

SOME REMARKS ON GENERALIZED BELTRAMI SYSTEMS

Akhalaia G., Manjavidze N.

Abstract. The generalized Beltrami systems in the complex plane are considered and the modified Dirichlet problem for such system is solved.

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The theory of elliptic systems on the plane is the classical object of investigation. We consider the first order system of partial differential equations in the complex plane C of the following form

$$w_{\bar{z}} = Q w_z, \quad (1)$$

where Q is a given $n \times n$ complex matrix of the class $W_p^1(C)$, $p > 2$ and $Q(z) = 0$ outside of some circle, satisfying the condition

$$Q(z_1) Q(z_2) = Q(z_2) Q(z_1). \quad (2)$$

Hile [1] notices that what appears to be the essential property of the elliptic systems in the plane for which one can obtain a useful extension of the analytic function theory is the self commuting property of the variable matrix Q , which is the condition (2), for any two points z_1, z_2 of the complex plane. Further, such a matrix cannot be brought into the quasi-diagonal form of Bojarski [2] by a similarity transformation. So, Hile [1] attempts to extend the results of Bojarski to a wider class of the systems in the some form as (1).

Following Hile if Q is self commuting in C , and if $Q(z)$ has eigenvalues less than 1, then system (1) is called generalized Beltrami system. Solution of such system will be called Q -holomorphic vector. Under a solution of the equation (1) in some domain D we mean so-called regular solution [3].

The matrix valued function $\Phi(z)$ is a generating solution of the system (1) if it satisfies the following properties [1]:

- (i) $\Phi(z)$ is a C^1 -solution of (1) in C ;
- (ii) $\Phi(z)$ is self-commuting and commutes with Q in C ;
- (iii) $\Phi(t) - \Phi(z)$ is invertible for all z, t in C , $z \neq t$;
- (iv) $\partial_z \Phi(z)$ is invertible for all z in C .

The matrix $V(t, z) = \partial_t \Phi(t) [\Phi(t) - \Phi(z)]^{-1}$ we call the generalized Cauchy kernel for the system (1).

Introduce some classes of Q -holomorphic vectors. Let D be a bounded domain with sufficiently smooth boundary. We say, that Q -holomorphic vector $\Phi(z)$ belongs

to the class $E_p(D, Q)$, $p > 1$, if the vector $\Phi(z)$ is representable in the domain D by the generalized Cauchy-Lebesgue type integral

$$\Phi(z) = \frac{1}{2\pi i} \int_{\Gamma} V(t, z) d_Q t \varphi(t), \quad (3)$$

where $d_Q t = I dt + Q d\bar{t}$, I is a identity matrix.

We need the following result in the sequel (see [4]).

Theorem 1. *Let $\Phi(z) \in L_p(\Gamma)$, $p > 1$. Then the generalized Cauchy-Lebesgue integral (3) belongs to the class $L_s(\overline{D})$, $s = 2p$, moreover, the following inequality*

$$\|\Phi\|_{L_s^n(\overline{D})} \leq M(p, D) \|\varphi\|_{L_p^n(\Gamma)}$$

holds. (The notation $A \in K$, where A is a matrix and K is some class of functions, means that every element $A_{\alpha\beta}$ of A belongs to K . If K is some linear normed space with the norm $\{\cdot\}_K$, then $\|A\|_K = \max_{\alpha, \beta} \|A_{\alpha\beta}\|_K$.)

Consider now the boundary value problem for the system (1), the so-called modified Dirichlet problem (see [5])

$$\operatorname{Re} [w(t)] = f(t) + a(t), \quad t \in \Gamma, \quad (4)$$

$$\operatorname{Im} [w(z_0)] = c_0, \quad z_0 \in D, \quad (5)$$

where $f(t)$ is a given real vector on Γ , c_0 given real constant vector, z_0 is an arbitrary fixed point of the domain D , $a(t) = a_j$ on Γ , $j = 0, \dots, m$ - piecewise continuous vector not defined beforehand. The vector $a(t)$ is completely defined by the problem itself, if one of its values is arbitrarily fixed. We assume, that $a_0 = 0$ in what follows. In case of absence of the curves $\Gamma_1, \dots, \Gamma_m$ we get the conditions of ordinary Dirichlet problem:

Every Q -holomorphic vector $\Phi(z)$ of the class $E_p(D, Q)$ admits the following representation:

$$\Phi(z) = \frac{1}{\pi i} \int_{\Gamma} V(t, z) d_Q t \mu(t) + iC, \quad (6)$$

where $\mu(t) \in L_p(\Gamma, \rho)$ is a real vector. The vector $\mu(t)$ is defined on Γ_j , $j \geq 1$, uniquely to within the constant vector, $\mu(t)$ on Γ_0 and the constant vector C is defined by the vector $\Phi(z)$ uniquely.

Using the representation (6) and the analog of the Sokhotsky-Plemelj formula for the integral (6) and the boundary condition (4) we obtain the system of Fredholm type integral equations:

$$[(I + M)\mu](t) = f(t) + a(t). \quad (7)$$

The corresponding homogeneous equation of (7) has nm linearly independent solutions, therefore, the inhomogeneous equation (7) is solvable if and only if the right-hand side of the equation satisfy some nm conditions. For the solution of the problem the constant vectors a_j should be chosen such, that these conditions will be fulfilled.

Following [5] instead of the equation (7) consider its equivalent equation:

$$(K\mu)(t_0) \equiv [(I + M)\mu](t_0) - \int_{\Gamma} k(t, t_0) \mu(t) ds = f(t_0), \quad (8)$$

where $k(t, t_0)$ is a diagonal matrix:

$$k(t, t_0) = \begin{cases} \rho_j(t) I, & t_0, t \in \Gamma_j, \quad j = 1, \dots, m, \\ 0, & \text{in all other cases.} \end{cases}$$

$\rho_j(t)$ denotes real continuous function given on Γ_j ($j = 1, \dots, m$) satisfying the condition

$$\int_{\Gamma_j} \rho_j(t) ds \neq 0.$$

It can be proved that the homogeneous equation (8) have not the non-trivial solutions. From this by virtue of Fredholm theorem it follows, that inhomogeneous equation (8) has always unique solution $\mu(t)$, which is a solution of initial equation (7). In addition the vectors a_j have completely defined values, namely $a_j = \int_{\Gamma_j} \rho_j \mu ds$.

We have, that the linear bounded operator K , appearing in (8), is invertible operator in Banach space $L_p^n(\Gamma)$, $p > 1$. Therefore,

$$\|\mu\|_{L_p^n(\Gamma)} \leq A(p, \Gamma) \|f\|_{L_p^n(\Gamma)},$$

where

$$A(p, \Gamma) = \|K^{-1}\|_{L_p^n(\Gamma)}.$$

Applying the estimation given in Theorem 1, it is possible to get the following estimation

$$\|\Phi\|_{L_s^n(\overline{D})} \leq B(p, \Gamma) \|f\|_{L_p^n(\Gamma)} + \sum_{i=1}^n |c_{0,i}| (mD)^{1/p},$$

where Φ is a Q -holomorphic vector resolving the problem (4), (5), mD is a measure of the domain D .

Consider the nonlinear differential system in the domain D which has the following complex form:

$$\frac{\partial w}{\partial \bar{z}} - Q(z) \frac{\partial w}{\partial z} = F(\cdot, w), \quad (9)$$

where $F(\cdot, w)$ is a $n \times 1$ -matrix.

Investigate the boundary value problem (4), (5) for the system (9), $f(t) \in L_p(\Gamma)$, $p > 1$ is a given vector on Γ , we seek the desired solution $w(z) = (w_1, \dots, w_n)$ in the class $E_p(D, Q) + C(\overline{D})$. More precisely, the boundary value problem (4), (5) in this case is posed in the following form:

Find a vector $w(z) = (w_1, \dots, w_n) \in W_p^1(D)$, $p > 2$, from the class $E_p(D, Q) + C(\overline{D})$, satisfying (9) almost everywhere in D and the condition (4) almost everywhere on Γ .

With respect to F we suppose to be fulfilled the following conditions:

- 1) $F(z, w)$ is measurable with respect to z for the fixed w ;
- 2) F satisfies the Lipshitz condition:

$$|F(z, w_1) - F(z, w_2)| \leq L|w_1 - w_2|, \quad L > 0;$$

3) $F(z, 0) \in L_s(\overline{D})$, where $s = 2p$.

From these conditions it follows that $F(z, w) \in L_s(\overline{D})$ for every vector $w \in L_s(\overline{D})$.

As a corollary of above obtained results it is possible to show, that the following theorem is valid:

Theorem 2. *If the right-hand side F of the system (9) satisfies the restrictions 1)–3) then in the case of sufficiently small Lipschitz constant L the boundary value problem (4), (5) for every given $f(t) \in L_p(\Gamma)$, $p > 1$ and c_0 has unique solution of the class $E_p(D, Q) + C(\overline{D})$. The piecewise constant vector $a(t)$ is defined completely by the problem itself, if one of its values is arbitrarily fixed.*

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Authors' addresses:

G. Akhalaia
I. Vekua Institute of Applied Mathematics of
Iv. Javakhishvili Tbilisi State University
2, University St., Tbilisi 0186
Georgia
E-mail: giaakha@gmail.com

N. Manjavidze
Georgian Technical University
77, M. Kostava St., Tbilisi 0175
Georgia
E-mail: Ninomanjavidze@yahoo.com