

SEMI-DISCRETE AND FINITE-DIFFERENCE SCHEMES FOR
ONE-DIMENSIONAL ANALOG OF THE MITCHISON NONLINEAR SYSTEM
WITH SOURCE TERM

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Abstract. One-dimensional analog of the Mitchison nonlinear partial differential system with source term is considered. The semi-discrete scheme with respect to spatial variable and finite-difference scheme for the numerical solution of the posed initial-boundary value problem are constructed. Convergence of these schemes are given.

Keywords and phrases: Nonlinear partial differential equations, vein formation, semi-discrete scheme, finite-difference scheme, convergence theorems.

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Two-dimensional model describing the vein formation of young leaves and some qualitative and structural properties of solutions of this model are given in [1]. In [2] investigations for one-dimensional analog are carried out. In biological modeling there are many works where this and many models of similar processes are also presented and discussed (see, for example, [3]-[6] and references therein). Many scientific works are devoted to the investigation and numerical resolution of different kinds of initial-boundary value problems for the model described in [1] and its one- and multi-dimensional analogs (see, for example, [7]-[17] and references therein). Let us consider the following initial-boundary value problem for one-dimensional analog of the vein formation model [1] with source term $|S|^{q-2}S$, $q \geq 2$:

$$\begin{aligned}\frac{\partial S}{\partial t} &= \frac{\partial}{\partial x} \left(D \frac{\partial S}{\partial x} \right) - |S|^{q-2}S, \quad (x, t) \in (0, 1) \times (0, T], \\ \frac{\partial D}{\partial t} &= -D + g \left(D \frac{\partial S}{\partial x} \right), \quad (x, t) \in (0, 1) \times (0, T], \\ S(0, t) &= 0, \quad D \frac{\partial S}{\partial x} \Big|_{x=1} = \psi, \quad t \in [0, T],\end{aligned}\tag{1}$$

$$S(x, 0) = S_0(x), \quad D(x, 0) = D_0(x) \geq \delta_0 = \text{const} > 0, \quad x \in [0, 1],$$

where $0 < g_0 \leq g(\xi) \leq G_0$, g_0 , G_0 , T and ψ are positive constants, g , S_0 and D_0 are given sufficiently smooth functions and D , S are unknown functions.

The purpose of our note is to construct approximate solution of problem (1) by using semi-discrete scheme with respect to spatial variable and fully-discrete finite-difference scheme.

Using known notations, the following semi-discrete scheme is constructed and its convergence in the norm of the usual space C_h is studied:

$$\begin{aligned} \frac{ds}{dt} - (ds_{\bar{x}})_x + |s|^{q-2}s &= 0, \\ \frac{dd}{dt} &= -d + g(ds_{\bar{x}}), \end{aligned} \tag{2}$$

$$s(x, 0) = S_0(x), \quad d(x, 0) = D_0(x),$$

$$s(0, t) = 0, \quad d_{M-1/2} s_{\bar{x}, M} + \frac{h}{2} \left(\frac{dd}{dt} \right) \Big|_{x=1} = \psi.$$

Here the function s is defined on the $\bar{\omega}_h \times [0, T]$, where

$$\bar{\omega}_h = \{x_i = ih, \quad i = 0, 1, \dots, M; \quad h = 1/M\}$$

and the function d is defined on the $\omega_h^* \times [0, T]$, where

$$\omega_h^* = \{x_i = (i - 1/2)h, \quad i = 1, 2, \dots, M\}$$

respectively.

Assume, problem (1) has a sufficiently smooth solution. The following statement takes place.

Theorem 1. *The semi-discrete scheme (2) converges to the solution of problem (1) in the norm of the space C_h with the rate $O(h^2)$.*

On the grids:

$$\bar{\omega}_h \times \omega_\tau, \quad \omega_h^* \times \omega_\tau,$$

where

$$\omega_\tau = \{t_j = j\tau, \quad j = 0, 1, \dots, N, \quad \tau = T/N\},$$

based on (2) the fully-discrete finite difference scheme for problem (1) is also constructed and investigated. This scheme has the following form:

$$\begin{aligned} s_{t,i}^j &= (d_i^{j+1} s_{\bar{x},i}^{j+1})_x - |s_i^{j+1}|^{q-2} s_i^{j+1}, \\ d_{t,i-1/2}^j &= -d_{i-1/2}^{j+1} + g \left(d_{i-1/2}^{j+1} s_{\bar{x},i}^{j+1} \right), \\ s_i^0 &= S_{0,i}, \quad d_{i-1/2}^0 = D_{0,i-1/2}, \end{aligned} \tag{3}$$

$$s_0^j = 0, \quad d_{M-1/2}^j s_{\bar{x},M} + \frac{h}{2} s_{t,M}^j = \psi.$$

The following statement takes place.

Theorem 2. *The finite difference scheme (3) converges to the solution of problem (1) in the norm of the space C_h with the rate $O(\tau + h^2)$.*

Using discrete analog (3), algorithm described in [17] and based on well known iterative procedures [18] many numerical experiments were carried out. Numerical results for tests examples fully agree with theoretical investigation.

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