# Seminar of I. Vekua Institute <br> of Applied Mathematics <br> REPORTS, Vol. 40, 2014 

# EFFECTIVE SOLUTION OF THE BASIC MIXED BOUNDARY VALUE <br> PROBLEM OF STATICS OF THE THEORY OF ELASTIC MIXTURE IN A CIRCULAR DOMAIN 

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#### Abstract

By the method N. Muskhelishvili an explisit solution to the basic mixed boundary value problem for homogeneous equation of statics of the linear theory of elastic mixture for a circular domain is obtained.


Keywords and phrases: Basic mixed boundary value problem, elastic mixture theory, equation of statics, nodal points.

AMS subject classification (2010): 74E35, 74E20, 74G05.

## 1. Introduction

The basic plane boundary value problem and the basic mixed boundary value problem in a simple connected domain for homogeneous equation of statics of the linear theory of elastic mixture, by analogues of general Kolosov-Muskhelishvili representation have been investigated in [3] and [2], respectively.

By the method M. Muskhelishvili an explicit solution of the basic mixed boundary value problem for homogeneous equation of statics of the linear theory of elastic mixture for an half-plane was obtained in [5].

In the present work we studied an analogous problem which in the case of the plane theory of elasticity has been studied by N. Muskhelishvili [4, §123]. To solve the problem we use the formulas due to Kolosov-Muskhelishvili and the method described in $[4,5]$.

## 1. Some auxiliary formulas and operators

The homogeneous equation of static of the linear theory of elastic mixtures in a complex form is of the type [3]

$$
\begin{equation*}
\frac{\partial^{2} U}{\partial z \partial \bar{z}}+K \frac{\partial^{2} \bar{U}}{\partial \bar{z}^{2}}=0 \tag{1.1}
\end{equation*}
$$

where $z=x_{1}+i x_{2}, \frac{\partial}{\partial z}=\frac{1}{2}\left(\frac{\partial}{\partial x_{1}}-i \frac{\partial}{\partial x_{2}}\right), U=\left(u_{1}+i u_{2}, u_{3}+i u_{4}\right)^{T}$,
$u^{\prime}=\left(u_{1}, u_{2}\right)^{T}$ and $u^{\prime \prime}=\left(u_{3}, u_{4}\right)^{T}$ are partial displacements,

$$
\begin{aligned}
& K=-\frac{1}{2} e m^{-1}, \quad e=\left[\begin{array}{cc}
e_{4} & e_{5} \\
e_{5} & e_{6}
\end{array}\right], \quad m^{-1}=\frac{1}{\triangle_{0}}\left[\begin{array}{cc}
m_{3} & -m_{2} \\
-m_{2} & m_{1}
\end{array}\right], \\
& \triangle_{0}=m_{1} m_{3}-m_{2}^{2}, \quad m_{k}=e_{k}+\frac{1}{2} e_{3+k}, \quad e_{1}=a_{2} / d_{2}, \quad e_{2}=-c / d_{2},
\end{aligned}
$$

$$
\begin{gathered}
e_{3}=a_{1} / d_{2}, \quad d_{2}=a_{1} a_{2}-c^{2}, \quad a_{1}=\mu_{1}-\lambda_{5}, \quad a_{2}=\mu_{2}-\lambda_{5}, \quad c=\mu_{3}+\lambda_{5}, \\
e_{1}+e_{4}=b / d_{1}, \quad e_{2}+e_{5}=-c_{0} / d_{1}, \quad e_{3}+e_{6}=a / d_{1}, \quad d_{1}=a b-c_{0}^{2}, \\
a=a_{1}+b_{1}, \quad b=a_{2}+b_{2}, \quad c_{0}=c+d, \quad b_{1}=\mu_{1}+\lambda_{1}+\lambda_{5}-\alpha_{2} \rho_{2} / \rho, \\
b_{2}=\mu_{2}+\lambda_{2}+\lambda_{5}+\alpha_{2} \rho_{1} / \rho, \quad \alpha_{2}=\lambda_{3}-\lambda_{4}, \quad \rho=\rho_{1}+\rho_{2}, \\
d=\mu_{2}+\lambda_{3}-\lambda_{5}-\alpha_{2} \rho_{1} / \rho \equiv \mu_{3}+\lambda_{4}-\lambda_{5}+\alpha_{2} \rho_{2} / \rho .
\end{gathered}
$$

Here $\mu_{1}, \mu_{2}, \mu_{3}, \quad \lambda_{p}, \quad p=\overline{1,5}, \quad$ are elastic modules characterizing mechanical properties of the mixture, $\rho_{1}$ and $\rho_{2}$ are partial densities of the mixture. It will be assumed that the elastic constants $\mu_{1}, \mu_{2}, \mu_{3}, \quad \lambda_{p}, \quad p=\overline{1,5}$, and partial rigid densities $\rho_{1}$ and $\rho_{2}$ satisfy the conditions (inequalities) [1].

In [3] M.O. Basheleishvili obtained the following representations:

$$
\begin{gather*}
U=\binom{u_{1}+i u_{2}}{u_{3}+i u_{4}}=m \varphi(z)+\frac{1}{2} e z \overline{\varphi^{\prime}(z)}+\overline{\psi(z)},  \tag{1.2}\\
T U=\binom{(T u)_{2}-i(T u)_{1}}{(T u)_{4}-i(T u)_{3}}=\frac{\partial}{\partial S(x)}\left[(A-2 E) \varphi(z)+B z \overline{\varphi^{\prime}(z)}+2 \mu \overline{\psi(z)}\right], \tag{1.3}
\end{gather*}
$$

where $\varphi(z)=\left(\varphi_{1}, \varphi_{2}\right)^{T}$ and $\psi(z)=\left(\psi_{1}, \psi_{2}\right)^{T}$ are arbitrary analytic vector-functions,
$A=\left[\begin{array}{ll}A_{1} & A_{2} \\ A_{3} & A_{4}\end{array}\right]=2 \mu m, \quad \mu=\left[\begin{array}{ll}\mu_{1} & \mu_{3} \\ \mu_{3} & \mu_{2}\end{array}\right], \quad B=\mu e, \quad m=\left[\begin{array}{ll}m_{1} & m_{2} \\ m_{2} & m_{3}\end{array}\right], \quad E=\left[\begin{array}{ll}0 & 1 \\ 1 & 0\end{array}\right]$,
$\Delta_{0}=\operatorname{dem}>0, \quad \Delta_{1}=\operatorname{det} \mu>0, \quad \Delta_{2}=\operatorname{det}(A-2 E)>0, \quad A_{1}+A_{3}-2=B_{1}+B_{3}$,

$$
A_{2}+A_{4}-2=B_{2}+B_{4}, \quad \frac{\partial}{\partial S(x)}=-n_{2} \frac{\partial}{\partial x_{1}}+n_{1} \frac{\partial}{\partial x_{2}}, \quad n=\left(n_{1}, n_{2}\right)^{T}
$$

unit vector of the outer normal, $(T u)_{p}, \quad p=\overline{1,4}$ are stress components, $T u=$ $\left((T u)_{1},(T u)_{2},(T u)_{3},(T u)_{4}\right)^{T},[1,6]$.

Now we note that, from $(1,2)$ we have

$$
\begin{equation*}
2 \mu \frac{\partial U}{\partial S(x)}=\frac{\partial}{\partial S(x)}\left[A \varphi(z)+B z \overline{\varphi^{\prime}(z)}+2 \mu \overline{\psi(z)}\right] . \tag{1.4}
\end{equation*}
$$

Formulas $(1,2),(1,3)$ and $(1,4)$ are analogous to the Kolosov-Muskhelishvili's formulas for the linear theory of elastic mixtures.

## 2. Statement of the mixed problem and scheme of its solution

In the present work we study an analogous problem which in the case of the plane theory of elasticity has been studied by N. Muskhelishvili [4, §123]. For the solution of the problem use will be made of the generalized Kolosov-Muskhelishvili's formula and the method developed in $[4,5]$.

Let us assume that an elastic mixture occupies the circular domain $D^{+}=\{z$ : $|z|<1\}$ bounded by the circumference $L=\{z:|z|=1$,$\} and let L_{j}=a_{j} b_{j}, \quad j=$ $\overline{1, n}, \quad\left(a_{j+1} \neq b_{j}, \quad a_{n+1} \equiv a_{1}\right)$, be arcs separately lying on it, note that the points $a_{1}, b_{1}, a_{2}, b_{2}, \ldots, a_{n}, b_{n}$ follow each other in the positive direction on L .

Suppose that $L^{\prime}=\bigcup_{j=1}^{n} L_{j}$ and $L^{\prime \prime}$ is the remaining part of $L$.
Definition 2.1. The vector $u=\left(u^{\prime}, u^{\prime \prime}\right)^{T}=\left(u_{1}, u_{2}, u_{3}, u_{4}\right)^{T}$ is called regular if $(\operatorname{see}[2])(i) \quad u_{p} \in C^{2}\left(D^{+}\right) \bigcap C\left(D^{+} \bigcup L\right), \quad p=\overline{1,4}$;
$(i i)(T u)_{p}, \quad(p=\overline{1,4})$, is continuously extendable at every point of $L$ from $D^{+}$except perhaps the points $a_{j}$ and $b_{j}, j=\overline{1, n}$;
(iii) near the points $a_{j}$ and $b_{j}, j=\overline{1, n}(T u)_{p}, p=\overline{1,4}$ admit estimate of the type $\left|(T u)_{p}\right|<$ const $\left|z-\alpha_{0}\right|^{-\beta}, 0 \leq \beta<1, z \in D^{+}\left(\alpha_{0}=a_{j} ; \quad \alpha_{0}=b_{j}, \quad j=\overline{1, n}\right)$, $p=\overline{1,4}$.

We consider the mixed boundary value problem. Define an elastic equilibrium of the plate $D^{+}$if

$$
\begin{equation*}
U^{+}(t)=f^{0}(t), \quad t \in L^{\prime}, \quad[T U(t)]^{+}=0, \quad t \in L^{\prime \prime} \tag{2,1}
\end{equation*}
$$

where $f^{0}=\left(f_{1}^{0}, f_{2}^{0}\right)$ is a given complex vector-function on $\left.L^{\prime},\left(f^{0}(t)\right)^{\prime} \in H\right)$. Using the Green formula [1] it is easy to prove.

Theorem 2.1. The homogeneous mixed boundary value problem (2.1) $)_{0}$ admits only a trivial solution.

Below instead of conditions $(2.1)_{f, 0}$ we consider its following equivalent conditions

$$
\begin{equation*}
2 \mu\left(\frac{\partial U(t)}{\partial S(t)}\right)^{+}=\frac{\partial f(t)}{\partial S(t)}, \quad t \in L^{\prime}, \quad(T U(t))^{+}=0, \quad t \in L^{\prime \prime} \tag{2.1}
\end{equation*}
$$

where $f(t)=2 \mu f^{0}(t)$.
Let $t=e^{i \theta} 0 \leq \theta \leq 2 \pi$. Then $\frac{\partial}{\partial S(t)}=\frac{d}{d \theta}=\frac{d}{d t} \frac{d}{d \theta}=i e^{i \theta} \frac{d}{d t}$.
Now note that, on the basis of analogous Kolosov-Muskhelishvili's formulas (1.4) and (1.3) our problem is reduced to finding two analytic vector-functions $\phi(z)=\varphi^{\prime}(z)$ and $\Psi(z)=\psi^{\prime}(z)$ in $D^{+}$by the boundary conditions (see (2.1) $)^{\prime}$ )

$$
\begin{gather*}
{\left[A \phi(t)+B \overline{\phi(t)}-B \overline{t^{\prime}(t)}-2 \mu \overline{t^{2} \Psi(t)}\right]^{+}=f^{\prime}(t), \quad t \in L^{\prime},} \\
{\left[(A-2 E) \phi(t)+B \overline{\phi(t)}-B \overline{B \phi^{\prime}(t)}-2 \mu \overline{t^{2} \Psi(t)}\right]^{+}=0, \quad t \in L^{\prime \prime} .} \tag{2.2}
\end{gather*}
$$

Consider the vector-function

$$
\begin{equation*}
(A-2 E) \phi(z)=-B \phi\left(\frac{1}{\bar{z}}\right)+B \frac{1}{\frac{1}{z} \phi^{\prime}\left(\frac{1}{\bar{z}}\right)}+2 \mu \frac{1}{z^{2}} \Psi\left(\frac{1}{\frac{1}{z}}\right) . \tag{2.3}
\end{equation*}
$$

From (2.3) it follows the equation (2.3) define $\phi(z)$ as an analytic vector-function toward $z$ in the domain $|z|>1$, and to $\frac{1}{\bar{z}}$ in the $|z|<1$.

Due to the above formula we find that

$$
\begin{equation*}
2 \mu \Psi(z)=(A-2 E) \frac{1}{z^{2}} \overline{\phi\left(\frac{1}{\bar{z}}\right)}+B \frac{1}{z^{2}} \phi(z)-B \frac{1}{z} \phi^{\prime}(z) . \tag{2.4}
\end{equation*}
$$

If follows from (2.4) that the vector-function $\Psi(z)$ is definite in the entire $z=x_{1}+i x_{2}$ plane by means of the $\phi(z)$.

Note also that if

$$
\begin{aligned}
& \phi_{j}(z)=A_{0}^{(j)}+A_{1}^{(j)} z+A_{2}^{(j)} z^{2}+\ldots, \quad|z|<1, \quad j=1,2, \\
& \phi_{j}(z)=B_{0}^{(j)}+B_{1}^{(j)} \frac{1}{z}+B_{2}^{(j)} \frac{1}{z^{2}}+\ldots, \quad|z|>1, \quad j=1,2,
\end{aligned}
$$

then due to $A_{1}+A_{3}-2=B_{1}+B_{3}, \quad A_{2}+A_{4}-2=B_{2}+B_{4}, \quad($ see $[2])$, we can conclude that, $(\operatorname{see}(2.4)), \Psi(z)$ to be analytic in the entire plane $z=x_{1}+i x_{2}$ with the point $z=0$ it is sufficient that the conditions

$$
\begin{equation*}
\left(A_{0}^{(1)}, A_{0}^{(2)}\right)^{T}+\left(\overline{B_{0}^{(1)}}, \overline{B_{0}^{(2)}}\right)^{T}=0, \quad\left(B_{1}^{(1)}, B_{1}^{(2)}\right)^{T}=0 \tag{2.5}
\end{equation*}
$$

be fulfilled.
In view of (2.3) the boundary conditions (2.2) can be written as:

$$
\begin{gather*}
\phi^{+}(t)-A^{-1}(A-2 E) \phi^{-}(t)=A^{-1} f^{\prime}(t)=h(t), \quad t \in L^{\prime}, \quad h=\left(h_{1}, h_{2}\right)^{T},  \tag{2.6}\\
\phi^{+}(t)-\phi^{-}(t)=0, \quad t \in L^{\prime \prime} . \tag{2.7}
\end{gather*}
$$

From (2.7) it follows that the vector-function $\phi(z)$ is analytic in the entire plane $z=x_{1}+i x_{2}$ cutting to the $L^{\prime}$.

To solve problem (2.6) we rewrite condition (2.6) as

$$
\begin{equation*}
\binom{1}{y} \phi^{+}(t)-\frac{2 \Delta_{0} \Delta_{1}-A_{4}+A_{3} y}{2 \Delta_{0} \Delta_{1}}\binom{1}{y} \phi^{-}(t)=\binom{1}{y} h(t), \quad t \in L^{\prime} \tag{2.8}
\end{equation*}
$$

where $y$ is an arbitrary real constant. We define the unknown $y$ by the equation

$$
y=\frac{A_{2}+y\left(2 \Delta_{0} \Delta_{1}-A_{1}\right)}{2 \Delta_{0} \Delta_{1}-A_{4}+A_{3} y}, \quad \text { or } \quad A_{3} y^{2}+\left(A_{1}-A_{4}\right) y-A_{2}=0
$$

Note that $0<A_{1}+A_{4}<4, A_{1}+A_{4}-4 \Delta_{0} \Delta_{1}>0$ and $\left(A_{1}+A_{4}\right)^{2}-16 \Delta_{0} \Delta_{1}>$ 0) (see[2]).

On the basis of $(2,8)$ representation we can conclude that a bounded at infinity solution of problem (2.6) is given by the formula (see [4 123])

$$
\phi(z)=\frac{1}{y_{2}-y_{1}}\left[\begin{array}{cc}
y_{2} & -y_{1}  \tag{2.10}\\
-1 & 1
\end{array}\right]\left[\frac{\aleph(z)}{2 \pi i} \int_{L^{\prime}} \frac{\left[\aleph^{+}(t)\right]^{-1} R(t) d t}{t-z}+\aleph(z) P_{n}(z)\right]
$$

where $y_{1}$ and $y_{2}$ are the roots of equation (2.9),

$$
\begin{gathered}
R(t)=\left[\begin{array}{ll}
1 & y_{1} \\
1 & y_{2}
\end{array}\right] h(t), \quad \aleph(z)=\left[\begin{array}{cc}
\aleph_{1}(z) & 0 \\
0 & \aleph_{2}(z)
\end{array}\right], \\
\aleph_{j}(z)=\prod_{k=1}^{n}\left(z-a_{k}\right)^{-\frac{1}{2}-i \beta_{j}}\left(z-b_{k}\right)^{-\frac{1}{2}+i \beta_{j}}, \quad \beta_{j}=\frac{\ln \left|M_{j}\right|}{2 \pi},
\end{gathered}
$$

$$
\begin{gathered}
M_{j}=\frac{1}{4 \Delta_{0} \Delta_{1}}\left[4 \Delta_{0} \Delta_{1}-A_{1}-A_{4}-(-1)^{j} \sqrt{\left(A_{1}+A_{4}\right)^{2}-16 \Delta_{0} \Delta_{1}}\right]<0 \\
P_{n}(z)=\left(P_{n_{1}}(z), P_{n_{2}}(z)\right)^{T}, \quad P_{n_{j}}(z)=\sum_{q=0}^{n} C_{q}^{(j)} z^{n-q}, \quad j=1,2 .
\end{gathered}
$$

To define $C_{q}^{(j)}, \quad j=1,2, \quad q=\overline{0, n}$, we use the following conditions (see [4, 123], (2.1) ${ }^{\prime}$ and (2.5))

$$
2 \mu \int_{b_{k} a_{k+1}} d\left[\begin{array}{l}
u_{1}+i u_{2}  \tag{2.11}\\
u_{3}+i u_{4}
\end{array}\right]=f\left(a_{k+1}\right)-f\left(b_{k}\right), \quad \phi(0)+\overline{\phi(\infty)}=0
$$

If we take into account (2.6), (2.7) and (2.10) for determining the unknown vectors $\left(C_{q}^{1}, C_{q}^{2}\right)^{T}, \quad q=\overline{0, n}$, from (2.11) we obtain the following system of equations:

$$
\begin{gather*}
2 \int_{b_{k} a_{k+1}} \phi_{0}\left(t_{0}\right) d t_{0}+\sum_{q=0}^{n} N_{k q}\binom{C_{q}^{(1)}}{C_{q}^{(2)}}=f\left(a_{k+1}\right)-f\left(b_{k}\right),  \tag{2.12}\\
\binom{\bar{C}_{0}^{(1)}}{\bar{C}_{0}^{(2)}}+\aleph(0)\binom{C n^{(1)}}{C n^{(2)}}+\frac{\aleph(0)}{2 \pi i} \int_{L^{\prime}}\left[\aleph^{+}(t)\right]^{-1} \frac{R(t) d t}{t}=0 . \tag{2.13}
\end{gather*}
$$

where (see (2.10))

$$
\begin{gathered}
\phi_{0}(t)=\frac{1}{y_{0}-y_{1}}\left[\begin{array}{cc}
y_{2} & -y_{1} \\
-1 & 1
\end{array}\right] \frac{\aleph\left(t_{0}\right)}{2 \pi i} \int_{L^{\prime}}\left[\aleph^{+}(t)\right]^{-1} \frac{R(t) d t}{t-t_{0}} \\
N_{k q}=\frac{2}{y_{2}-y_{1}}\left[\begin{array}{cc}
y_{2} & -y_{1} \\
-1 & 1
\end{array}\right] \int_{b_{k} a_{k+1}} \aleph(t) t^{n-q} d t
\end{gathered}
$$

Now note that, on the basis of the uniqueness theorem (see Theorem 2.1) for (2.1) mixed problem, we can conclude that the (2.12) and (2.13) system is solvable for $C_{q}^{(1)}, \quad q=\overline{0, n}, \quad j=1,2$.

Having found $C_{q}^{(1)}, \quad q=\overline{0, n}, \quad j=1,2$ we can be define $\phi(z)$, hence $\Psi(z), \varphi(z)$ and $\psi(z)$. Finally by (1.2) we obtain the solution of the mixed $(2.1)_{f, 0}$ problem.

The mixed boundary value problem considered in the paper, for domain outside the circle, can be solved in a similar way.

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Received 12.11.2013; revised 6.04.2014; accepted 20.07.2014.
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