11)

respectively, where

$$h_2(\mathbf{z}) = \frac{g_1(\mathbf{z}) + g_2(\mathbf{z})}{k_0},$$

$$h_3(\mathbf{z}) = \frac{(k_1 + k_{21})[(k_1 + k_{12})g_2(\mathbf{z}) - (k_2 + k_{21})g_1(\mathbf{z})]}{k_0(k_1k_2 - k_{12}k_{21})}.$$

Problem A₁. Find in the domain D a regular solution $\mathbf{v}(\mathbf{x})$ of equation (8), satisfying the following boundary condition

$$\mathbf{v}^+(\mathbf{z}) = \mathbf{\Psi}(\mathbf{z}) - \mathbf{v}_0(\mathbf{z}) = \boldsymbol{\omega}(\mathbf{z}), \quad \mathbf{z} \in S.$$
(12)

Problem A₂. Find in the domain D a solution $\mathbf{v}(\mathbf{x})$ of equation (8), satisfying the following boundary condition

$$[\mathbf{T}(\partial \mathbf{z}, \mathbf{n})\mathbf{v}(\mathbf{z})]^{+} = \mathbf{G}(\mathbf{z}) - \mathbf{T}(\partial \mathbf{z}, \mathbf{n})\mathbf{v}_{0}(\mathbf{z}) + \mathbf{n}[\beta_{1}p_{1}(\mathbf{z}) + \beta_{2}p_{2}(\mathbf{z})] = \mathbf{\Omega}(\mathbf{z}), \quad (13)$$
$$\mathbf{z} \in S.$$

In problems A_1 and A_2 the functions $p_1(\mathbf{x})$ and $p_2(\mathbf{x})$ are solutions of problems B_1 and B_2 respectively.

3. Explicit solutions of the boundary value problems

3.1. Problem B_1 .

Let us introduce the equalities of spherical coordinates

$$\begin{aligned} x_1 &= \rho \sin \vartheta \cos \eta, \quad x_2 = \rho \sin \vartheta \sin \eta, \quad x_3 = \rho \cos \vartheta, \quad x \in D^+, \\ y_1 &= R \sin \vartheta_0 \cos \eta_0, \quad y_2 = R \sin \vartheta_0 \sin \eta_0, \quad y_3 = R \cos \vartheta_0, \quad y \in S, \\ |x|^2 &= \rho^2 = x_1^2 + x_2^2 + x_3^2, \quad 0 \le \vartheta \le \pi, \quad 0 \le \eta \le 2\pi \quad 0 \le \rho \le R. \end{aligned}$$

Let us expand the functions h and h_1 in spherical harmonics

$$h(\mathbf{z}) = \sum_{n=0}^{\infty} h_n(\vartheta, \eta), \quad h_1(\mathbf{z}) = \sum_{n=0}^{\infty} h_{1n}(\vartheta, \eta),$$

where h_n and h_{1n} are the spherical harmonics of order n:

$$h_n = \frac{2n+1}{4\pi R^2} \int_S P_n(\cos\gamma)h(\mathbf{y})d_y S,$$

$$h_{1n} = \frac{2n+1}{4\pi R^2} \int\limits_{S} P_n(\cos\gamma) h_1(\mathbf{y}) d_y S,$$

 P_n is Legender polynomial of the n-th order, γ is an angle formed by the radius-vectors Ox and Oy,

$$\cos\gamma = \frac{1}{|\mathbf{x}||\mathbf{y}|} \sum_{k=1}^{3} x_k y_k.$$

For the unknowns harmonic function $\varphi(\mathbf{x})$ and metaharmonic function $\varphi_1(\mathbf{x})$ we obtain the Dirichlet BVPs for system (6) with boundary conditions (10). The solutions of Problem B_1 in D have the form [26,27]:

$$\varphi(\mathbf{x}) = \sum_{n=0}^{\infty} \frac{\rho^n}{R^n} h_n(\vartheta, \eta), \quad \rho < R,$$

$$\varphi_1(\mathbf{x}) = \sum_{n=0}^{\infty} \phi_n^{(1)}(\lambda_1 \rho) h_{1n}(\vartheta, \eta), \quad \rho < R,$$
(14)

respectively, where

$$\phi_n^{(1)}(\lambda_1 \rho) = \frac{\sqrt{RJ_{n+\frac{1}{2}}(\lambda_1 \rho)}}{\sqrt{\rho}J_{n+\frac{1}{2}}(\lambda_1 R)},$$

 $J_{n+\frac{1}{2}}(\lambda_1 \rho)$ is the Bessel function.

If we substitute the values of $\varphi(\mathbf{x})$ and $\varphi_1(\mathbf{x})$ from (14) into (5), we find the functions $p_1(\mathbf{x})$ and $p_2(\mathbf{x})$ in D.

For the solution of equation $\Delta \varphi_0 = \varphi$, where φ is given by (14), we have

$$\varphi_0(\mathbf{x}) = \frac{1}{2} \sum_{n=0}^{\infty} \frac{\rho^{n+2} h_n(\vartheta, \eta)}{(3+2n)R^n}, \quad \mathbf{x} \in D.$$
(15)

3.2. Problem B_2 .

For the unknowns harmonic function $\varphi(\mathbf{x})$ and metaharmonic function $\varphi_1(\mathbf{x})$ we obtain the Neumann BVPs for system (6) with boundary conditions (11). The

solutions of Problem B_2 in D have the form [27,28]:

$$\varphi(\mathbf{x}) = C + \sum_{n=1}^{\infty} \frac{\rho^n}{nR^{n-1}} h_{2n}(\vartheta, \eta), \quad \rho < R,$$

$$\varphi_1(\mathbf{x}) = \sum_{n=0}^{\infty} \frac{\phi_n^{(1)}(\lambda_1 \rho) h_{3n}(\vartheta, \eta)}{H_n(R)}, \quad \rho < R.$$
(16)

respectively, where

$$H_n(\rho) = \frac{\partial}{\partial \rho} \phi_n^{(1)}(\lambda_1 \rho), \quad \phi_n^{(1)}(\lambda_1 \rho) = \frac{J_{n+\frac{1}{2}}(\lambda_1 \rho)}{\sqrt{\rho}},$$

$$h_{2n} = \frac{2n+1}{4\pi R^2} \int\limits_{S} P_n(\cos\gamma) h_2(\mathbf{y}) d_y S,$$

$$h_{3n} = \frac{2n+1}{4\pi R^2} \int\limits_S P_n(\cos\gamma) h_3(\mathbf{y}) d_y S,$$

C is an arbitrary constant.

For the solution to exist it is necessary that the condition

$$h_{20} = \int\limits_{S} h_2(\mathbf{y}) ds = 0$$

be fulfilled.

If we substitute the values of $\varphi(\mathbf{x})$ and $\varphi_1(\mathbf{x})$ from (16) into (5), we find the functions $p_1(\mathbf{x})$ and $p_2(\mathbf{x})$ in D.

For the solution of equation $\Delta \varphi_0 = \varphi$, where φ is given by (16), we have

$$\varphi_0(\mathbf{x}) = \frac{\rho^2}{6}C + \frac{1}{2}\sum_{n=1}^{\infty} \frac{\rho^{n+2}h_{2n}(\vartheta,\eta)}{n(3+2n)R^{n-1}}, \quad \mathbf{x} \in D.$$
(17)

3.3. Problem A_1 .

For a ball the solution $\mathbf{v}(\mathbf{x})$ of equation (8), with boundary condition (12) is given in [29,30] in the following form

$$\rho \mathbf{v}(\mathbf{x}) = \mathbf{x}\psi_1(\mathbf{x}) + \left[\frac{\partial \psi_2(\mathbf{x})}{\partial s} \cdot \mathbf{x}\right] + \rho \frac{\partial \psi_3(\mathbf{x})}{\partial s}, \quad \mathbf{x} \in D,$$
(18)

where

$$\frac{\partial}{\partial s} = \left(\frac{\partial}{\partial s_1}, \frac{\partial}{\partial s_2}, \frac{\partial}{\partial s_3}\right); \quad \frac{\partial}{\partial s_k(\mathbf{x})} = [\mathbf{x} \cdot \nabla]_k, \quad k = 1, 2, 3;$$

 ∇ is the Hamiltonian operator and the functions ψ_j , j = 1, 2, 3 are represented in the following form

$$\psi_{1}(\mathbf{x}) = \frac{\rho}{R} f_{0}(\theta, \eta) + \frac{a-1}{2(a+1)} \sum_{n=1}^{\infty} \left\{ \left[\frac{(n+b)(n+1)}{n+\alpha} \left(\frac{\rho}{R} \right)^{n+1} - \frac{(n+c)n}{n+\alpha} \left(\frac{\rho}{R} \right)^{n-1} \right] f_{n}(\theta, \eta) + \frac{n+b}{n+\alpha} \left[\left(\frac{\rho}{R} \right)^{n+1} - \left(\frac{\rho}{R} \right)^{n-1} \right] F_{n}(\theta, \eta) \right\},$$

$$\psi_{2}(\mathbf{x}) = \frac{a-1}{2(a+1)} \sum_{n=1}^{\infty} \left\{ \left[\frac{(n+c)}{(n+1)(n+\alpha)} \left(\frac{\rho}{R} \right)^{n+1} - \left(\frac{\rho}{R} \right)^{n-1} \right] f_{n}(\theta, \eta) \right\},$$

$$(19)$$

$$- \frac{(n+b)}{n(n+\alpha)} \left(\frac{\rho}{R} \right)^{n-1} \right] F_{n}(\theta, \eta) + \frac{n+c}{n+\alpha} \left[\left(\frac{\rho}{R} \right)^{n+1} - \left(\frac{\rho}{R} \right)^{n-1} \right] f_{n}(\theta, \eta) \right\},$$

$$\psi_{3}(\mathbf{x}) = - \sum_{n=1}^{\infty} \frac{1}{n(n+1)} \left(\frac{\rho}{R} \right)^{n} \Phi_{n}(\theta, \eta).$$

Here

$$a = \frac{\mu}{\lambda + 2\mu}, \quad \alpha = \frac{a}{a+1} < 1, \quad b = \frac{2a}{a-1}, \quad c = \frac{a-3}{a-1},$$

$$\begin{split} f_n &= \frac{2n+1}{4\pi R^2} \int\limits_S P_n(\cos\gamma) f(\mathbf{y}) d_y S, \quad F_n = \frac{2n+1}{4\pi R^2} \int\limits_S P_n(\cos\gamma) F(\mathbf{y}) d_y S, \\ \Phi_n &= \frac{2n+1}{4\pi R^2} \int\limits_S P_n(\cos\gamma) \Phi(\mathbf{y}) d_y S. \end{split}$$

The functions f, F, and Φ are given by the formulas

$$f(\mathbf{z}) = \frac{1}{R} \sum_{k=1}^{3} z_k \omega_k(\mathbf{z}), \quad F(\mathbf{z}) = \sum_{k=1}^{3} \left[\frac{\partial}{\partial s_k(\mathbf{x})} \frac{[\mathbf{x} \cdot \boldsymbol{\omega}(\mathbf{x})]_k}{\rho} \right]_{\rho=R},$$
$$\Phi(\mathbf{z}) = \sum_{k=1}^{3} \left[\frac{\partial \omega_k(\mathbf{x})}{\partial s_k} \right]_{\rho=R}, \quad \mathbf{z} \in S.$$

Note that $F_0 = 0$, $\Phi_0 = 0$.

Thus, the solutions of the Problem 1 for the sphere is represented by formulas (5),(7),(14),(15),(9),(18),(19).

For absolutely and uniformly convergence of obtained series together with their first derivatives it is sufficient to assume that

$$\omega(\mathbf{z}) \in C^5(S), \quad h(\mathbf{z}) \in C^5(S), \quad h_1(\mathbf{z}) \in C^5(S).$$

Solutions obtained under such conditions are regular in D.

3.4. Problem A_2 .

For a ball the solution of equation (8), with boundary condition (13) was constructed in [29,30] and it is represented as (18), where

$$\begin{split} \psi_{1}(\mathbf{x}) &= \frac{l(x)}{\rho} + \frac{f_{0}}{3\mu + 2\mu} + c_{1} \frac{\rho^{2} - R^{2}}{R} f_{1}(\theta, \eta) \\ &+ \sum_{n=2}^{\infty} \frac{1}{2\Delta_{n}} \left(\frac{\rho}{R}\right)^{n-1} \left\{ \left[A_{1n} \left(\frac{\rho}{R}\right)^{2} + A_{2n} \right] R[A_{3n}f_{n}(\theta, \eta) + A_{4n}F_{n}(\theta, \eta)] \right. \\ &+ \frac{\rho^{2} - R^{2}}{R} A_{5n}(A_{6n}F_{n}(\theta, \eta) + n(n+1)A_{4n}f_{n}(\theta, \eta)) \right\}, \\ \psi_{2}(\mathbf{x}) &= \frac{l(x)}{\rho} - \frac{R}{c_{2}} \left[(2-a) \left(\frac{\rho}{R}\right)^{2} + 3a - 1 \right] f_{1}(\theta, \eta) \end{split}$$
(20)
$$&- \sum_{n=2}^{\infty} \frac{1}{2n(n+1)\Delta_{n}} \left(\frac{\rho}{R}\right)^{n-1} \left\{ (n+1)A_{2n} \frac{\rho^{2} - R^{2}}{R} [A_{3n}f_{n}(\theta, \eta) + A_{4n}F_{n}(\theta, \eta)] \right. \\ &+ R \left[A_{2n} \left(\frac{\rho}{R}\right)^{2} + (n+1)A_{5n} \right] [A_{6n}F_{n}(\theta, \eta) + n(n+1)A_{4n}f_{n}(\theta, \eta)] \right\}, \\ \psi_{3}(\mathbf{x}) &= q(x) - \frac{R}{\mu} \sum_{n=2}^{\infty} \frac{1}{n(n^{2} - 1)} \left(\frac{\rho}{R}\right)^{n} \Phi_{n}(\theta, \eta). \end{split}$$

Here

$$\begin{split} f_1 &= F_1, \quad A_{1n} = [(a-1)n+2a](n+1), \quad A_{2n} = [(1-a)n+3-a]n, \\ A_{3n} &= 2n^2 + (1-2a)n-2a, \quad A_{4n} = 2an+2a-3, \quad A_{5n} = (a-1)n+2a, \\ A_{6n} &= 2n^2 + (1-4a)n+3-4a, c_1 = (3a-1)c_2^{-1}, \quad c_2 = 2\mu(3-4a), \\ \Delta_n &= 2\mu(n-1)[2(1-a^2)n^3+4(1-2a^2)n^2+(3+3a-10a^2)n+a(3-4a)], \\ l &= (\mathbf{x}\cdot\mathbf{b}), \quad q = (\mathbf{x}\cdot\mathbf{q}), \quad \Delta_n \neq 0, \quad n = 2, 3, \ldots; \end{split}$$

 $\mathbf{q}(q_1,q_2,q_3)$ and $\mathbf{b}(b_1,b_2,b_3)$ are arbitrary constant vectors,

$$f_n = \frac{2n+1}{4\pi R^2} \int_S P_n(\cos\gamma) f(\mathbf{y}) d_y S, \quad F_n = \frac{2n+1}{4\pi R^2} \int_S P_n(\cos\gamma) F(\mathbf{y}) d_y S,$$
$$\Phi_n = \frac{2n+1}{4\pi R^2} \int_S P_n(\cos\gamma) \Phi(\mathbf{y}) d_y S.$$

The functions f, F, and Φ are given in the form

$$\begin{split} f(\mathbf{z}) &= \frac{1}{R} \sum_{k=1}^{3} z_k \Omega_k(\mathbf{z}), \quad F(\mathbf{z}) = \sum_{k=1}^{3} \left[\frac{\partial}{\partial s_k(\mathbf{x})} \frac{[\mathbf{x} \cdot \mathbf{\Omega}(\mathbf{x})]_{\mathbf{k}}}{\rho} \right]_{\rho=R}, \\ \Phi(\mathbf{z}) &= \sum_{k=1}^{3} \left[\frac{\partial \Omega_k(\mathbf{x})}{\partial s_k(\mathbf{x})} \right]_{\rho=R}, \quad \mathbf{z} \in S. \end{split}$$

For determining the stress vector we obtain

$$\mathbf{T}(\partial \mathbf{x}, \mathbf{n})\mathbf{v}(\mathbf{x}) = 2\mu \frac{\partial \mathbf{v}(\mathbf{x})}{\partial n} + \lambda \mathbf{n} div \mathbf{v}(\mathbf{x}) + \mu [\mathbf{n} \times rot \mathbf{v}(\mathbf{x})],$$

where the vector \mathbf{v} is determined by (18).

Thus, the solution of Problem A_2 for the sphere is represented by formulas (5),(7), (16), (17),(9),(18),(20).

For absolutely and uniformly convergence of series in (20), together with their first derivatives, it is sufficient to assume that $\Omega \in C^5(S)$, $|\Omega| \leq \frac{1}{n^4}$. Solutions of Problem A_2 obtained under such conditions are regular in D. For the solution to exist it is necessary that the conditions $F_0 = \Phi_0 = \Phi_1 = 0$, $f_1 = F_1$ be fulfilled.

Note that Problem 2 is solvable if the principal vector and the principal moment of external stresses are equal to zero

$$\int_{S} \mathbf{\Omega}(\mathbf{y}) dS = 0, \quad \int_{S} [\mathbf{y} \times \mathbf{\Omega}(\mathbf{y})] dS = 0.$$

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