

## CLOSED CONVEX SHELLS

Meunargia T.

**Abstract.** If  $\Omega$  is a closed convex shell, then  $S : x_3 = 0$  is an ovaloid. It is proved that in this case the equation of equilibrium may have only the unique regular solution and hence, the corresponding homogenous equation has no non-zero solution on  $S$ .

**Keywords and phrases:** Closed shells, stress and strain tensors.

**AMS subject classification (2010):** 74B20.

Mixed forms of stress-strain relations are given in the form

$$\sigma_j^i = \lambda\theta g_j^i + 2\mu e_j^i \quad (i = j = 1, 2, 3) \quad (1)$$

where  $\sigma_j^i$  and  $e_j^i$  are the mixed components, respectively, of stress and strain tensors,  $\theta$  is the cubical dilatation which will be written as

$$\theta = e_i^i = \theta' + e_3^3, \quad \theta' = e_\alpha^\alpha, \quad (\alpha = 1, 2) \quad (2)$$

when  $j = 3$  from (1) we have

$$\sigma_3^\alpha = 2\mu e_3^\alpha, \quad \sigma_3^3 = \lambda\theta + 2\mu e_3^3 = \lambda\theta' + (\lambda + 2\mu)e_3^3. \quad (3)$$

from (3)

$$e_3^\alpha = \frac{1}{2\mu}\sigma_3^\alpha, \quad e_3^3 = -\frac{\lambda}{\lambda + 2\mu}\theta' + \frac{1}{\lambda + 2\mu}\sigma_3^3. \quad (4)$$

By inserting (4) into (2) we obtain

$$\theta = \frac{\lambda'}{\lambda}\theta' + \frac{\lambda}{\lambda + 2\mu}\sigma_3^3, \quad (5)$$

where  $\lambda' = \frac{2\lambda\mu}{\lambda + 2\mu}$ .

Substituting expression (5) into (1) we get

$$\sigma_j^i = T_j^i + Q_j^i = \left( \lambda'\theta' + \frac{\lambda}{\lambda + 2\mu}\sigma_3^3 \right) g_j^i + 2\mu e_j^i$$

where

$$T_\beta^\alpha = \lambda'\theta' g_\beta^\alpha + 2\mu e_\beta^\alpha, \quad Q_\beta^\alpha = \sigma' \sigma_3^3 g_\beta^\alpha, \quad T_3^i = 0, \quad Q_3^i = \sigma_3^i,$$

and  $\sigma' = \frac{\lambda}{\lambda + 2\mu}$ .

The vector  $\mathbf{T}^\alpha$  satisfies the condition  $\mathbf{nT}^\alpha = 0$  and is therefore called the tangential stress field and the vector  $\mathbf{Q}^i$  will be called the transverse stress field.

The vectorial equation of equilibrium has the form

$$\frac{1}{\sqrt{g}}\partial_i(\sqrt{g}\sigma^i) + \Phi = 0,$$

$$(\sqrt{g} = \sqrt{a}\vartheta, \quad \vartheta = 1 - 2Hx_3 + Kx_3^2)$$

where  $H$  and  $K$  are respectively, middle and principal curvatures of the surface  $S$ , may be written as

$$\frac{1}{\sqrt{g}}[\partial_\alpha\sqrt{g}\mathbf{T}^\alpha] + \partial_i(\sqrt{g}\mathbf{Q}^i) + \Phi = 0 \quad (6)$$

Let the surface  $\hat{S} : x^3 = \text{const}$  be the neutral surface of a non-shallow shell. Then  $\mathbf{T}^\alpha = 0$ , i.e.  $T^{\alpha\beta} = 0$  (on  $\hat{S}$ ), and equation (6) becomes

$$\frac{1}{\sqrt{g}}\partial_\alpha(\sqrt{a}\vartheta\mathbf{Q}^\alpha) + \partial_3(\vartheta\sigma^3) + \vartheta\Phi = 0,$$

or

$$[\nabla_\alpha(\vartheta\mathbf{Q}^\alpha) + \partial_3(\vartheta\sigma^3) + \vartheta\Phi]_{x^3=c} = 0; \quad (-h \leq x^3 = x_3 \leq h)$$

where  $2h$  is the thickness of shell and

$$\mathbf{Q}^\alpha = \sigma' \sigma_3^3 \mathbf{r}^\alpha + \sigma_3^\alpha \mathbf{n}, \quad \nabla_\alpha(\cdot) = \frac{1}{\sqrt{a}}\partial_\alpha(\sqrt{a}(\cdot)).$$

Denoting the stress forces acting on the face surfaces  $S^+$  and  $S^-$  by  $\mathbf{P}^{(+)}$  and  $\mathbf{P}^{(-)}$  we have

$$\mathbf{P}^{(+)} = -(\sigma^3)_{x^3=h}, \quad \mathbf{P}^{(-)} = (\sigma^3)_{x^3=-h}, \quad (7)$$

If we approximately represent  $\sigma^3$  by the formula

$$\sigma^3(x^1, x^2, x^3) \cong \sigma^{(0)}(x^1, x^2) + x^3 \sigma^{(1)}(x^1, x^2).$$

From (7) we get

$$\begin{aligned} \sigma^3(x^1, x^2, x^3) &\cong -\frac{1}{2} \left[ \mathbf{P}^{(+)} - \mathbf{P}^{(-)} + \frac{x^3}{h} (\mathbf{P}^{(+)} + \mathbf{P}^{(-)}) \right] \\ &= -\frac{1}{2} \left[ \frac{h+x^3}{h} (\mathbf{P}^{(+)} - \mathbf{P}^{(-)}) + \frac{2x^3}{h} \mathbf{P}^{(-)} \right] \end{aligned}$$

or

$$\begin{aligned} \sigma^3(x^1, x^2, x^3) &= -\frac{1}{2} \left[ \frac{h+x^3}{h} (p^\alpha \mathbf{r}_\alpha + p^3 \mathbf{n}) + \frac{2x^3}{h} \mathbf{P}^{(-)} \right], \\ p^\alpha &= P^{\alpha(+)} - P^{\alpha(-)}, \quad p = P^3(+)-P^3(-). \end{aligned}$$

Then to define the vector field  $\mathbf{P}^{(+)}$  we have the equation

$$\{\nabla_\alpha(\sigma' A_\beta^\alpha p \mathbf{r}^\beta + A p^\alpha \mathbf{n}) + B(p \mathbf{n} + p^\alpha \mathbf{r}_\alpha) + \tilde{\Phi}\}_{x^3=c} = 0 \quad (8)$$

where

$$A_\beta^\alpha = \frac{h+c}{h}[a_\beta^\alpha + c(b_\beta^\alpha - 2H a_\beta^\alpha)], \quad A = \frac{h+c}{h}\vartheta(c)$$

$$B = \frac{1}{h}[1 - 2Hh + 2(Kh - 2H)c + 3kc^2],$$

$$\begin{aligned} \tilde{\Phi} = & -2\vartheta(c)\Phi(c) + \nabla_\alpha\{\sigma'\frac{2c}{h}[a_\beta^\alpha + c(b_\beta^\alpha - 2H a_\beta^\alpha)]p^3\mathbf{r}^\beta + \frac{2c}{h}\vartheta(c)p^\alpha\mathbf{n}\} \\ & + \frac{2}{h}[\vartheta(c) + 2(kc - h)]\mathbf{p}^{(-)}. \end{aligned}$$

From (8) we have

$$\sigma'\nabla_\alpha(A_\beta^\alpha p) + (B a_{\alpha\beta} - A b_{\alpha\beta})p^\alpha + \tilde{\Phi}_\beta = 0, \quad \tilde{\Phi}_\beta = \tilde{\phi}\mathbf{r}_\beta, \quad (9)$$

$$\nabla_\alpha(A p^\alpha) + (\sigma' A_\beta^\alpha b_\alpha^\beta + B)p + \tilde{\Phi}_3 = 0, \quad (\tilde{\Phi}_3 = \tilde{\Phi}\mathbf{n}). \quad (10)$$

From the system of equation (9) we have

$$p^\alpha = P^\alpha - P^\alpha = -\tilde{d}^{\alpha\beta}[\nabla_\gamma(A_\beta^\gamma p) + \tilde{\Phi}_\beta], \quad p = P^3 - P^3 \quad (11)$$

where

$$\hat{d}^{\alpha\beta} = \frac{1}{\Delta}[(B - 2AH)a^{\alpha\beta} + Ab^{\alpha\beta}] \quad \hat{F}_\beta = -[\tilde{\Phi}_\beta + \nabla_\alpha(A_\beta^\alpha p)],$$

$$\Delta = B^2 - 2ABH + A^2K.$$

Inserting expressions (11) into (10) we obtain the equation

$$\sigma'\nabla_\alpha[A\tilde{d}^{\alpha\beta}\nabla_\gamma(A_\beta^\gamma p)] - (B + \sigma'A_\beta^\alpha b_\alpha^\beta)p + \Phi = 0. \quad (12)$$

It is easily seen that equation (12) is of the elliptic type.

Thus, if the surface  $x^3 = c$  is neutral then the stresses  $\mathbf{P}^{(+)}$  and  $\mathbf{P}^{(-)}$  applied to the face surfaces, must satisfy the vector equations (9) and (10). This means that the stresses  $\mathbf{P}^{(+)}$  and  $\mathbf{P}^{(-)}$  cannot be prescribed arbitrarily both at the same time. However there are problems when this does not occur. For example, in aircraft or submarine apparatus the force  $\mathbf{P}^{(-)}$  acting on the inner face surface  $S^-$  may be assumed to be prescribed, but the force  $\mathbf{P}^{(+)}$  acting on the external face surface  $S^+$  is not, in general, assigned beforehand. The same situation occurs on dams. One face surface of the dam is free from stresses and the other is under the hydrodynamic load, a variable which is generally difficult to define exactly at any moment of time.

For closed convex shells when  $x^3 = c$  is the middle surface (i.e.  $c = 0 \Rightarrow x^3 = 0$ ) the homogenous equation (12) may be written in the form

$$\nabla_\alpha(d^{\alpha\beta}\nabla_\beta u) - d^2u = 0, \quad (13)$$

where

$$d^{\alpha\beta} = \frac{h[a^{\alpha\beta}(1 - 2hH) + hb^{\alpha\beta}]}{1 - 2Hh + Kh^2 + 4hH(2Hh - 1)},$$

$$d^2 = \frac{1}{\sigma'h}[1 - 2h(1 - \sigma')H] > 0, \quad \left(\sigma' = \frac{\lambda}{\lambda + 2\mu}\right)$$

$$a^{\alpha\beta} = \mathbf{r}^\alpha \mathbf{r}^\beta, \quad \mathbf{r}^\alpha \mathbf{r}_\beta = a_\beta^\alpha = \sigma_\beta^\alpha, \quad 2H = b_1^1 + b_2^2, \quad K = b_1^1 b_2^2 - b_1^2 b_2^1,$$

$$I = a_{\alpha\beta} dx^\alpha dx^\beta, \quad a_{\alpha\beta} = \mathbf{r}_\alpha \mathbf{r}_\beta,$$

$$II = b_{\alpha\beta} dx^\alpha dx^\beta, \quad b_{\alpha\beta} = -\mathbf{n}_\alpha \mathbf{r}_\beta.$$

Let  $u$  be the regular solution (13) on  $S(x^3 = 0)$ , i.e.  $u$  is the continuous function of the point of the surface  $S$  and has continuous partial derivatives with respect to Gaussian coordinates of this surface. We represent the surface  $S$  as  $S = S_1 \cup S_2$ , where  $S_1$  and  $S_2$  are parts of the surface with no common points  $S_1 \cap S_2 = \cap = \emptyset$ . Let  $L$  be the common boundary of  $S_1$  and  $S_2$ . Denote the tangential normal to  $L$  by  $l$  directed to  $S_1$ . Multiplying both sides of equation (13) by  $u$ , we may rewrite it as

$$\nabla_\alpha(ud^{\alpha\beta}\nabla_\beta u) - d^{\alpha\beta}\nabla_\alpha u \nabla_\beta u - d^2u^2 = 0.$$

Integrating this equality with respect to the surfaces  $S_1$  and  $S_2$ , and then applying Green's formula, we have

$$\int_L ul_\alpha d^{\alpha\beta}\nabla_\beta u ds - \iint_{S_1} (d^{\alpha\beta}\nabla_\alpha u \nabla_\beta u + d^2u^2) dS_1 = 0,$$

$$- \int_L ul_\alpha d^{\alpha\beta}\nabla_\beta u ds - \iint_{S_2} (d^{\alpha\beta}\nabla_\alpha u \nabla_\beta u + d^2u^2) dS_2 = 0.$$

By adding these equalities we obtain

$$\iint_s (d^{\alpha\beta}\nabla_\alpha u \nabla_\beta u + d^2u^2) dS = 0. \quad (14)$$

Since  $d^{\alpha\beta}\nabla_\alpha u \nabla_\beta u \geq 0$ ,  $d^2 > 0$  from (14) it follows that  $u = 0$ , which was to be proved.

The problem under consideration is thus reduced to the determination of the globally regular particular solution of the non-homogeneous equation

$$\sigma'\nabla_\alpha(d^{\alpha\beta}\nabla_\beta p) - \frac{1}{h}[1 - 2(1 - \sigma')hH]p + \Phi = 0. \quad (15)$$

It remains to show that if equation (15) has globally regular solution, then the middle surface  $S : x^3 = 0$  of the shell is neutral. To do this we have to show first that the tangential stress field vanishes on  $S$ , i.e. it should be shown that the equation

$$\frac{1}{\sqrt{a}}\partial_\alpha(\sqrt{a}\mathbf{T}^\alpha) \equiv \frac{1}{\sqrt{a}}\partial_\alpha(\sqrt{a}T^{\alpha\beta}\mathbf{r}_\beta) = 0 \quad (16)$$

has no global solution, except trivial  $T_{\alpha\beta} = 0$ . It is evident since, with respect to isometric-conjugate coordinates  $x, y$ , equation (16) is equivalent to the homogeneous generalized Cauchy-Riemann equation

$$\partial_{\bar{z}}w - B\bar{w} = 0, \quad (z = x + iy)$$

where

$$w = \frac{1}{2}aK^{\frac{1}{4}}(T^{11} - T^{22} - 2iT^{12}), \quad T^{11} + T^{22} = 0. \quad (17)$$

The complex stress function  $w$  is continuous on the whole plane  $E$  of the complex variable  $z = x + iy$  and at infinity satisfies the condition

$$w = O(|z|^{-4}).$$

This implies, in view of the generalized Liouville theorem, that  $w = 0$ . then from (17) it follows that  $T^{\alpha\beta} = 0$ , which was to be proved.

**Acknowledgment.** The designated project has been fulfilled by a financial support of Shota Rustaveli National Science Foundation (Grant SRNSF/FR /358/5-109/14).

## R E F E R E N C E S

1. Vekua I. N. Shell Theory: General Methods of Construction, Pitman Advanced Publishing Program. *Boston-London-Melburne*, 1985.

Received 05.09.2017; revised 10.10.2017; accepted 12.11.2017.

Author's address:

T. Meunargia  
 I. Vekua Institute of Applied Mathematics of  
 I. Javakhishvili Tbilisi State University  
 2, University St., Tbilisi 0186  
 Georgia  
 E-mail: tengiz.meunargia@viam.sci.tsu.ge