



Using the results from [3], we can prove that the matrix of system (1) is negatively defined, and the norm  $\Phi(x) = \left[ \sum_{i=1}^m (h_i(x_1, x_2))^2 \right]^{1/2}$ , where  $u(x)$  is a regular solution of (1), cannot achieve non-zero relative maximum for any point  $x \in \Omega$ . Taking into account this fact, it is easy to show that the regular solution of problem of Dirichlet for system (1) is unique. Also note that for the system (1) there exist generalized solutions for all classical boundary value problems, of course under specific restrictions for  $\Omega$ ,  $\Gamma$  and initial data. Hence, in case of classical boundary value problems, in corresponding generalized spaces, operator (1) will be coercive and therefore for these problems it will be possible to apply variational methods, methods of finite elements or finite differences. It is important to remark, that there exist rather powerful packages of the program for finite elements method for the systems similar to (1) which can be successfully applied to the considered boundary problems.

While modeling the filtration problems, penetration of admixtures into the different environments (soils, different kinds water basins) etc., there arise non-classical nonlocal boundary and initial-boundary problems.

**2 Mathematical modeling of filtration problem with nonlocal boundary conditions.** Let us consider the domain  $\Omega$  and subdomains  $\Omega_i$  ( $i = 1, \dots, k$ ), where  $\Gamma$  is the boundary of  $\Omega$ ,  $\Gamma_i$  boundaries of  $\Omega_i$  are Liapunov's manifolds and  $\bar{\Omega} \supset \bar{\Omega}_1 \supset \dots \supset \bar{\Omega}_k$ ; Assume that distances between  $\Gamma$  and  $\Gamma_1$ ,  $\Gamma_1$  and  $\Gamma_2$ , etc.  $\Gamma_{k-1}$  and  $\Gamma_k$  are equal to  $\varepsilon_1, \varepsilon_2, \dots, \varepsilon_k$ , ( $\varepsilon_i > 0$ ), respectively and  $\Gamma_i$  is the diffeomorphic image of  $\Gamma$ , i.e.  $\Gamma_i = I_i(\Gamma)$ , where  $I_i(\cdot)$  is diffeomorphism,  $i = 1, \dots, k$ . Let us consider the general nonlocal boundary condition for the system (1):

$$\begin{aligned} \mu_0(x) \frac{\partial u}{\partial t} \Big|_{\Gamma} + \bar{\nu}_0(x)u(x) &= \sum_{i=1}^k \bar{\nu}_i(x)u(x^{(i)}) + P(x) \quad x \in \Gamma, \\ x^{(i)} \in \Gamma_i, \quad x^{(i)} &= I_i(x), \quad x \in \Gamma, \end{aligned} \tag{2}$$

where  $\mu_0(x)$ ,  $u(x)$ ,  $\nu_i(x)$ ,  $P(x)$  are continuous functions defined on  $\Gamma$ ;  $l$  is the unit vector, going out from the boundary point  $x \in \Gamma$ . Note that the problems of type (1), (2) for concrete scalar equations are widely studied.

Our aim is to reduce the solution of nonlocal boundary problem (1), (2) to the solution of a sequence of classical Dirichlet problems. For this purpose let us consider the following iteration process:

$$\begin{aligned} \beta_1 \Delta h_1^{(p+1)} - (\gamma_0 + \gamma_1) h_1^{(p+1)} + \gamma_1 h_2^{(p+1)} &= -\gamma_0 H_0, \\ \beta_2 \Delta h_2^{(p+1)} + \gamma_1 h_1^{(p+1)} - (\gamma_1 + \gamma_2) h_1^{(p+1)} + \gamma_2 h_1^{(p+1)} &= 0, \quad x \in \Omega, \\ \dots \dots \dots \end{aligned} \tag{3}$$

$$\begin{aligned} \beta_m \Delta h_m^{(p+1)} + \gamma_{m-1} h_{m-1}^{(p+1)} - (\gamma_{m-1} + \gamma_m) h_m^{(p+1)} &= -\gamma_m H_{m+1}, \\ \mu_0(x) \frac{\partial h^{(p+1)}}{\partial l} \Big|_{\Gamma} + \bar{\nu}_0(x)h^{(p+1)}(x) &= \sum_{i=1}^k \bar{\nu}_i(x)h^{(p)}(x^{(i)}) + P(x) \quad x \in \Gamma, \\ x^{(i)} \in \Gamma_i, \quad x^{(i)} &= I_i(x), \quad x \in \Gamma, \quad p = 0, 1, 2, \dots, \end{aligned} \tag{4}$$

where  $h^{(0)}$  is an arbitrarily chosen function, but it is required that if we insert  $h^{(0)}$  into the (4), the received problem should be solvable.

The following theorem is true.

**Theorem.** Assume that  $\mu_0 = 0$ ,  $\bar{\nu}_0 = E$  (a unit operator),  $k = 1$ ,  $\bar{\nu} \equiv \text{const}$  and  $|\bar{\nu}_1| \leq q < 1$ . Then for the solution of the problem (4), (5)  $h^{(p)}(x_1, x_2) \rightarrow h(x_1, x_2)$  and the following estimation is valid:

$$\|h^{(p)} - h\| < c\bar{\nu}_1^p,$$

where  $c = \text{const}$  and doesn't depend on  $h^{(p)}$  and  $h$ . To prove this theorem, the methodology offered in [4], [5] is used. Note that  $\bar{\nu}_1$  in (4) is a coefficient of self-cleaning.

**3 Some numerical results in the case of a two-layer soil.** Let us consider the equations for soil having only two permeable layers, partitioned and limited by the poorly permeable layers:

$$\begin{aligned} \sigma_1 \frac{\partial h_1}{\partial t} &= k_1 M_1 \Delta h_1 - \frac{K_0}{M_0} (h_1 - h_2) + W, \\ \sigma_2 \frac{\partial h_2}{\partial t} &= k_2 M_2 \Delta h_2 - \frac{K_0}{M_0} (h_2 - h_1) - \frac{K_{00}}{M_{00}} (h_2 - H), \end{aligned} \quad (5)$$

where  $\sigma_1, \sigma_2$  are the coefficients of lack of saturation.  $K_0, K_{00}$  are the coefficients of filtration,  $M_0, M_{00}$  are the powers of low permeable layers.

It is evident that the operator of this system is strongly elliptic. So if one considers the classical initial-boundary problems for this equations, such problems will have a unique solution in Sobolev's spaces, of course, under the corresponding restrictions on  $\Omega, \Gamma$  and  $f_1(x, t)$ ,  $i = 1, 2$ .

The calculations were carried out for the following values of constants:

$\sigma_1 = 0.15$ ,  $\sigma_2 = 0.12$ ,  $k_1 = 0.54$ ,  $k_2 = 0.63$ ,  $M_1 = 240$ ,  $M_2 = 124$ ,  $K_0 = 0.35$ ,  $K_{00} = 0.43$ ,  $M_0 = 222$ ,  $M_{00} = 314$ ,  $p_0 = 150$ ,  $s = 0.0001$ ,  $t = 1000$ ,  $H = 0.000267$ ,  $x_1 = [0, 100]$ ,  $x_2 = [0, 100]$ .

$$W_s = p_0 \cdot e^{-st} \cdot 1 / (1 + 50(x_1 - x_1^0)^2 + 50(x_2 - x_2^0)^2).$$

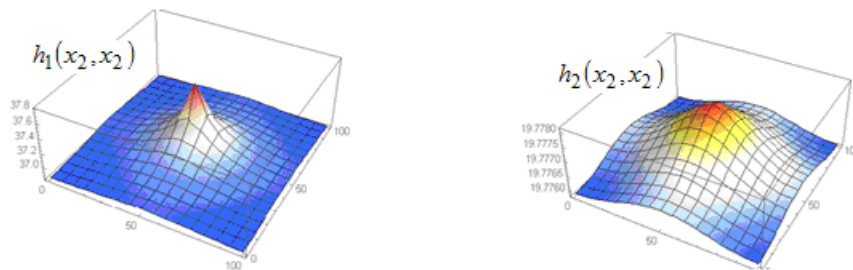


Figure 1: Stationary case, Neumann Value = 0.

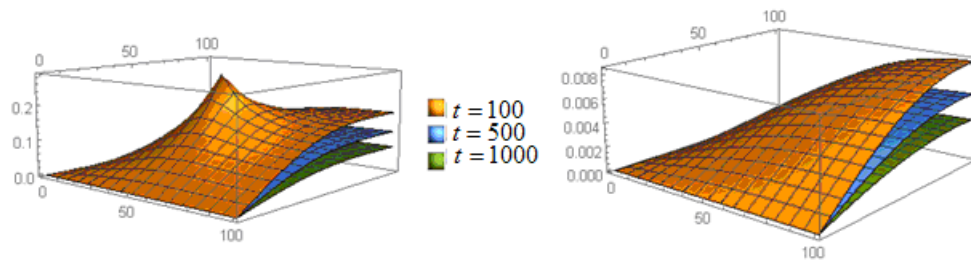


Figure 2: Nonstationary case, Neumann Value = 0.

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