

ON ONE VARIATIONAL INTERPRETATION OF BITSADZE-SAMARSKII
NON-LOCAL BOUNDARY VALUE PROBLEM
FOR THE BIHARMONIC EQUATION

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In this article one variational concept of the Bitsadze-Samarskii nonlocal boundary value problem for the biharmonic equation in the rectangle is considered [1].

Problem. Find the function $u(x, y) \in C^1(\overline{G}) \cap C^4(G)$ satisfying the conditions

$$\begin{aligned} \Delta^2 u(x, y) &= f(x, y), \quad \text{for } (x, y) \in G, \\ u(x, y)|_{\Gamma} &= 0, \quad \frac{\partial u(x, y)}{\partial \nu} \Big|_{\partial G} = 0, \\ u(x, y)|_{\Gamma_{-\xi}} &= u(x, y)|_{\Gamma_0}, \end{aligned} \tag{1}$$

where $G = \{(x, y) | -a < x < 0, 0 < y < b\}$ is the rectangle, a and b are the given positive constants, $f(x, y)$ is the given function $f(x, y) \in C(\overline{G})$, ν is the external unitary normal of the boundary of G , Γ_t is the intersection of the line $x = t$ with the set $\overline{G} = G \cup \partial G$, $\Gamma = \partial G \setminus \Gamma_0$, $\xi \in]-a, 0[$ is the given number.

Let us denote by $D(\overline{G})$ the lineal of all the real functions $u(x, y)$ satisfying the following conditions:

1. $u(x, y)$ is defined almost everywhere on $\overline{G} \setminus \Gamma_0$, and the boundary value $u(0, y)$ is defined almost everywhere on Γ_0 .
2. $u(x, y) \in L_2(G)$, $u(0, y) \in L_2(0, b)$.

We note that the definition of the function $u(x, y) \in D(G)$ means the definition of the couple $u(x, y), u(0, y)$, $(x, y) \in \overline{G} - \Gamma_0, y \in [0, b]$.

The same definition of the function $u(x, y)$ of the lineal $D(\overline{G})$ and for the function $u(x, y) \in L_2(G)$ defined almost everywhere on $\overline{G} \setminus \Gamma_0$ will be clear from the context.

Two functions $u_1(x, y)$ and $u_2(x, y)$ are assumed as the same element of $D(\overline{G})$ if $u_1(x, y) = u_2(x, y)$ almost everywhere on $\overline{G} \setminus \Gamma_0$ and $u_1(0, y) = u_2(0, y)$ almost everywhere on $[0, b]$.

Let us define on $D(\overline{G})$ the operator of symmetrical extension \mathcal{T} as follows

$$\mathcal{T} u(x, y) = \begin{cases} u(x, y), & \text{if } (x, y) \in \overline{G}, \\ -u(-x, y) + 2u(0, y), & \text{if } (x, y) \in \overline{Q}. \end{cases}$$

where $Q = \{(x, y) | 0 < x < \xi, 0 < y < b\}$.

Let us note that the operator \mathcal{T} associates to every function $u(x, y)$ of the lineal $D(\overline{G})$ the function $\tilde{u}(x, y) = \mathcal{T} u(x, y)$ defined almost everywhere on $\overline{G} \cup \Gamma_0$ in such a way that the function $\tilde{u}(x, y) - u(0, y)$ is the odd function with respect to the variable x almost everywhere on $[-\xi, \xi]$ for the almost all $y \in [0, b]$.

For two arbitrary functions $u(x, y)$ and $v(x, y)$ from the linear $D(\overline{G})$ we define the scalar product

$$[u, v] = \int_0^b \int_{-\xi}^{\xi} \int_{-a}^x \tilde{u}(s, y) \tilde{v}(s, y) ds dx dy. \quad (2)$$

After the introduction of the scalar product (2) the linear $D(\overline{G})$ becomes the pre-Hilbert space, which we denote by $H(\overline{G})$. The norm originated from the scalar product (2) in $H(\overline{G})$ we denote by $\|\cdot\|_H$:

$$\|u\|_H^2 = \int_0^b \int_{-\xi}^{\xi} \int_{-a}^x \tilde{u}(s, y)^2 ds dx dy. \quad (3)$$

Theorem 1. *The norm defined on the linear $D(\overline{G})$ by the formula*

$$\|u\|^2 = \|u(x, y)\|_{L_2(G)}^2 + \|u(0, y)\|_{L_2(0, b)}^2$$

is equivalent to the norm $\|\cdot\|_H$.

Consequence. $H(\overline{G})$ *is the Hilbert space.*

Let, the area of definition of the operator $A = \Delta^2$ is the linear $D_A(\overline{G})$ of the functions from the space $H(\overline{G})$ for the elements $u(x, y)$ of which the following conditions are fulfilled:

1. $u(x, y) \in C^4(\overline{G})$, $\frac{\partial^k u(0, y)}{\partial x^k} = 0 \quad \forall y \in [0, b], \quad k = 2, 4;$
2. $u(x, y)|_{\Gamma} = 0$, $\frac{\partial u}{\partial \nu}|_{\partial G} = 0$, $\frac{\partial^2 u}{\partial x^2}(-\xi, y) = 0$, $u(-\xi, y) = u(0, y)$, $\forall y \in [0, b]$.

Theorem 2. *The linear $D_A(G)$ is danced in the space $H(\overline{G})$.*

Hence, the operator A acts from the linear $D_A(\overline{G})$ danced in the space $H(\overline{G})$ to the space $H(\overline{G})$.

Lemma 1. *For an arbitrary function $u(x, y)$ of the linear $D_A(\overline{G})$ the following identity is valid*

$$\mathcal{T}Au = A\mathcal{T}u.$$

Lemma 2. *For two arbitrary functions $u(x, y)$ and $v(x, y)$ of the linear $D_A(\overline{G})$ we have*

$$\int_{-\xi}^{\xi} \frac{\partial \tilde{u}(x, y)}{\partial x} \tilde{v}(x, y) dx = 0 \quad \forall y \in [0, b].$$

Taking into account Lemmas 1,2 and Poincare's and Fridrikh's inequalities [3] we easily obtain the following

Theorem 3. *Operator $A = \Delta^2$ is positively defined on the linear $D_A(\overline{G})$.*

Let us note, that in the article [2] by using the scalar product

$$(u, v) = \int_0^b \int_{-\xi}^0 \int_{-a}^x u(s, y) v(s, y) ds dx dy \quad (4)$$

was proved the inequality of the positively definition (the uniqueness of the solution) for the corresponding operator of various non-local boundary value problems.

In the articles [4,5] by using of the scalar product of the type (2) was proved that the operators corresponding to the simple non-local boundary value problems are positively defined on the corresponding lineals.

Hence the operator $A = \Delta^2$ is positively defined on the lineal $D_A(\overline{G})$ in the Hilbert space $H(\overline{G})$. So we can follow the standard way.

After introducing the scalar product on $[u, v]_A$ the lineal $D_A(\overline{G})$ becomes the pre-Hilbert space which we denote by $S_A(\overline{G})$. By $H_A(\overline{G})$ we denote the Hilbert space obtained after completion of $S_A(\overline{G})$ by the norm $\| \cdot \|_A$. For every function $f(x, y) \in H(\overline{G})$ the quadratic function

$$F(u) = [u, u]_A - 2[f, u] \tag{5}$$

has the unique function $u_0(x, y) \in H_A(\overline{G})$, which minimizes the functional (3) and the function $u_0(x, y)$ satisfies the condition $[u_0, u]_A = [f, u]$ for every $u(x, y) \in D_A(\overline{G})$. When the function $f(x, y)$ belongs to the lineal $R_A(\overline{G})$ of the operator A, then the function $u_0(x, y) \in D_A(\overline{G})$ is the solution of the following problem

$$\begin{aligned} \Delta^2 u(x, y) &= f(x, y), \quad \text{for } (x, y) \in \overline{G}, \\ u(x, y)|_{\Gamma} &= 0, \quad \frac{\partial u(x, y)}{\partial \nu} \Big|_{\partial G} = 0, \\ u(x, y)|_{\Gamma_{-\xi}} &= u(x, y)|_{\Gamma_0}. \end{aligned} \tag{6}$$

It is naturally to introduce the following definition

Definition. The function $u_0(x, y)$ which minimizes the quadratic functional (3) in the space $H_A(\overline{G})$ is called the generalized solution of the equation (4).

Remark. For the Problem (1) $f(x, y) \in C(\overline{G})$ and the general solution originated from the couple $(f(x, y), f(0, y))$ corresponding to the function $f(x, y) \in H(\overline{G})$ is not generally equal to the Bitsadze-Samarski solution of the Problem (1), for example it is equal in the case $f(x, y) \in R_A(\overline{G})$. The problem of finding the function $f_0(x, y)$ for which the general solution of the problem (1) corresponding to the couple $(f(x, y), f(0, y))$ is equal to the ordinary solution is to be studied. Two following theorems are characterized the space $H_A(\overline{G})$.

Theorem 4. *The function $u(x, y) \in H(\overline{G})$ belongs to the space $H_A(\overline{G})$ if and only if the following relations are fulfilled*

$$u(x, y) \in W_2^2(G)$$

and the traces $u(x, y)|_{\Gamma_{-\xi}}$, $u(x, y)|_{\Gamma_0}$ and the boundary value $u(0, y)$ are the same elements of the space $W_2^2(0, b)$

$$u(x, y)|_{\Gamma} = 0, \quad \frac{\partial u(x, y)}{\partial \nu} \Big|_{\Gamma} = 0.$$

Theorem 5. *The norm*

$$\| \|u\| \|^2 = \|u(x, y)\|_{W_2^2(G)}^2 + \|u(0, y)\|_{W_2^2(0, b)}^2$$

defined in the space $H_A(\overline{G})$ is equivalent to the norm $\|\cdot\|_A$.

R E F E R E N C E S

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