

THE METHOD OF A SMALL PARAMETER
FOR THE NON-SHALLOW SHELLS

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1. There exist several methods of reduction of the three-dimensional problems to the two-dimensional ones (Kirchhoff-Love, E. Reissner, A. Green, W. Koiter, P. Nagdi, A. Goldenveizer, I. Vorovich, I. Vekua, etc).

Under thin and shallow shells I. Vekua meant the three-dimensional shell-type elastic bodies satisfying the conditions

$$1 - k_\alpha x_3 \equiv 1 \quad (\alpha, \beta = 1, 2), \quad -h \leq x_3 \leq h \quad (*)$$

(h-semithickness of shell Ω), which means that geometry of the shell doesn't vary in thickness and therefore such kind of shells are usually called the shells with non-varying geometry. Here k_1 and k_2 are principal curvature of the midsurface S .

In the sequel, under non-shallow shells will be meant elastic bodies free from the assumption of the type (*), or more exactly the bodies with the conditions

$$1 - k_\alpha x_3 \neq 1, \quad |hk_\alpha| \leq q < 1.$$

Such kind of shells are called shells with varying in thickness geometry, or non-shallow shells.

Now following I. Vekua we obtain the system of two-dimensional equations, which is lines of curvature coordinates written as:

$$a) \left\{ \begin{array}{l} h \nabla_\alpha \binom{(m)}{\sigma}^{\alpha 1} - \varepsilon k_1 R \binom{(m)}{\sigma}^{13} - (2m+1) \left(\binom{(m-1)}{\sigma}^{31} + \binom{(m-3)}{\sigma}^{31} + \dots \right) + h \binom{(m)}{F}^1 = 0, \\ h \nabla_\alpha \binom{(m)}{\sigma}^{\alpha 2} - \varepsilon k_2 R \binom{(m)}{\sigma}^{23} - (2m+1) \left(\binom{(m-1)}{\sigma}^{32} + \binom{(m-3)}{\sigma}^{32} + \dots \right) + h \binom{(m)}{F}^2 = 0, \\ h \nabla_\alpha \binom{(m)}{\sigma}^{\alpha 3} + \varepsilon R (k_1 \binom{(m)}{\sigma}^1_1 + k_2 \binom{(m)}{\sigma}^2_2) - (2m+1) \left(\binom{(m-1)}{\sigma}^{33} + \binom{(m-3)}{\sigma}^{33} + \dots \right) \\ + h \binom{(m)}{F}^3 = 0, \quad \left(\binom{(k)}{\sigma}^{ij} = 0, \quad k < 0, \quad i, j = 1, 2, 3 \right) \quad (m = 0, 1, \dots, N) \end{array} \right. \quad (1)$$

where $\varepsilon = \frac{h}{R}$ is a small parameter, R -characteristic radius of curvature, then

$$\begin{aligned} \binom{(m)}{\mathbf{F}} &= \binom{(m)}{\Phi} + \frac{2m+1}{h} \left[(1 - \varepsilon k_1 R)(1 - \varepsilon k_2 R) \binom{(+)}{\sigma}^3 \right. \\ &\quad \left. - (-1)^m (1 + \varepsilon k_1 R)(1 + \varepsilon k_2 R) \binom{(-)}{\sigma}^3 \right], \end{aligned}$$

b) Hooke's law

$$\left\{ \begin{array}{l} h \sigma^{\alpha\beta} = \sum_{s=0}^{\infty} \left\{ I_{\alpha_1\gamma_1}^{(m,s)\alpha\gamma} \left[\lambda (h\nabla_{\gamma} \mathbf{U}^{\gamma_1} - \varepsilon b_{\gamma}^{\gamma_1} R \mathbf{U}_3) a^{\alpha_1\beta} + \mu (h\nabla_{\gamma} \mathbf{U}^{\alpha_1} - \varepsilon b_{\gamma}^{\alpha_1} R \mathbf{U}_3) a^{\beta\gamma_1} + \mu (h\nabla_{\gamma} \mathbf{U}^{\beta} - \varepsilon b_{\gamma}^{\beta} R \mathbf{U}_3) a^{\alpha_1\gamma_1} \right] + \lambda I_{3\alpha_1}^{(m,s)3\alpha} \mathbf{U}'_{\alpha_1} \right\}, \\ h \sigma^{\alpha 3} = \mu \sum_{s=0}^{\infty} \left[I_{\alpha_1\gamma_1}^{(m,s)\alpha\gamma} (h\nabla_{\gamma} \mathbf{U}_3 + \varepsilon b_{\gamma}^{\eta} R \mathbf{U}_{\eta}) a^{\alpha_1\gamma_1} + I_{3\alpha_1}^{(m,s)3\alpha} \mathbf{U}'_{\alpha_1} \right], \\ h \sigma^{3\alpha} = \mu \sum_{s=0}^{\infty} \left[I_{3\alpha_1}^{(m,s)3\alpha} (h\nabla_{\gamma} \mathbf{U}_3 + \varepsilon b_{\gamma}^{\eta} R \mathbf{U}_{\eta}) a^{\alpha_1\gamma} + I_{33}^{(m,s)33} \mathbf{U}'_{\alpha_1} \right], \\ h \sigma^{33} = \sum_{s=0}^{\infty} \left[\lambda I_{3\gamma_1}^{(m,s)3\gamma} (h\nabla_{\gamma} \mathbf{U}^{\gamma_1} - \varepsilon b_{\gamma}^{\gamma_1} R \mathbf{U}_3) + (\lambda + 2\mu) I_{33}^{(m,s)33} \mathbf{U}_3 \right] \end{array} \right. \quad (2)$$

where $b_1^1 = k_1$, $b_2^2 = k_2$, $b_2^1 = b_1^2 = 0$,

$$\mathbf{u}' = (2s+1) \left(\binom{s+1}{\mathbf{u}} + \binom{s+3}{\mathbf{u}} + \dots \right),$$

$$\begin{aligned} I_{\alpha\alpha}^{(m,s)\alpha\alpha} &= \frac{2m+1}{2h} \int_{-h}^h \frac{1-k_{\beta}x_3}{1-k_{\alpha}x_3} p_m p_s dx_3 = \frac{k_{\beta}}{k_{\alpha}} \delta^{ms} + \frac{2m+1}{2k_{\alpha}h} \frac{k_{\alpha}-k_{\beta}}{k_{\alpha}} P_m \left(\frac{1}{k_{\alpha}h} \right) Q_s \left(\frac{1}{k_{\alpha}h} \right) \\ &= \frac{k_{\beta}}{k_{\alpha}} \delta^{ms} + \frac{k_{\alpha}-k_{\beta}}{k_{\alpha}} \sum_{p=0}^{\lfloor \frac{m}{2} \rfloor} \sum_{q=0}^{\infty} M_{pq}^{(m,s)} (\varepsilon R k_{\alpha})^{s-m+2(p+q)}, \quad (m \leq s; \alpha \neq \beta). \end{aligned}$$

Here P_m and Q_s - are Legendre polynomial and functions of the second kind, then

$$M_{pq}^{(m,s)} = 2^{s-m} \frac{(-1)^p}{p!} \frac{(2m-2p)!}{(m-p)!(m-2p)!} \frac{(s+q)!(s+2q)!}{(2s+2q+1)!}, \quad (m \leq s),$$

$$I_{\alpha\beta}^{(m,s)\alpha\beta} = I_{\beta\alpha}^{(m,s)\beta\alpha} = \delta_{ms}, \quad I_{\beta}^{\alpha} = 0, \quad (\alpha \neq \beta),$$

$$\begin{aligned} I_{\alpha 3}^{(m,s)\alpha 3} &= I_{3\alpha}^{(m,s)3\alpha} = \frac{2m+1}{2h} \int_{-h}^h (1-k_{\beta}x_3) p_m p_s dx_3 \\ &= \delta^{ms} - \varepsilon k_{\beta} R \left(\frac{m}{2m-1} \delta_m^{s-1} + \frac{m+1}{2m+3} \delta_m^{s+1} \right) \quad (\alpha \neq \beta), \end{aligned}$$

$$\begin{aligned} I_{33}^{(m,s)33} &= \frac{2m+1}{2h} \int_{-h}^h \sqrt{\frac{g}{a}} p_m p_s dx_3 = \delta_{ms} - 2H\varepsilon R \left(\frac{m}{2m-1} \delta_m^{s-1} + \frac{m+1}{2m+3} \delta_m^{s+1} \right) \\ &+ \varepsilon^2 K R^2 \left(\frac{m(m-1)}{(2m+1)(2m-3)} \delta_m^{s+1} + \frac{1}{2m+1} \left(\frac{(m+1)^2}{2m+3} + \frac{m^2}{2m-1} \right) \delta_m^s \right. \\ &\left. + \frac{(m+1)(m+2)}{(2m+3)(2m+5)} \delta_m^{s-2} \right) \end{aligned}$$

$$(2H = k_1 + k_2, \quad K = k_1 k_2).$$

c) Boundary conditions of the lateral contour of midsurface S :

$$\begin{aligned}
 I) \quad & \begin{aligned} \begin{pmatrix} m \\ \sigma \end{pmatrix} \begin{pmatrix} \text{II} \end{pmatrix} &= \begin{pmatrix} m \\ \sigma \end{pmatrix} \alpha\beta l_\alpha l_\beta = f_1, & \begin{pmatrix} m \\ \sigma \end{pmatrix} \begin{pmatrix} \text{Is} \end{pmatrix} &= \begin{pmatrix} m \\ \sigma \end{pmatrix} \alpha\beta l_\alpha s_\beta = f_2, \\ \begin{pmatrix} m \\ \sigma \end{pmatrix} \begin{pmatrix} \text{In} \end{pmatrix} &= \begin{pmatrix} m \\ \sigma \end{pmatrix} \alpha^3 l_\alpha = f_3, \end{aligned} \\
 II) \quad & \begin{aligned} \begin{pmatrix} m \\ U \end{pmatrix} \begin{pmatrix} \text{I} \end{pmatrix} &= \begin{pmatrix} m \\ U \end{pmatrix} \alpha l_\alpha = g_1, & \begin{pmatrix} m \\ U \end{pmatrix} \begin{pmatrix} \text{s} \end{pmatrix} &= \begin{pmatrix} m \\ U \end{pmatrix} \alpha l_\alpha = g_2, & \begin{pmatrix} m \\ U \end{pmatrix} \begin{pmatrix} \text{3} \end{pmatrix} &= g_3. \end{aligned} \\
 & \quad (\mathbf{l} \times \mathbf{s} = \mathbf{n}, \quad l_\alpha = \mathbf{l} \cdot \mathbf{r}_\alpha, \quad s_\alpha = \mathbf{s} \cdot \mathbf{r}_\alpha)
 \end{aligned} \tag{3}$$

2. Approximations of order $N = 0$ and $N = 1$. By introducing the following notations

$$\left(\begin{pmatrix} 0 \\ \sigma \end{pmatrix}^{ij}, \begin{pmatrix} 0 \\ \mathbf{U} \end{pmatrix}, \begin{pmatrix} 0 \\ F \end{pmatrix}^i \right) = (T^{ij}, \mathbf{u}, X^i), \quad \begin{pmatrix} 0,0 \\ I \end{pmatrix} \dots = I \dots$$

for approximation $N = 0$, we obtain

a) Equation of equilibrium

$$\begin{cases} h(\nabla_1 T^{1\alpha} + \nabla_2 T^{2\alpha}) - \varepsilon k_1 R T^{\alpha 3} + h X^\alpha = 0 (\alpha = 1, 2), \\ h(\nabla_1 T^{13} + \nabla_2 T^{23}) + \varepsilon R(k_1 T_1^1 + k_2 T_2^2) + h X^3 = 0. \end{cases}$$

b) Hooke's law

$$\begin{cases} hT^{\alpha\beta} = I_{\alpha_1\gamma_1}^{\alpha\gamma} [\lambda(h\nabla_\gamma u^{\gamma_1} - \varepsilon b_\gamma^{\gamma_1} R u_3) a^{\alpha_1\beta} + \mu(h\nabla_\gamma u^{\alpha_1} - \varepsilon b_\gamma^{\alpha_1} R u_3) a^{\beta\gamma_1} \\ \quad + \mu(h\nabla_\gamma u^\beta - \varepsilon b_\gamma^\beta R u_3) a^{\alpha_1\gamma_1}], \\ hT^{\alpha 3} = \mu I_{\alpha_1\gamma_1}^{\alpha\gamma} (h\nabla_\gamma u_3 + \varepsilon b_\gamma^\eta R u_\eta) a^{\alpha_1\gamma_1}, \\ I_{\alpha\alpha}^{\alpha\alpha} = 1 + \varepsilon^2 \frac{k_\alpha^2 - k_\alpha k_\beta}{3} R^2 + \dots + \varepsilon^{2p} \frac{k_\alpha^{2p} - k_\alpha^{2p-1} k_\beta}{2p+1} R^{2p} + \dots \\ I_{\alpha\beta}^{\alpha\beta} = I_{\beta\alpha}^{\beta\alpha} = 1, \quad I_{33}^{33} = 1, \quad (\alpha \neq \beta). \end{cases}$$

To determine the components of the displacement vector and stress tensor we shall use expansions with respect to the small parameter ε :

$$(T^{ij}, \mathbf{u}, X^i) = \sum_{n=0}^{\infty} \left(\begin{pmatrix} n \\ T \end{pmatrix}^{ij}, \begin{pmatrix} n \\ \mathbf{u} \end{pmatrix}, \begin{pmatrix} n \\ X \end{pmatrix}^i \right) \varepsilon^n$$

and then equate to zero the factors ε^n , we have

$$\begin{cases} \mu \nabla_\alpha \nabla^\alpha \begin{pmatrix} n \\ \mathbf{u} \end{pmatrix}_\beta + (\lambda + \mu) \partial_\beta \begin{pmatrix} n \\ \theta \end{pmatrix} = Y_\beta \begin{pmatrix} n \\ \mathbf{u}, \dots, \begin{pmatrix} n-1 \\ \mathbf{u} \end{pmatrix} \end{pmatrix} \quad (\beta = 1, 2) \\ \mu \nabla_\alpha \nabla^\alpha \begin{pmatrix} n \\ \mathbf{u} \end{pmatrix}_3 = Y_3 \begin{pmatrix} n \\ \mathbf{u}, \dots, \begin{pmatrix} n-1 \\ \mathbf{u} \end{pmatrix} \end{pmatrix} \quad (\theta = \nabla_\alpha \begin{pmatrix} n \\ \mathbf{u} \end{pmatrix}^\alpha). \end{cases} \\
 (n = 0, 1, 2, \dots)$$

The general solution of the system is expressed by three harmonic functions on the midsurface S , and it ensure the satisfaction of three given physical or kinematic conditions [1].

For approximate of order $N = 1$ we have the following systems equation of equilibrium

$$\left\{ \begin{array}{l} \mu h \nabla_{\alpha} \nabla^{\alpha} u_{\beta}^{(n)} + (\lambda + \mu) h \partial_{\beta} \theta^{(n)} + 2\lambda \partial_{\beta} v_3^{(n)} = A_{\beta}^{(n)}(\mathbf{u}^{(0)}, \mathbf{v}^{(0)}, \dots, \mathbf{u}^{(n-1)}, \mathbf{v}^{(n-1)}), \\ \mu \left(h \nabla_{\alpha} \nabla^{\alpha} u_3^{(n)} + \rho^{(n)} \right) = A_3^{(n)}(\mathbf{u}^{(0)}, \mathbf{v}^{(0)}, \dots, \mathbf{u}^{(n-1)}, \mathbf{v}^{(n-1)}), \\ \mu h^2 \nabla_{\alpha} \nabla^{\alpha} v_{\beta}^{(n)} + (\lambda + \mu) h^2 \partial_{\beta} \rho^{(n)} - 3\mu \left(h \partial_{\beta} u_3^{(n)} + v_{\beta}^{(n)} \right) = B_{\beta}^{(n)}(\mathbf{u}^{(0)}, \mathbf{v}^{(0)}, \dots, \mathbf{u}^{(n-1)}, \mathbf{v}^{(n-1)}), \\ \mu h^2 \nabla_{\alpha} \nabla^{\alpha} v_3^{(n)} + 3 \left[\lambda h \theta^{(n)} + (\lambda + 2\mu) v^{(n)} \right] = B_3^{(n)}(\mathbf{u}^{(0)}, \mathbf{v}^{(0)}, \dots, \mathbf{u}^{(n-1)}, \mathbf{v}^{(n-1)}), \end{array} \right.$$

where $\theta^{(n)} = \nabla_{\alpha} u^{\alpha (n)}$, $\rho^{(n)} = \nabla_{\alpha} v^{\alpha (n)}$, $\mathbf{U} = \mathbf{u} + p_1 \left(\frac{x_3}{h} \right) \mathbf{v}$.

The general solution of the system is expressed by six poliharmonic functions on the midsurface S .

REFERENCES

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