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ELASTIC BODY IN THE SCALAR FIELD

Sadunishvili G., Karseladze G.

Georgian Technical University

Abstract

It is considered the contact problem for domains bounded by spherical surfaces. Uniqueness theorem of the problem is proved. The solutions are represented by absolutely and uniformly convergent series.

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We denote by Ω^+ the ball bounded by the sphere $\partial\Omega$ centered at the origin and with radius R, i.e. $\Omega^+ = \{x : x \in \mathbb{R}^3, |x| < R\}, \ \partial\Omega = \{x : x \in \mathbb{R}^3, |x| = R\}$. Let $\Omega^- = \mathbb{R}^3 \setminus \overline{\Omega}^+$. Let us consider the following problem:

Problem (A). Find a regular vector $U(x) = (u(x), \omega(x))$ and a scalar function v(x) in Ω^+ and Ω^- , respectively, which satisfy: a) the differential equations [2]

$$(\mu + \alpha)\Delta u(x) + (\lambda + \mu - \alpha) \operatorname{grad} \operatorname{div} u(x) + 2\alpha \operatorname{rot} \omega(x) = 0,$$

$$(\nu + \beta)\Delta\omega(x) + (\varepsilon + \nu - \beta) \operatorname{grad} \operatorname{div} \omega(x) + 2\alpha \operatorname{rot} u(x) - 4\alpha\omega(x) = 0, \ x \in \Omega^+,$$
(1)

$$\Delta v(x) = 0, \quad x \in \Omega^{-}; \tag{2}$$

b) the contact and boundary conditions on $\partial \Omega$

$$[n(z)u(z)]^{+} - d_{1} \left[\frac{\partial v(z)}{\partial n(z)} \right]^{-} = f_{4}(z),$$

$$[H(\partial z, n)U(z)]^{+} - d_{2}n(z)[v(z)]^{-} = f^{(1)}(z),$$

$$[\widetilde{T}(\partial z, n)\omega(z)]^{+} = f^{(2)}(z);$$
(3)

c) while in the vicinity of the infinity the function v(x) meets the following asymptotic relations

$$v(x) = O(|x|^{-1}), \quad \frac{\partial v(x)}{\partial x_j} = o(|x|^{-1}), \quad j = 1, 2, 3,$$
 (4)

where $u(x) = (u_1(x), u_2(x), u_3(x))$ is the displacement vector, $\omega(x) = (\omega_1(x), \omega_2(x), \omega_3(x))$ vector of rotation, $f^{(j)} = (f_1^{(j)}, f_2^{(j)}, f_3^{(j)})$, $f_4(z)$, $f_k^{(j)}(z)$, k = 1, 2, 3, j = 1, 2, are given functions on $\partial\Omega$. n(z) is the outward (to Ω^+) unit normal vector at the point $z \in \partial\Omega$,

$$\begin{split} H(\partial x, n)U(x) &= 2\mu \frac{\partial u(x)}{\partial n(x)} + \lambda n(x) \operatorname{div} u(x) + (\mu - \alpha)[n(x) \times \operatorname{rot} u(x)] \\ &+ 2\alpha[n(x) \times \omega(x)], \\ \widetilde{T}(\partial x, n)\omega(x) &= 2\nu \frac{\partial \omega(x)}{\partial n(x)} + \varepsilon n(x) \operatorname{div} \omega(x) + (\nu - \beta)[n(x) \times \operatorname{rot} \omega(x)], \end{split}$$

 $\lambda, \mu, \nu, \alpha, \beta, \varepsilon, d_1, d_2$ are the constants, which satisfy the conditions: $\mu > 0, \alpha > 0, \nu > 0, \beta > 0, 3\lambda + 2\mu > 0, 3\varepsilon + 2\nu > 0, d_1d_2 > 0.$

Theorem. The general solution of the problem $(A)_0$ $(f_4 = 0, f^{(j)} = 0, j = 1, 2)$ is

$$u(x)=[a\times x],\ \omega(x)=a,\ x\in\Omega^+,\quad v(x)=0,\ x\in\Omega^-$$

Proof. We have Green's formulas for (1),(2) system in domains Ω^{\pm} [2]

$$\int_{\Omega^{+}} U(x) \cdot M(\partial x)U(x) \, dx = \int_{\partial\Omega} [u(z) \cdot H(\partial z, n)U(z) + \omega(z) \cdot \widetilde{T}(\partial z, n)\omega(z)]^{+} \, ds - \int_{\Omega^{+}} E(U, U) \, dx,$$

$$\int_{\Omega^{-}} v(x)\Delta v(x) \, dx = -\int_{\partial\Omega} \left[v(z) \frac{\partial v(z)}{\partial n(z)} \right]^{-} \, ds - \int_{\Omega^{-}} (\operatorname{grad} v(x))^{2} \, dx,$$
(5)

where

$$E(U,U) = \frac{3\lambda + 2\mu}{3} (\operatorname{div} u)^2 + \frac{3\varepsilon + 2\nu}{3} (\operatorname{div} \omega)^2 + \frac{\mu}{2} \sum_{i,j=1}^3 \left(\frac{\partial u_i}{\partial x_j} + \frac{\partial u_j}{\partial x_i} - \frac{2}{3} \delta_{ij} \operatorname{div} u \right)^2 + \frac{\nu}{2} \sum_{i,j=1}^3 \left(\frac{\partial \omega_i}{\partial x_j} + \frac{\partial \omega_j}{\partial x_i} - \frac{2}{3} \delta_{ij} \operatorname{div} \omega \right)^2 + \frac{\alpha}{2} \sum_{i,j=1}^3 \left(\frac{\partial u_j}{\partial x_i} - \frac{\partial u_i}{\partial x_j} + 2 \sum_{k=1}^3 \varepsilon_{kji} \omega_k \right)^2 + \frac{\beta}{2} \sum_{i,j=1}^3 \left(\frac{\partial \omega_j}{\partial x_i} - \frac{\partial \omega_i}{\partial x_j} \right)^2,$$

 $M(\partial x)U(x)$ is the left part of the system (1).

Taking into account the conditions of the $Problem(A)_0$. from (5) we have

$$E(U, U) = 0, \quad \text{grad} v(x) = 0.$$

The solutions of this equations has the form [2]

$$u(x) = [a \times x] + b, \quad \omega(x) = a, \quad x \in \Omega^+, \quad v(x) = c, \quad x \in \Omega^-,$$

where a and b are three-dimensional vectors, c is a constant.

From the conditions (4) and boundary conditions of problem $(A)_0$ we have

$$u(x)=[a\times x], \ \omega(x)=a, \ x\in \Omega^+, \quad v(x)=0, \ x\in \Omega^-.\square$$

Let us seek the solutions of the formulated problem (A) in the form [3]

$$u(x) = \operatorname{grad} \Phi_1(x) - a \operatorname{grad} r^2 \left(r \frac{\partial}{\partial r} + 1 \right) \Phi_2(x) + \operatorname{rot} \operatorname{rot}(xr^2 \Phi_2(x)) + \operatorname{rot}(x\Phi_3(x)) + 2\alpha [\operatorname{rot} \operatorname{rot}(x\Phi_5(x)) + \operatorname{rot}(x\Phi_6(x))],$$

$$\omega(x) = \operatorname{grad} \Phi_4(x) - \operatorname{rot} \left[x \left(2r \frac{\partial}{\partial r} + 3 \right) \Phi_2(x) \right] + \frac{1}{2} \operatorname{rot} \operatorname{rot}(x\Phi_3(x)) - (\mu + \alpha) [\lambda_2^2 \operatorname{rot}(x\Phi_5(x)) - \operatorname{rot} \operatorname{rot}(x\Phi_6(x))],$$
(6)

$$v(x) = \sum_{k=0}^{\infty} \sum_{m=-k}^{k} \left(\frac{R}{r}\right)^{k+1} Y_k^{(m)}(\vartheta, \varphi) B_{mk},\tag{7}$$

where B_{mk} is sought for constant, $x = (x_1, x_2, x_3), r = |x|, r\frac{\partial}{\partial r} = (x \cdot \text{grad}), \Delta \Phi_j(x) = 0,$ $j = 1, 2, 3, \quad (\Delta - \lambda_1^2) \Phi_4(x) = 0, \quad (\Delta - \lambda_2^2) \Phi_j(x) = 0, \ j = 5, 6, \quad a = \mu(\lambda + 2\mu)^{-1},$ $\lambda_1^2 = 4\alpha(\varepsilon + 2\nu)^{-1}, \quad \lambda_2^2 = 4\alpha\mu[(\nu + \beta)(\mu + \alpha)]^{-1},$

$$Y_k^{(m)}(\vartheta,\varphi) = \sqrt{\frac{2k+1}{4\pi} \cdot \frac{(k-m)!}{(k+m)!}} P_k^{(m)}(\cos\vartheta) e^{im\varphi}$$

We look for functions $\Phi_j(x)$, j = 1, 2, ..., 6, in the following form

$$\Phi_{j}(x) = \sum_{k=0}^{\infty} \sum_{m=-k}^{k} \left(\frac{r}{R}\right)^{k} Y_{k}^{(m)}(\vartheta,\varphi) A_{mk}^{(j)}, \quad j = 1, 2, 3,$$

$$\Phi_{4}(x) = \sum_{k=0}^{\infty} \sum_{m=-k}^{k} g_{k}(\lambda_{1}, r) Y_{k}^{(m)}(\vartheta,\varphi) A_{mk}^{(4)}, \quad (8)$$

$$\Phi_{j}(x) = \sum_{k=0}^{\infty} \sum_{m=-k}^{k} g_{k}(\lambda_{2}, r) Y_{k}^{(m)}(\vartheta,\varphi) A_{mk}^{(j)}, \quad j = 5, 6,$$

where

$$g_k(\lambda_j r) = \sqrt{\frac{R}{r}} \frac{I_{k+\frac{1}{2}}(\lambda_j r)}{I_{k+\frac{1}{2}}(\lambda_j R)}, \quad j = 1, 2.$$

Upon substitution of the $\Phi_j(x)$ from (8) into the representations u(x) and $\omega(x)$, we have

$$u(x) = \sum_{k=0}^{\infty} \sum_{m=-k}^{k} \left[u_{mk}^{(1)}(r) X_{mk}(\vartheta, \varphi) + \sqrt{k(k+1)} \left(v_{mk}^{(1)}(r) Y_{mk}(\vartheta, \varphi) + w_{mk}^{(1)}(r) Z_{mk}(\vartheta, \varphi) \right) \right],$$

$$\omega(x) = \sum_{k=0}^{\infty} \sum_{m=-k}^{k} \left[u_{mk}^{(2)}(r) X_{mk}(\vartheta, \varphi) + \sqrt{k(k+1)} \left(v_{mk}^{(2)}(r) Y_{mk}(\vartheta, \varphi) + w_{mk}^{(2)}(r) Z_{mk}(\vartheta, \varphi) \right) \right]$$
(9)

The stress vectors has the following form

$$H(\partial x, n)U(x) = \sum_{k=0}^{\infty} \sum_{m=-k}^{k} \left[a_{mk}^{(1)}(r) X_{mk}(\vartheta, \varphi) + \sqrt{k(k+1)} \left(b_{mk}^{(1)}(r) Y_{mk}(\vartheta, \varphi) + c_{mk}^{(1)}(r) Z_{mk}(\vartheta, \varphi) \right) \right],$$

$$\widetilde{T}(\partial x, n)\omega(x) = \sum_{k=0}^{\infty} \sum_{m=-k}^{k} \left[a_{mk}^{(2)}(r) X_{mk}(\vartheta, \varphi) + \sqrt{k(k+1)} \left(b_{mk}^{(2)}(r) Y_{mk}(\vartheta, \varphi) + c_{mk}^{(2)}(r) Z_{mk}(\vartheta, \varphi) \right) \right]$$
(10)

where $u_{mk}^{(j)}(z)$, $v_{mk}^{(j)}(z),...,c_{mk}^{(j)}(z)$, j = 1,2 are functions of r, $X_{mk}(\vartheta,\varphi)$, $Y_{mk}(\vartheta,\varphi)$, $Z_{mk}(\vartheta,\varphi)$ are orthonormal vectors from $L_2(\Sigma_1)$. [1]

Let us assume that the function $f_4(z)$ and the vector $f^{(j)}(z)$, j = 1, 2, satisfy the sufficient smoothness conditions, that allow us to represent them into a Fourier-Laplas series

$$f^{(j)}(z) = \sum_{k=0}^{\infty} \sum_{m=-k}^{k} \left[\alpha_{mk}^{(j)}(r) X_{mk}(\vartheta, \varphi) + \sqrt{k(k+1)} \left(\beta_{mk}^{(j)}(r) Y_{mk}(\vartheta, \varphi) + \gamma_{mk}^{(j)}(r) Z_{mk}(\vartheta, \varphi) \right) \right], \quad j = 1, 2,$$

$$f_4(z) = \sum_{k=0}^{\infty} \sum_{m=-k}^{k} \alpha_{mk}^{(4)} Y_k^{(m)}(\vartheta, \varphi).$$

$$(11)$$

If in (7), (9), (10), we pass to the limit as $x \to z \in \partial \Omega$ $(r \to R)$, with the help of (11) and the contact and boundary conditions (3), we obtain the system of linear algebraic equations for the sought for constants $A_{mk}^{(j)}$, B_{mk} ,

$$u_{mk}^{(1)}(R) - d_1(k+1)R^{-1}B_{mk} = \alpha_{mk}^{(4)}, \ a_{mk}^{(1)}(R) - d_2B_{mk} = \alpha_{mk}^{(1)}, \ k \ge 0,$$

$$b_{mk}^{(j)}(R) = \beta_{mk}^{(j)}, \ c_{mk}^{(j)}(R) = \gamma_{mk}^{(j)}, \ k \ge 1, \ j = 1, 2, \ a_{mk}^{(2)}(R) = \alpha_{mk}^{(2)}, \ k \ge 0.$$
 (12)

The condition

$$\int_{\partial\Omega} [z \times f^{(1)}(z) + f^{(2)}(z)] ds = 0$$

is necessary and sufficient for the above problem to be solvable.

Substituting of functions $f^{(j)}(z)$, j = 1, 2, into the last formulae, we see that the coefficient $\beta_{mk}^{(2)}$ and $\gamma_{mk}^{(1)}$ satisfy the following condition

$$\beta_{mk}^{(2)} + R\gamma_{mk}^{(1)} = 0, \quad m = 0, \pm 1.$$
(13)

Proceeding from the uniqueness theorem for the Problem (A) and condition (13), we can infer to (12) system is solvable and the constant $A_{m1}^{(3)}$ is not defined. This is natural since the solution of the Problem (A) is defined within the vector

$$u(x) = [a \times x], \ \omega(x) = a, \ v(x) = 0.$$

If $f^{(j)}(z) \in C^3(\partial\Omega)$, $j = 1, 2, f_4(z) \in C^4(\partial\Omega)$, then the obtained series (7), (9), (10) are absolutely and uniformly convergent.

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