MAIN ARTICLES

THE NEUMANN PROBLEM FOR A DEGENERATE DIFFERENTIAL-OPERATOR EQUATION

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Abstract. We consider the Neumann problem for a degenerate differential– operator equation of higher order. We establish some embedding theorems in weighted Sobolev space W^m_{α} and show existence and uniqueness of the generalized solution of the Neumann problem. We also give a description of the domain of definition and of the spectrum for the corresponding operator.

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1. Introduction

sponding operator $\mathbb{P} = t^{-\alpha} P$.

In present paper we consider the Neumann problem for the operator equation

$$Pu \equiv (-1)^m D_t^m (t^\alpha D_t^m) u + t^\alpha A u = f, \tag{1}$$

where $t \in (0, b)$, $\alpha \geq 0$, $D_t \equiv d/dt$, $f \in L_{2,-\alpha}((0, b), H)$ and A is a linear operator in Hilbert space H and has a complete system $\{\varphi_k\}_{k=1}^{\infty}$ of the eigenfunctions, which form a Riesz's basis in H. Note that the operator A in general is an unbounded operator in H.

Our approach, similar to that used in [3], for the case m = 1 and in [11] for m = 2, is based on the consideration of the one-dimensional equation (1), i.e. when A is the operator of multiplication by a number $a, a \in \mathbb{C}$, Au = au(see [4]).

In Section 2 we define the weighted Sobolev space W^m_{α} , describe the behavior of the functions from this space close to t = 0 (see [7], [8], [13]). We give the description of the domain of the definition D(B) of the operator B and prove that for $1 - a \notin \sigma \mathbb{B}$ ($\sigma \mathbb{B}$ is the spectrum of the operator \mathbb{B}) the generalized solution of the Neumann problem for the one-dimensional equation (1) exists and is unique for every $f \in L_{2,-\alpha}$.

In Section 3 under some conditions on the spectrum of the operator A we prove unique solvability of the operator equation (1) for every $f \in L_{2,-\alpha}((0,b), H)$ and give the description of the spectrum for the corre-

2. The One-dimensional Case

2.1. The space W^m_{α}

Denote by W^m_{α} the completion of $C^m[0,b]$ in the norm

$$||u||_{W^m_{\alpha}}^2 = \int_0^b \left(t^{\alpha} \, |u^{(m)}(t)|^2 + t^{\alpha} |u(t)|^2 \right) \, dt. \tag{2}$$

For the proofs of the Propositions 1, 2 and Remark 3 see [2] and [13].

Proposition 1 For every $u \in W^m_{\alpha}$ close to t = 0 we have

$$|u^{(j)}(t)|^2 \le (B_j + C_j t^{2m-2j-1-\alpha}) ||u||^2_{W^m_\alpha}, \tag{3}$$

where $\alpha \neq 1, 3, \dots, 2m - 1$, $j = 0, 1, \dots, m - 1$. For $\alpha = 2n + 1$, $n = 0, 1, \dots, m - 1$ in (3) the factor $t^{2m-2j-1-\alpha}$ is to be replaced by $t^{2m-2j-2n-2} |\ln t|$, $j = 0, 1, \dots, m - n - 1$.

From Proposition 1 it follows that in the case $\alpha < 1$ (weak degeneracy) $u^{(j)}(0)$ exist for all $j = 0, 1, \ldots, m-1$, while for $\alpha \ge 1$ (strong degeneracy) not all $u^{(j)}(0)$ exist. More precisely, for $1 \le \alpha < 2m-1$ the derivatives at zero $u^{(j)}(0)$ exist only for $j = 0, 1, \ldots, s_{\alpha}$, where $s_{\alpha} = m-1-\left[\frac{\alpha+1}{2}\right]$ (here [a] is the integer part of a number a) and for $\alpha \ge 2m-1$ all $u^{(j)}(0)$, $j = 0, 1, \ldots, m-1$, in general may be infinite.

Proposition 2 The embedding

$$W^m_\alpha \subset L_{2,\alpha} \tag{4}$$

is compact for every $\alpha \geq 0$.

Remark 3 The embedding

$$W^m_{\alpha} \subset L_{2,\beta} \tag{5}$$

is compact for every $\alpha > 2m - 1$ and $\beta > \alpha - 2m$.

Observe that in the case $\beta = \alpha - 2m$ and $\alpha \leq 2m - 1$ the embedding (5) fails (see [8]). For $\alpha \leq 2m - 1$ we only have the embedding $W_{\alpha}^m \subset L_{2,\gamma}, \gamma > -1$. However, for $\alpha > 2m - 1$ we have the embedding $W_{\alpha}^m \subset L_{2,\alpha-2m}$, which can be proved by using of the Hardy inequality (see [6] and [8]) and this embedding is not compact. Indeed, it is easy to verify, that for the bounded in W_{α}^m sequence $u_n(t) = n^{-\frac{1}{2}} t^{\frac{2m-\alpha-1}{2}} (\ln t)^{-\frac{1}{2}-\frac{1}{2n}} \varphi(t)$, where $\varphi \in C^m[0,b], \ \varphi(t) = 1$ for $t \in [0, \frac{\varepsilon}{2}], 0 < \varepsilon < \min\{1,b\}$ and $\varphi(t) = 0$ for $t \in [\varepsilon, b]$ doesn't exist the convergent in $L_{2,\alpha-2m}$ subsequence (see [5], [12]).

2.2 One-dimensional Equation

Now we consider the Neumann problem for the special case a = 1 of the one-dimensional equation (1)

$$Bu \equiv (-1)^m (t^{\alpha} u^{(m)})^{(m)} + t^{\alpha} u = f, \quad f \in L_{2,-\alpha}.$$
 (6)

Definition 4 A function $u \in W^m_{\alpha}$ is called a generalized solution of the Neumann problem for the equation (6) if for every $v \in W^m_{\alpha}$ we have

$$(t^{\alpha}u^{(m)}, v^{(m)}) + (t^{\alpha}u, v) = (f, v),$$
(7)

where (\cdot, \cdot) is the scalar product in $L_2(0, b)$.

Proposition 5 The generalized solution of the Neumann problem for the equation (6) exists and is unique for every $f \in L_{2,-\alpha}$.

The uniqueness of the generalized solution immediately follows from Definition 4. To prove the existence we note that the linear functional $l_f(v) = (f, v)$ is continuous in W^m_{α} because

$$|l_f(v)| \le ||f||_{L_{2,-\alpha}} ||v||_{L_{2,\alpha}} \le ||f||_{L_{2,-\alpha}} ||v||_{W_{\alpha}^m}$$

and use Riesz's lemma on the representation of continuous functionals.

If the generalized solution is classical then from (7) after integration by parts we get

$$(-1)^{m}((t^{\alpha}u^{(m)})^{(m)},v) + \sum_{j=0}^{m-1} (-1)^{j} ((t^{\alpha}u^{(m)}(t))^{(j)}\overline{v}^{(m-j-1)}(t))\Big|_{0}^{b} + (t^{\alpha}u,v) = (f,v).$$

Since the function $v \in W^m_{\alpha}$ is arbitrarily we conclude that the function u(t) fulfills the following conditions (see [10])

$$\left(t^{\alpha}u^{(m)}(t)\right)^{(j)}\Big|_{t=0} = u^{(m+j)}(t)\Big|_{t=b} = 0, \quad j = 0, 1, \dots, m-1.$$
(8)

For $\alpha = 0$ the conditions (8) are usual Neumann conditions, which are of Sturm type and, therefore, regular (see [9]).

Definition 6 We say that $u \in W^m_{\alpha}$ belongs to D(B), if the equality (7) is satisfied for some $f \in L_{2,-\alpha}$. In this case we will write Bu = f.

According to Definition 6 we have an operator

$$B: D(B) \subset W^m_{\alpha} \subset L_{2,\alpha} \to L_{2,-\alpha}.$$

If $u \in W^m_{\alpha}$ we know that $u^{(j)}(0), j = 0, 1, \dots, m-1$ exist only for $\alpha < 2m - 2j - 1$ (see Proposition 1). But for the generalized solution of the equation (7) we can improve it and give the following description of $u \in D(B)$.

Proposition 7 The domain of definition of the operator B consists of the functions $u \in W^m_{\alpha}$ for which $u^{(j)}(0)$ are finite for $0 \leq \alpha < 2m - 2j$ and $2m - 1 \leq \alpha < 4m - 2j - 1$. The value u(0) is finite for $0 \leq \alpha < 2m + 1$. The values $u^{(j)}(0)$ cannot be specified arbitrarily, but are determined by the right-hand side of (7).

Proof. To describe the domain of definitions D(B) of the operator B first note, that $t^{\alpha}u \in L_{2,-\alpha}$ since $u \in L_{2,\alpha}$. Hence it is enough to study the behaviour of the solutions for the equation $(-1)^m (t^{\alpha}u^{(m)})^{(m)} = f, f \in L_{2,-\alpha}$ near to the point t = 0. Let $\alpha \ge 2m - 1$. For the solution u(t) of this equation we have

$$u^{(m)}(t) = t^{-\alpha} P_{m-1}(t) + \frac{(-1)^m t^{-\alpha}}{(m-1)!} \int_0^t (t-\tau)^{m-1} f(\tau) \, d\tau, \tag{9}$$

where $P_{m-1}(t) = a_0 + a_1 t + \cdots + a_{m-1} t^{m-1}$ is the polynomial of the degree m-1. Since $u \in W^m_{\alpha}$ we have that $P_{m-1}(t) = 0$. Hence we can write

$$|u^{(m)}(t)| = \left|\frac{(-1)^m t^{-\alpha}}{(m-1)!} \int_0^t (t-\tau)^{m-1} \tau^{\frac{\alpha}{2}} \tau^{-\frac{\alpha}{2}} f(\tau) \, d\tau\right| \le c ||f||_{L_{2,-\alpha}} t^{\frac{2m-1-\alpha}{2}},$$

therefore, integrating $u^{(m)}(t)$ (m-j)-times, $j = 0, 1, \ldots, m-1$, we get for some polynomial Q_{m-j-1} of the degree m-j-1

$$|u^{(j)}(t)| = \left| Q_{m-j-1}(t) + \frac{1}{(m-j-1)!} \int_0^t (t-\tau)^{m-j-1} u^{(m)}(t) \, d\tau \right| \le \le c_j + d_j ||f||_{L_{2,-\alpha}} t^{\frac{2m-1-\alpha}{2} + m-j} = c_j + d_j ||f||_{L_{2,-\alpha}} t^{\frac{4m-2j-1-\alpha}{2}}.$$

Let now $2m-2j-1 \leq \alpha < 2m-2j+1, j = 1, 2, \ldots, m-1$. Then in the equality (9) $a_0 = a_1 = \ldots = a_{m-j-1} = 0$ since $u \in W^m_{\alpha}$. The second term in (9) we have already estimated and it exists for $\alpha < 2m - 1$. Now it is enough to estimate only first term after integrating $u^{(m)}(t) \quad (m-j)$ -times. The main term after integration remains $c_{m-j}t^{2m-2j-\alpha}$, therefore for the existence of $u^{(j)}(0)$ we get the condition $2m-2j-\alpha > 0$, i.e., $\alpha < 2m-2j$. Note that for other values of α the existence of the values $u^{(j)}(0)$ is proved in Proposition 1 (see [13]). Note also that the conditions in Proposition 7 are exact, i.e., if we take for example $\alpha = 2m - 2j$, then the statement is false, the value $u^{(j)}(0)$ in general doesn't exist. \Box

To get an operator in the same space we set $g(t) = t^{-\alpha}f(t)$. It is evident that g(t) belongs to $L_{2,\alpha}$ and $||f||_{L_{2,-\alpha}} = ||g||_{L_{2,\alpha}}$. Therefore, we get an operator $\mathbb{B} \equiv t^{-\alpha}B : D(\mathbb{B}) = D(B) \subset W^m_{\alpha} \subset L_{2,\alpha} \to L_{2,\alpha}$ with $\mathbb{B}u = g$.

Proposition 8 The operator $\mathbb{B}: L_{2,\alpha} \to L_{2,\alpha}$ is positive and selfadjoint. Moreover, the inverse operator $\mathbb{B}^{-1}: L_{2,\alpha} \to L_{2,\alpha}$ is compact.

Proof. The self-adjointness of the symmetric operator \mathbb{B} (symmetry and positivity of the operator \mathbb{B} follow from the Definition 6) is a consequence of

the existence of the generalized solution for every $f \in L_{2,-\alpha}$ (see [4]). Now using (2) and the equality (7) with v = u we get

$$|u||_{W_{\alpha}^{m}}^{2} = (f, u) \leq ||f||_{L_{2,-\alpha}} ||u||_{L_{2,\alpha}} \leq ||g||_{L_{2,\alpha}} ||u||_{W_{\alpha}^{m}},$$

and, therefore, we have

$$||u||_{L_{2,\alpha}} \le ||\mathbb{B}u||_{L_{2,\alpha}}.$$
 (10)

The compactness of the operator \mathbb{B}^{-1} : $L_{2,\alpha} \to L_{2,\alpha}$ now follows from the inequality (10) and Proposition 2. \Box

Corollary 9 The operator \mathbb{B} has a discrete spectrum, and the system of the corresponding eigenfunctions is dense in $L_{2,\alpha}$.

This follows from the connection of the spectra of the operators \mathbb{B} and \mathbb{B}^{-1} and from the properties of compact selfadjoint operators (see [4]).

Note that if λ is an eigenvalue and u(t) a corresponding eigenfunction of the operator \mathbb{B} then we have

$$(-1)^{m} (t^{\alpha} u^{(m)})^{(m)} + t^{\alpha} u = \lambda t^{\alpha} u.$$
(11)

It follows then from the inequality (10) and Definition 6 that $\lambda \geq 1$. Note that the number $\lambda = 1$ is an eigenvalue for the operator \mathbb{B} with the multiplicity msince every polynomial of order m - 1 is an eigenfunction. Therefore, for the solvability of the equation

$$(-1)^m (t^{\alpha} u^{(m)})^{(m)} = f, \quad f \in L_{2,-\alpha},$$
(12)

we get the following result:

Proposition 10 The generalized solution of the Neumann problem for the equation (12) exists if and only if $(f, P_{m-1}(t)) = 0$ for any polynomial $P_{m-1}(t)$ of order m - 1.

Here we have used both $(g, P_{m-1}(t))_{\alpha} = (f, P_{m-1}(t))$ since $t^{\alpha}g(t) = f(t)$ ($(\cdot, \cdot)_{\alpha}$ is the scalar product in $L_{2,\alpha}$) and the definition of the operator \mathbb{B} . Note that the generalized solution of the Neumann problem for the equation (12) is unique up to an arbitrary additive polynomial of order m-1.

Now we can consider the general case of the one-dimensional equation (1)

$$Pu \equiv (-1)^m (t^{\alpha} u^{(m)})^{(m)} + at^{\alpha} u = f, \quad f \in L_{2,-\alpha},$$
(13)

because the number 1 - a can be regarded as a spectral parameter for the operator \mathbb{B} . Therefore, we can state that if $1 - a \notin \sigma \mathbb{B}$ then the equation (13) is uniquely solvable for every $f \in L_{2,-\alpha}$.

3. The Operator Equation

In this section we consider the operator version of the equation (1)

$$Pu \equiv (-1)^m D_t^m (t^{\alpha} D_t^m) u + t^{\alpha} A u = f, \quad f \in L_{2,-\alpha}((0,b), H), \quad \alpha \ge 0.$$
(14)

Suppose that the operator $A: H \to H$ has a complete system of eigenfunctions $\{\varphi_k\}_{k=1}^{\infty}, A\varphi_k = a_k\varphi_k, k \in \mathbb{N}$, forming a Riesz's basis in H (see [4]), i.e., for every $x \in H$ we have $x = \sum_{k=1}^{\infty} x_k\varphi_k$, and there are some positive constants c_1 and c_2 such that

$$c_1 \sum_{k=1}^{\infty} |x_k|^2 \le ||x||^2 \le c_2 \sum_{k=1}^{\infty} |x_k|^2.$$
(15)

Hence for every $u \in L_{2,\alpha}((0,b), H), f \in L_{2,-\alpha}((0,b), H)$ we have

$$u = \sum_{k=1}^{\infty} u_k(t)\varphi_k, \quad f = \sum_{k=1}^{\infty} f_k(t)\varphi_k, \quad k \in \mathbb{N}.$$
 (16)

Therefore, the operator equation (14) can be decomposed into an infinite chain of ordinary differential equations

$$P_k u_k \equiv (-1)^m (t^{\alpha} u_k^{(m)})^{(m)} + a_k t^{\alpha} u_k = f_k, \quad f_k \in L_{2,-\alpha}, \quad k \in \mathbb{N}.$$
(17)

For the equations (17) we can define the generalized solutions $u_k(t), k \in \mathbb{N}$, of the Neumann problem (see Section 2).

Definition 11 A function $u \in L_{2,\alpha}((0,b), H)$ is called a generalized solution of the Neumann problem for the equation (14) if the functions $u_k(t), k \in \mathbb{N}$, in the representation (16) are generalized solutions of the Neumann problem for the equations (17).

Proposition 12 The operator equation (14) is uniquely solvable for every $f \in L_{2,-\alpha}((0,b),H)$ if and only if the equations (17) are uniquely solvable for every $f_k \in L_{2,-\alpha}$, $k \in \mathbb{N}$, and the inequalities

$$||u_k||_{L_{2,\alpha}} \le c||f_k||_{L_{2,-\alpha}} \tag{18}$$

are satisfied uniformly with respect to $k \in \mathbb{N}$.

For the proof of Proposition 12 see [4].

Let the numbers $\lambda_1 = 1 < \lambda_2 < \cdots < \lambda_k < \cdots, \lambda_k \to +\infty$ when $k \to \infty$, are the eigenvalues of the operator \mathbb{B} (see Section 2). Suppose that

$$\rho(1 - a_k, \lambda_m) > \varepsilon, \quad k, m \in \mathbb{N},\tag{19}$$

where $\varepsilon > 0$ and ρ is the distance in the complex plane.

Theorem 13 Under the condition (19) the generalized solution of the Neumann problem for the operator equation (14) exists and is unique for every $f \in L_{2,-\alpha}((0,b), H)$.

First note that under the condition (19) the equations (17) are uniquely solvable for every $f_k \in L_{2,-\alpha}, k \in \mathbb{N}$ and the inequalities (18) are satisfied. Now the proof of Theorem 13 follows from Proposition 12.

Let $g = t^{-\alpha} f$, $f \in L_{2,-\alpha}((0,b), H)$. Then $g \in L_{2,\alpha}((0,b), H)$ and we define an operator

$$\mathbb{P} \equiv t^{-\alpha}P : D(\mathbb{P}) = D(P) \subset L_{2,\alpha}((0,b),H) \to L_{2,\alpha}((0,b),H),$$

with $\mathbb{P}u = g$ in $L_{2,\alpha}((0,b), H)$. It follows from the condition (19) that for the generalized solution of the Neumann problem we have

$$||u||_{L_{2,\alpha}((0,b),H)} \le c||g||_{L_{2,\alpha}((0,b),H)}.$$
(20)

The operator $\mathbb{P}^{-1}: L_{2,\alpha}((0,b), H) \to L_{2,\alpha}((0,b), H)$ in general is not compact in contrast to Proposition 8 (it will be compact only in the case when the space H is finite-dimensional). If the operator $A: H \to H$ is selfadjoint we can describe the spectrum of the operator \mathbb{P} .

Proposition 14 The spectrum of the operator \mathbb{P} is equal to the closure of the direct sum of the spectra $\sigma \mathbb{B}$ and $\sigma(A - I)$, i.e.,

$$\sigma \mathbb{P} = \overline{\sigma \mathbb{B} + \sigma(A - I)} \equiv \overline{\{\lambda_1 + \lambda_2 - 1 : \lambda_1 \in \sigma \mathbb{B}, \, \lambda_2 \in \sigma A\}}.$$

The proof of Proposition 14 immediately follows from the equality

$$\mathbb{P} = \mathbb{B} \otimes I_H + I_{L_{2,\alpha}} \otimes (A - I)$$

(here \otimes means the tensor product of the operators). Note that here we use the assertion, that if $\lambda \in \sigma T$ for the selfadjoint operator T in some separable Hilbert space $T : X \to X$, then there is some sequence $x_n \in D(T), n \in$ $\mathbb{N}, ||x_n|| = 1$ such that $(T - \lambda)x_n \to 0, n \to \infty$ (see [1], [14]).

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