# ON ONE PROBLEM IN THE PLANE THEORY OF VISCOELASTICITY FOR POLYGONAL AREA WITH A CIRCULAR HOLE

B. Gulua<sup>1,2</sup>, G. Kapanadze<sup>2,3</sup>

<sup>1</sup>Sokhumi State University, Politkovskaya str. 61, 0186 Tbilisi, Georgia bak.gulua@gmail.com

- <sup>2</sup>I. Vekua Institute of Applied Mathematics of I. Javakhishvili Tbilisi State University, 11 University Str., Tbilisi 0186, Georgia
- <sup>3</sup>A. Razmadze Mathematical Institute of I. Javakhishvili Tbilisi State University, 2, Merab Aleksidze II Lane, Tbilisi 0193, Georgia kapanadze.49@mail.ru

(Received 20.07.2022; accepted 14.11.2022)

#### Abstract

The problem of the plane theory of viscoelasticity for a convex polygon with a circular hole is considered according to the Kelvin-Voigt model. It is assumed that absolutely rigid smooth stamps are applied on the sides of the polygon on which normal compressive forces are applied with given main vectors (or constant normal displacements are given) and the internal boundary is subject to a normal compressive force (pressure) of a given intensity.

The purpose of this work is to determine the elastic equilibrium of a viscoelastic plate occupying a given region using the Kelvin-Voigt model. To solve the problem, methods of conformal mapping and boundary problems of analytical functions are used. The required complex potentials are constructed efficiently (in analytical form).

Keywords and phrases: The Kelvin-Voigt model, the Riemann-Hilbert problem, Kolosov-Muskhelishvili formulas

AMS subject classification (2010): 74B05, 45J05.

### 1 Statement of the Problem

Let a viscoelastic plate on the plane of a complex variable occupy a doubly connected domain S, bounded by a convex polygon (A) and a circle of unit radius  $L_0$  (i.e., we have a polygonal domain with a circular hole). Let us denote by  $L_1$  the boundary of the polygon (A), i.e.

$$L_1 = \bigcup_{k=1}^{n} L_k^{(1)}, \quad L_k^{(1)} = A_k A_{k+1} \quad (k = \overline{1, n}, \ A_{n+1} = A_1),$$

The values of the internal angles of the domain S at the vertices  $A_k$ ,  $k = \overline{1,n}$  will be denoted by  $\pi\alpha_k^0$ . The angle between the axis x and the external normal to the contour  $L_1$  at a point will  $\sigma$  be denoted by  $\alpha(\sigma)$ , i.e.  $\alpha(\sigma) = \alpha_0^{(k)} = const$ ,  $\sigma \in L_1^{(k)}$ .

Let us assume that straight absolutely rigid smooth stamps with known main normal forces  $N_k$   $(k=\overline{1,n})$  are applied to the sides  $L_k^{(1)}$  and the internal boundary is subject to uniformly distributed normal pressure  $P_0$  (This type of external load somewhat simplifies some calculations and does not change the essence of the solution to the problem).

The purpose of this work is to determine complex potentials characterizing the distribution of stresses and displacements in the plate according to the Kelvin-Voigt model.

Similar problems of the plane theory of elasticity for finite doubly connected polygonal regions are considered in [1-3].

# 2 Solution of the problemm

The problem is solved by the methods of conformal mappings and the theory of boundary value problems of analytic functions. Based on the Kolosov-Muskhelishvili formulas [6], the problem of finding the required complex potentials is reduced to the Riemann-Hilbert boundary value problem for a circular ring.

Due to the fact that the given domain is doubly connected, it is advisable to use functions  $\Phi(z,t)$  and  $\Psi(z,t)$ , which are also Unique in the case of a multiply connected domain.

Let us present some results arising from the works [4-6].

The function  $z = \omega(\zeta)$  conformally maps the circular ring  $D = \{1 < |\zeta| < R\}$  onto the domain S. Its derivative is the solution of the Riemann-Hilbert problem for the circular ring D

$$Re\left[i\omega'(\xi)\right] = 0, \ \xi \in l_0; \quad Re\left[i\xi e^{-i\alpha(\xi)}\omega'(\xi)\right] = 0, \ \xi \in l_1,$$

where  $l_0$  and  $l_1$  are the inverse images of contours  $L_0$  and  $L_1$ , respectively, i.e.

$$l_0 = \{ |\zeta| = 1 \}; \quad l_1 = \{ |\zeta| = R \},$$

and subject to

$$\prod_{k=1}^{n} \left(\frac{a_k}{R}\right)^{\alpha_k^0 - 1} = 1,$$

have the form

$$\omega'(\zeta) = K^{0} \prod_{k=1}^{n} \left(1 - \frac{a_{k}}{\zeta}\right)^{\alpha_{k}^{0} - 1} \prod_{j=1}^{\infty} \prod_{k=1}^{n} \left(1 - \frac{\zeta}{R^{2j} a_{k}}\right)^{\alpha_{k}^{0} - 1} \times \left(1 - \frac{a_{k}}{R^{2j} \zeta}\right)^{\alpha_{k}^{0} - 1}, \tag{1}$$

where  $K^0$  real constant  $a_k = \omega^{-1}(A_k), \ k = \overline{1, n}$ .

The first and second basic boundary value problems of the viscoelasticity plane S for the Kelvin-Voigt linear model have the following forms

$$\varphi(\sigma,t) + \sigma \overline{\varphi'(\sigma,t)} + \overline{\psi(\sigma,t)} = i \int_{\sigma_0}^{\sigma} (X_n + iY_n) \, ds + C_1 + iC_2, \quad (2)$$

$$\Gamma \varphi(\sigma, t) - M \left[ \varphi(\sigma, t) + \sigma \overline{\varphi'(\sigma, t)} + \overline{\psi(\sigma, t)} \right] = 2\mu^*(u + iv),$$

$$\sigma \in L_0 \bigcup L_1$$
(3)

here and then the coordinate t is the parameter of the time,  $\Gamma$  and M are operators of the time t

$$\begin{split} &\Gamma\varphi(\sigma,t) = \int_{0}^{t} \left[ \underline{\mathbf{x}}^{*}e^{k(\tau-t)} + 2e^{m(\tau-t)} \right] \varphi(\sigma,\tau) d\tau, \\ &\mathbf{M} \left[ \varphi(\sigma,t) + \sigma \overline{\varphi'(\sigma,t)} + \overline{\psi(\sigma,t)} \right] \\ &= \int_{0}^{t} e^{m(\tau-t)} \left[ \varphi(\sigma,\tau) + \sigma \overline{\varphi'(\sigma,\tau)} + \overline{\psi(\sigma,\tau)} \right] d\tau, \quad \sigma \in L. \end{split} \tag{4}$$

Considering the equality

$$X_n + iY_n = (N + iT) e^{i\alpha(\sigma)} = -i(N + iT) \frac{dt}{ds},$$

from (2) by differentiation with respect  $\sigma$  to we obtain

$$\frac{d}{d\sigma} \left[ \varphi(\sigma, t) + \sigma \overline{\varphi'(\sigma, t)} + \overline{\psi(\sigma, t)} \right] = \Phi(\sigma, t) + \overline{\Phi(\sigma, t)} + \overline{\varphi_s'^2} \left[ \sigma \overline{\Phi'(\sigma, t)} + \overline{\psi(\sigma, t)} \right] = N + iT,$$
(5)

where  $\Phi(\sigma, t) = \varphi'(\sigma, t)$ ,  $\Psi(\sigma, t) = \psi'(\sigma, t)$ .

Considering (5) and taking into account the equalities

$$\begin{array}{ll} u+iv=(v_{n}+iv_{\tau})e^{i\alpha(\sigma)}, & v_{n}=v_{n}^{(j)}=const, \ \sigma\in L_{1}^{(j)}, \ (j=\overline{1,n}),\\ v_{n}=V_{n}^{(0)}=const, \ \sigma\in L_{0}; \ e^{i\alpha(\sigma)}=\sigma, \ \sigma\in L_{0};\\ v_{\tau}=0, \ T(\sigma)=0, \ \sigma\in L_{0}\bigcup L_{1}, \end{array}$$

from (3) by differentiation with respect  $\sigma$  to we obtain

$$\Gamma\Phi(\sigma,t) - M[N+iT] = \begin{cases} 2\mu^* v_n^{(0)}, & \sigma \in L_0, \\ 0, & \sigma \in L_1. \end{cases}$$
 (6)

If we take into account that  $N = P_0$ ,  $\sigma \in L_0$  and T = 0,  $\sigma \in L_1$ , from (6) we have

$$Re\Gamma\Phi(\sigma,t) = P(t), \ \sigma \in L_0; \ Im\Gamma\Phi(\sigma,t) = 0, \ \sigma \in L_1,$$
 (7)

where

$$P(t) = P_0 F(t) + 2\mu^* v_n^{(0)}; \quad F(t) = \frac{1}{m} \left[ 1 - e^{-mt} \right].$$
 (8)

Mapping domain S onto a circular ring  $D = \{1 < |\zeta| < R\}$  (see point 1), with respect to the function

$$\Omega(\zeta, t) = \Gamma \Phi_0(\zeta, t), \quad \Phi_0(\zeta, t) = \Phi\left[\omega(\zeta), t\right] \tag{9}$$

from (7) we obtain the Riemann-Hilbert boundary value problem for a circular ring  ${\cal D}$ 

$$Re \left[ \Omega(\eta, t) - P(t) \right] = 0, \, \eta \in l_0; \quad Im \left[ \Omega(\eta, t) - P(t) \right] = 0, \, \eta \in l_1, \quad (10)$$

where  $l_0$  and  $l_1$  are inverse images of boundaries  $L_0$  and  $L_1$ .

Since problem (10) has only a trivial solution, we will have  $\Omega(\zeta,t) = P(t)$ ,  $\zeta \in D$  and, therefore, to determine function  $\Phi_0(\zeta,t)$  based on (4) and (9) we obtain the integral equation

$$\int_0^t \left[ e^* e^{k(\tau - t)} + 2e^{m(\tau - t)} \right] \Phi_0(\zeta, \tau) d\tau = P(t). \tag{11}$$

By differentiating (11) with respect to t and then adding the resulting equality with (11) multiplied by m, we will have

$$(m-k)\mathbb{E}^* \int_0^t e^{k\tau} \Phi_0(\zeta,\tau) d\tau + (\mathbb{E}^* + 2)e^{kt} \Phi_0(\zeta,t) = (P_0 + mv_n^{(0)})e^{kt}.$$
(12)

From (12) by differentiation with respect to t we obtain a differential equation of the first kind

$$\dot{\Phi}_0(\zeta, t) + a\Phi_0(\zeta, t) = b, \tag{13}$$

where

$$a = \frac{m\omega^* + 2k}{\omega^* + 2}, \qquad b = \frac{k(P_0 + mv_n^{(0)})}{\omega^* + 2}$$
 (14)

(the dot over  $\Phi_0(\zeta, t)$  means the derivative with respect to t).

From (12) we have

$$\Phi_0(\sigma, 0) = \frac{b}{k}.\tag{15}$$

The solution to equation (13), under the initial condition (15) has the form

$$\Phi_0(\zeta, t) = b \left[ \frac{1}{a} + \left( \frac{1}{k} - \frac{1}{a} \right) e^{-at} \right], \tag{16}$$

where a and b are defined by formula (14).

After function  $\Phi_0(\zeta,t)$  is found, to define the function

$$\Psi_0(\zeta, t) = \Psi[\omega(\zeta), t]$$

Let us use the boundary condition (6), which after the conformal mapping, taking into account (5), will be written in the form

$$\Gamma \overline{\Phi_0(\eta, t)} - M \left\{ \Phi_0(\eta, t) + \overline{\Phi_0(\eta, t)} - \frac{\eta^2}{\overline{\omega'(\eta)}} \left[ \overline{\omega(\eta)} \Phi'_0(\eta, t) + \omega'(\eta) \Psi_0(\eta, t) \right] \right\}$$

$$= \begin{cases}
2\mu^* v_n^{(0)}, & \sigma \in l_0, \\
0, & \sigma \in l_1,
\end{cases} \quad \eta \in l = l_0 \bigcup l_1.$$
(17)

Based on (16), from (17) we obtain

$$Im\Omega_0(\eta, t) = 0, \quad \eta \in l_0 \bigcup l_1, \tag{18}$$

where

$$\Omega_0(\zeta, t) = \mathcal{M}\left[\zeta^2 \omega'^2(\zeta) \Psi_0(\zeta, t)\right]. \tag{19}$$

The solution to problem (18) has the form  $\Omega_0(\zeta, t) = K_1$  where  $K_1$  is a real constant.

Thus, for Definition  $\Psi_0(\zeta,t)$  we obtain the equation

$$M\left[\zeta^2 \omega'^2(\zeta) \Psi_0(\zeta, t)\right] = K_1. \tag{20}$$

Taking into account the form of operator M, from (20) we easily obtain

$$\Psi_0(\zeta,t) = \frac{mK_1}{\zeta^2 \omega'^2(\zeta)}.$$

From (14) and (16) we conclude that expression  $\Phi_0(\zeta, t)$  involves both  $P_0$  and  $v_n^{(0)}$ , and the condition of the problem implies that  $L_0$  is set to one of them. Therefore, it is in our interests to find the relationship between these quantities. Let us assume that at the initial moment the value  $L_0$  is set to  $P_0$ . Then we will have

$$X_x = Y_y = P_0$$
,  $X_x + Y_y = 4Re\Phi(\sigma, t)$ ,  $Re\Phi(\sigma, t) = \frac{P_0}{2}$ ,  $\sigma \in L_0$ 

and condition (6), taking into account (4), will be written in the form

$$\frac{P_0 \mathbf{x}^*}{2} \int_0^t e^{k(\tau - t)} d\tau = 2\mu^* v_n^{(0)},$$

from which we easily obtain

$$v_n^{(0)} = \frac{\mathbf{æ}^* P_0}{4\mu^* k}.$$

## References

- Bantsuri R. Solution of the third basic problem of elasticity theory for doubly connected domains with polygonal boundary (Russian). *Dokl. Acad. Nauk SSSR*, 243, 4 (1978), 882-885.
- 2. Bantsuri R., Kapanadze G. The plane problem of the theory of elasticity for a polygonal domain with a rectilinear cut. *Proc. A. Razmadze Math. Inst.* **164** (2014), 13-17.
- 3. Kapanadze G. On a problem of the bending of a plate for a doubly connected domain bounded by polygons (Russian). *Prikl. Math.Mekh.* **66**, 4 (2002), 616-620.
- 4. Kapanadze. On conformal mapping of doubly-connected domain bounded by convex polygon with linear section on circular ring. *Bull. Georgian Acad. Sci.* **161**, 2 (2000), 192-194.
- 5. Shavlakadze N., Kapanadze G., Gogolauri L. About one contact problem for a viscoelastic halfplate. *Trans. of A Razmadze Math. Inst.*, **173** (2019), 103-110.
- 6. Muskhelishvili N. I. Some Basic Problems of the Mathematical Theory of Elasticity. Fundamental equations, plane theory of elasticity, torsion and bending. Fifth revised and enlarged edition (Russian). Nauka, Moscow, 1966.